

Radar as a tool to study the Solar System

GBT/AO Single Dish Workshop
September 16, 2021

Maxime Devogèle
Planetary Radar Science Group



ARECIBO OBSERVATORY
PUERTO RICO
UCF • YSI • UMET



UCF

Outline

- What is a radar system and why do we use it for Solar System studies
- Introduction to Radar Systems and observing methods
- Results from planetary radar observations
- Introduction to Solar System radar data processing



What is RADAR?

- **RA**dio **D**etection **A**nd **R**anging
- Active remote sensing – we control the signal!
- Maximize signal properties to enhance SNR
- Measure reflected radio waves (so targets must be reflective)

Klystron Amplifier

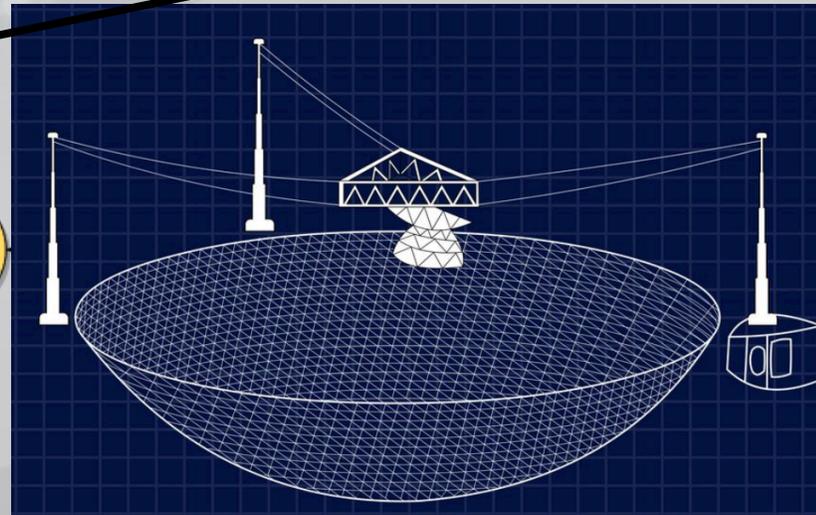
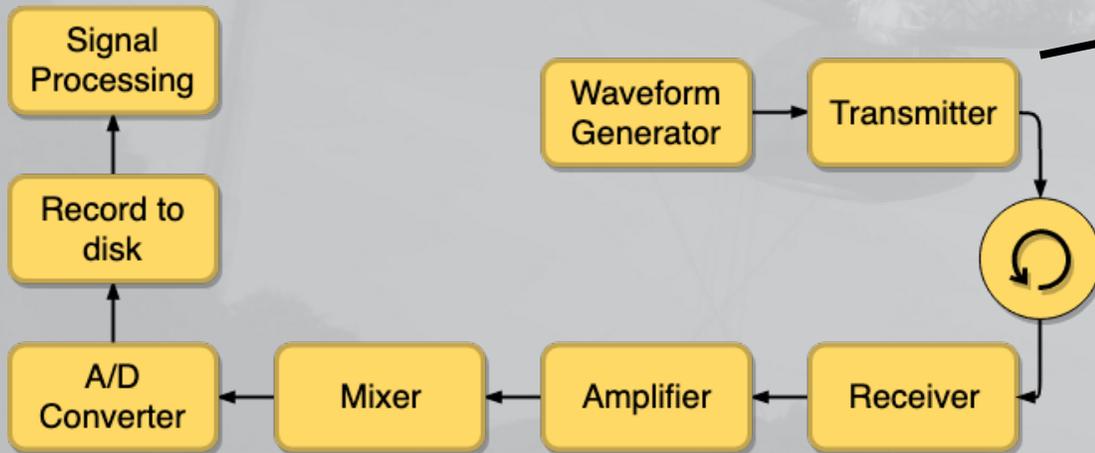


Image source: <https://en.wikipedia.org/wiki/Klystron>

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Solid State Amplifier

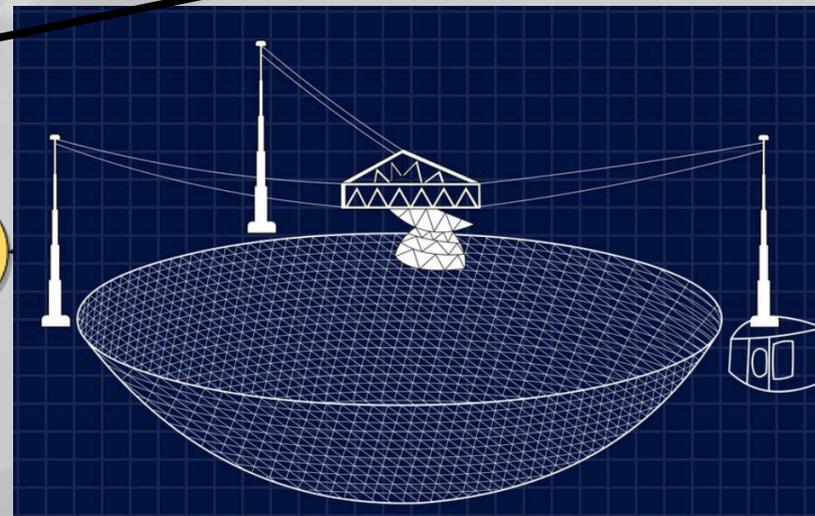
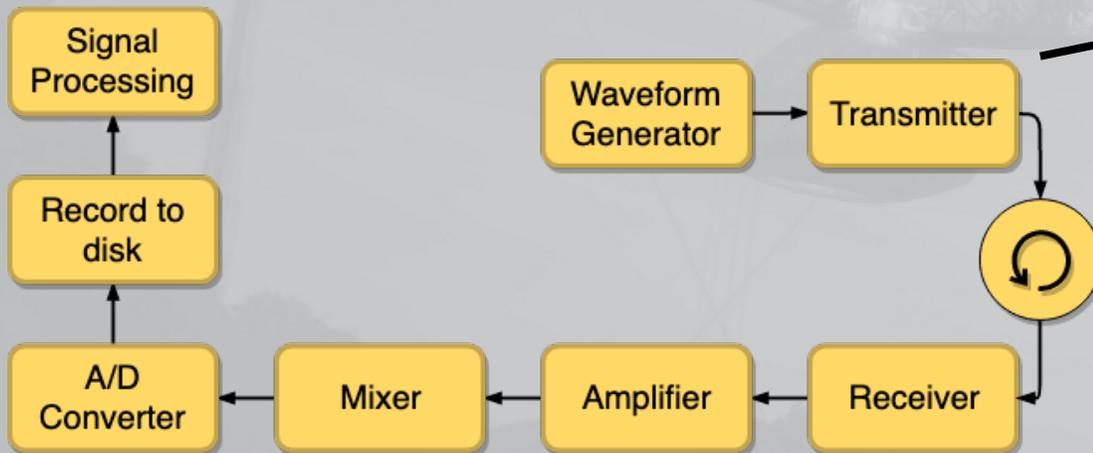
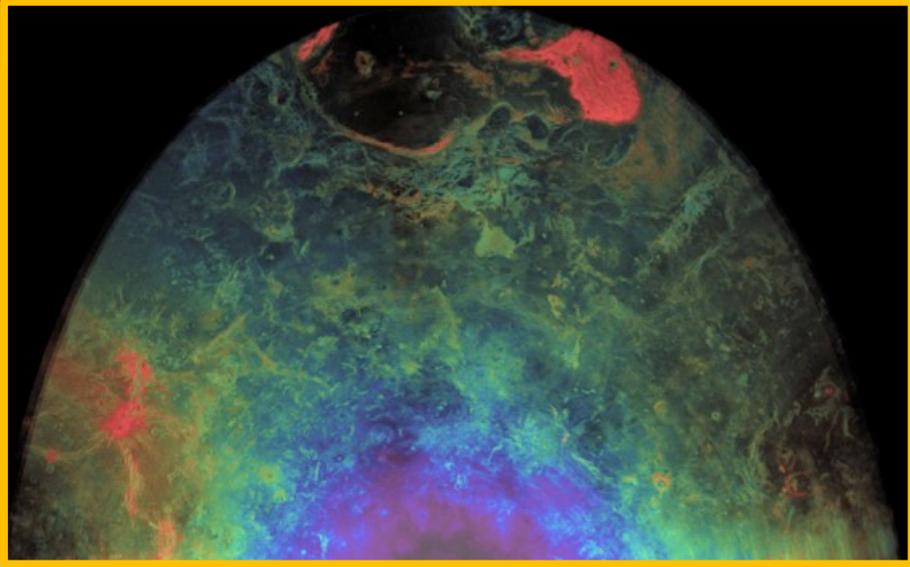


Image source: <https://en.wikipedia.org/wiki/Klystron>

Image credit: Lynn Carter (LPL)



Penetrate through atmospheres

Reveal buried features

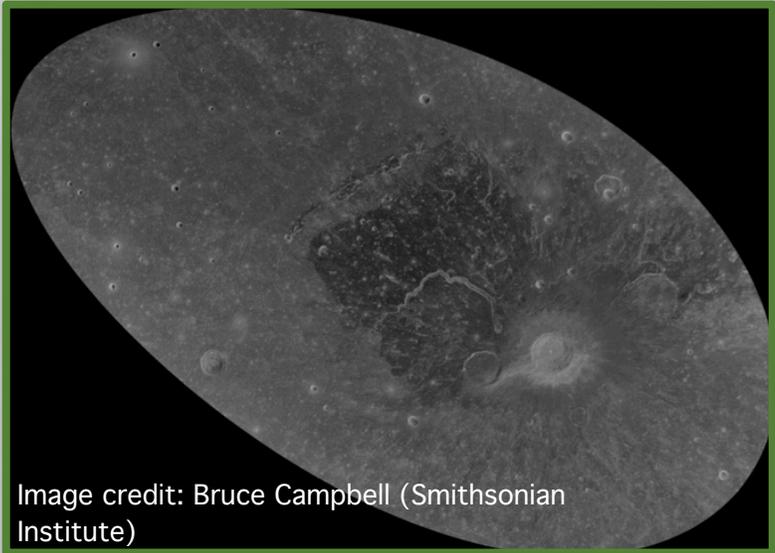


Image credit: Bruce Campbell (Smithsonian Institute)

Arecibo Observatory - Green Bank
NASA/NSF

(163899) 2003 SD220 18 December 2018

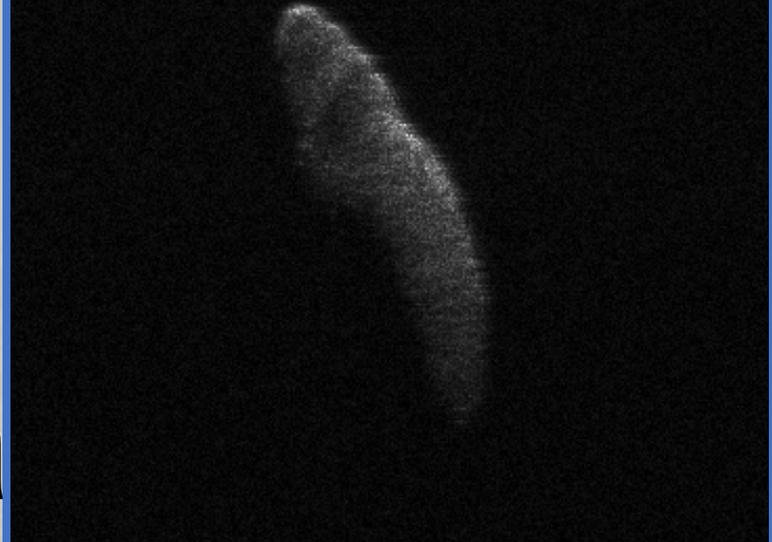


Image at resolutions comparable to space missions

Use polarimetry to detect surface properties

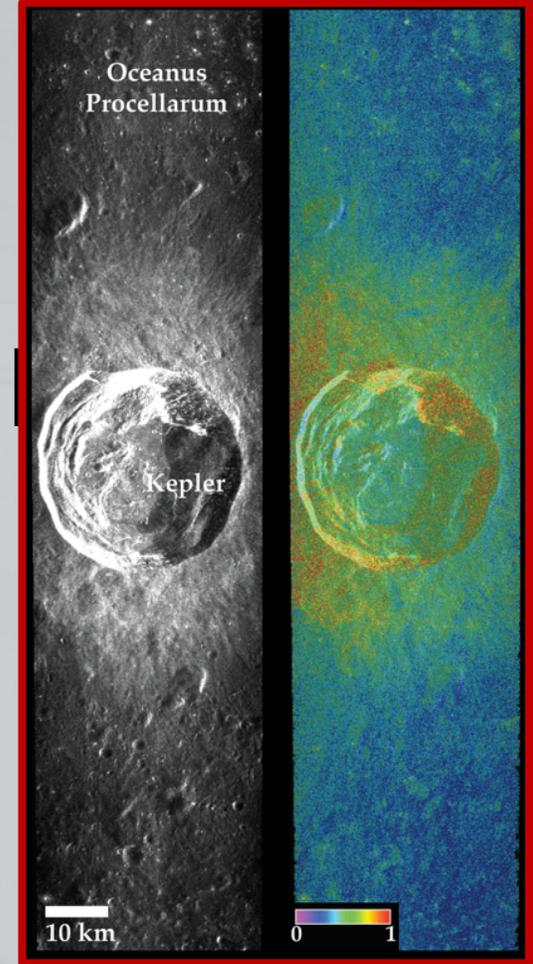
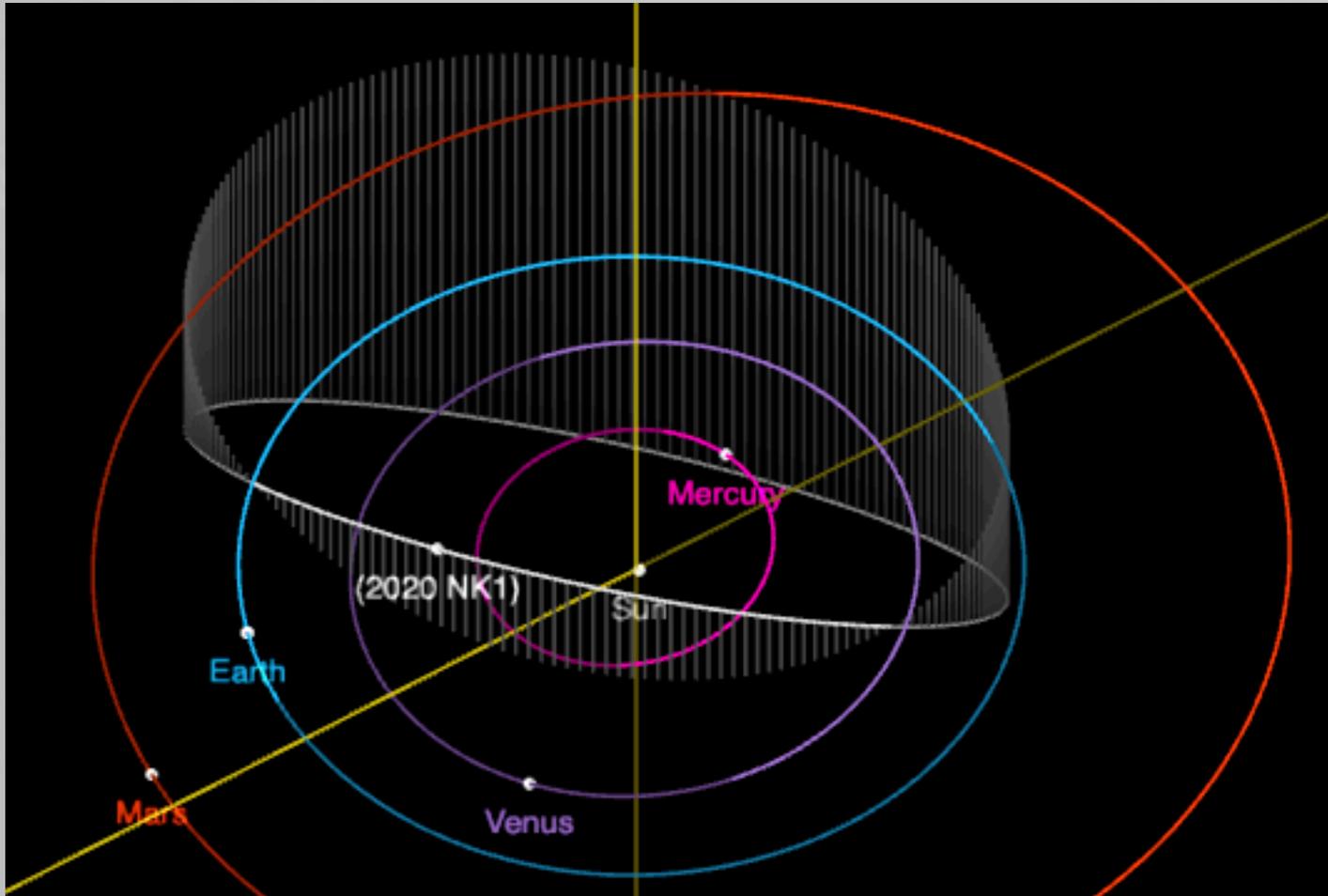


Image credit: G. Wes Patterson (JHU/APL)



Astrometry: refining orbits of celestial bodies



- Range (distance) resolution as fine as ~ 5 m
- Relative velocity resolution as fine as ~ 10 mm/s

Image credit: <https://ssd.jpl.nasa.gov/sbdb.cgi#top>

Astrometry: refining orbits of celestial bodies



Image credit: Jon Giorgini (JPL)



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Astrometry: refining orbits of celestial bodies

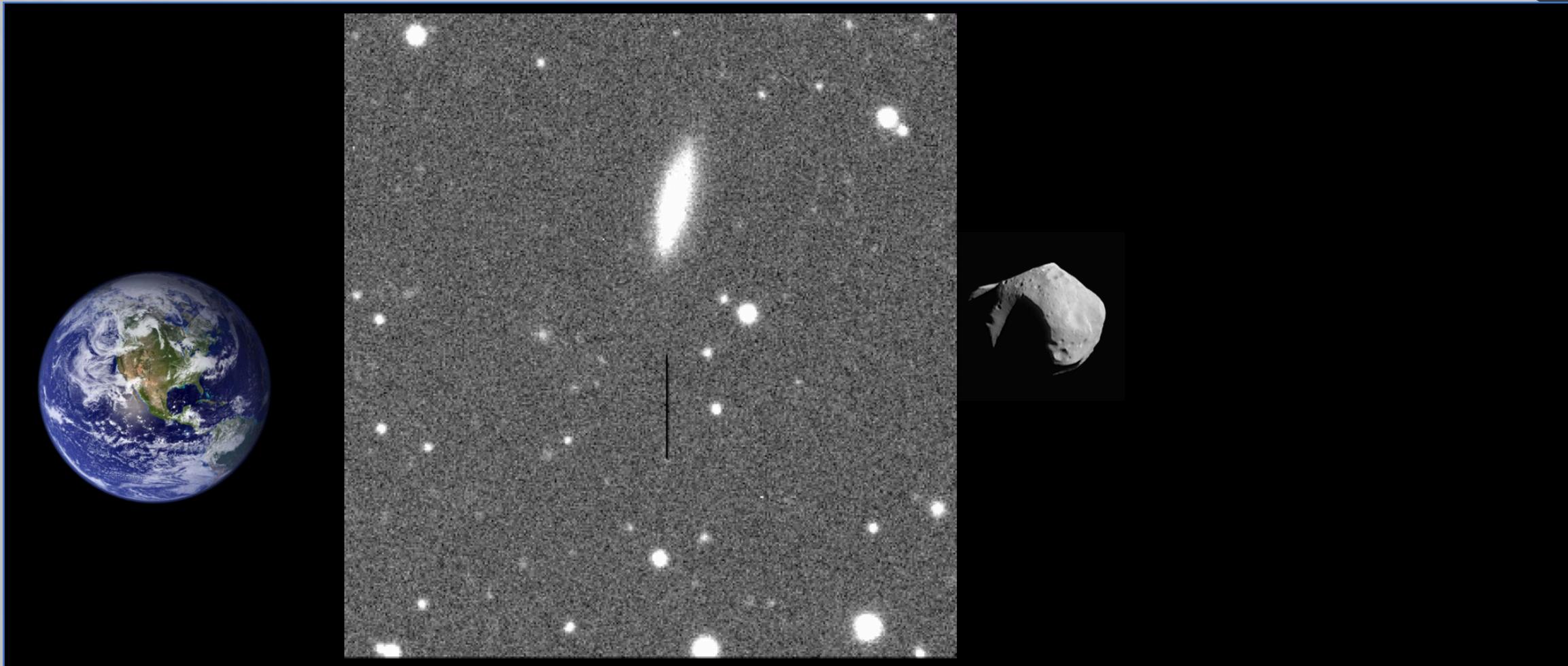


Image credit: Jon Giorgini (JPL)



Astrometry: refining orbits of celestial bodies

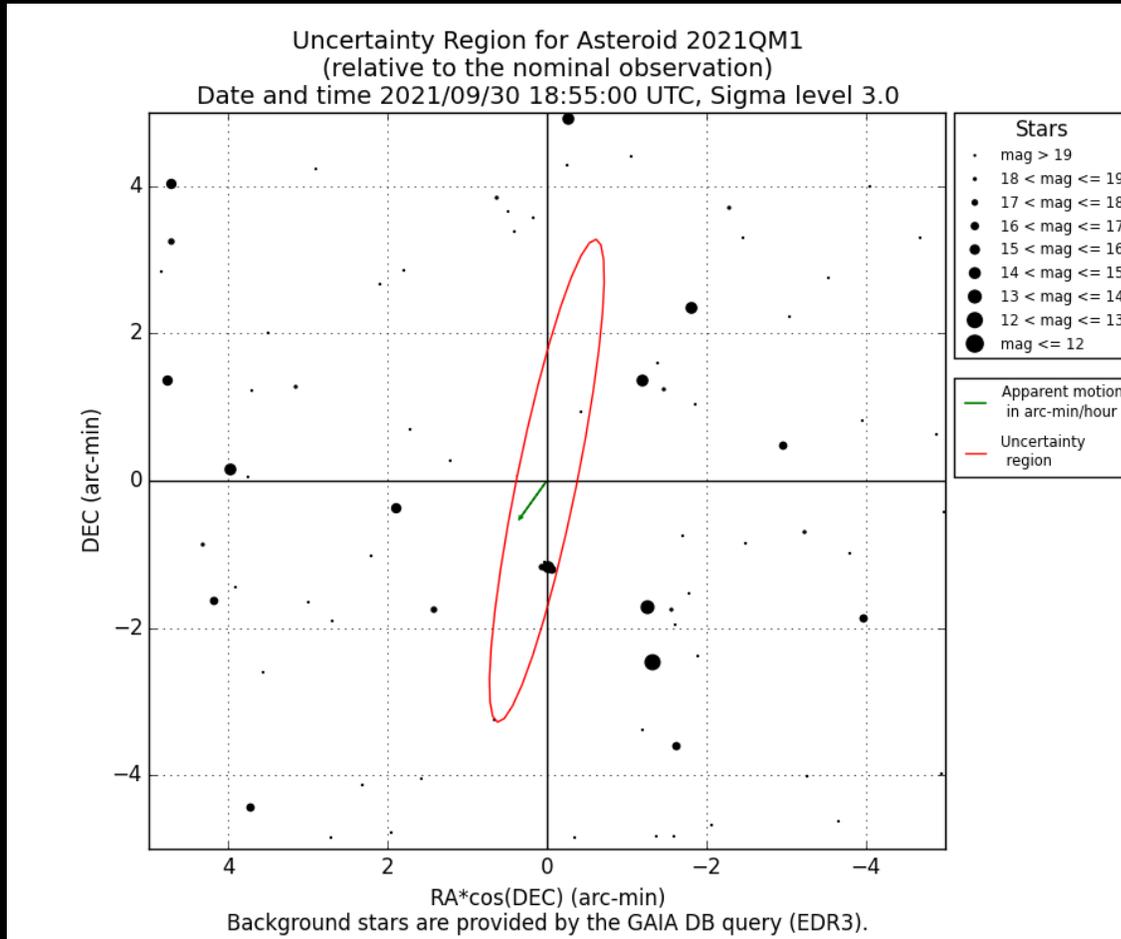


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Astrometry: refining orbits of celestial bodies

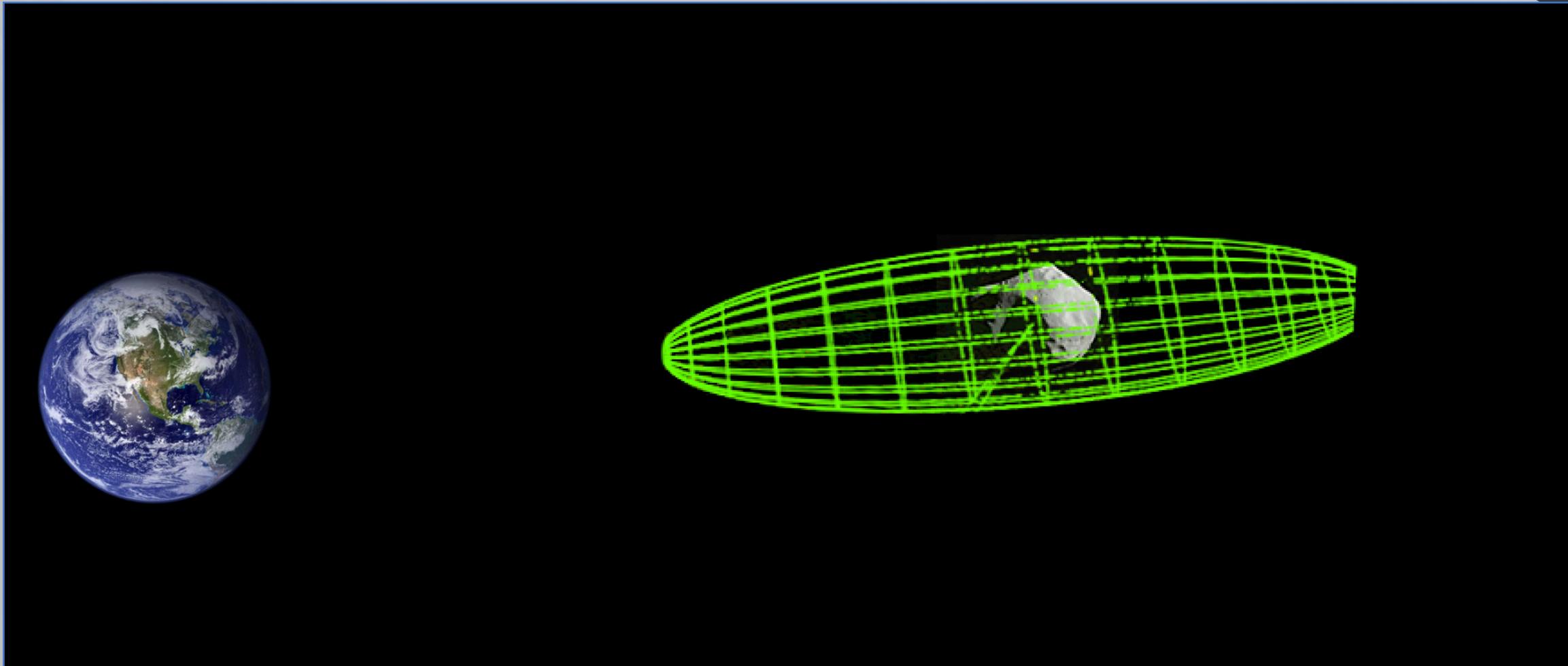


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Astrometry: refining orbits of celestial bodies

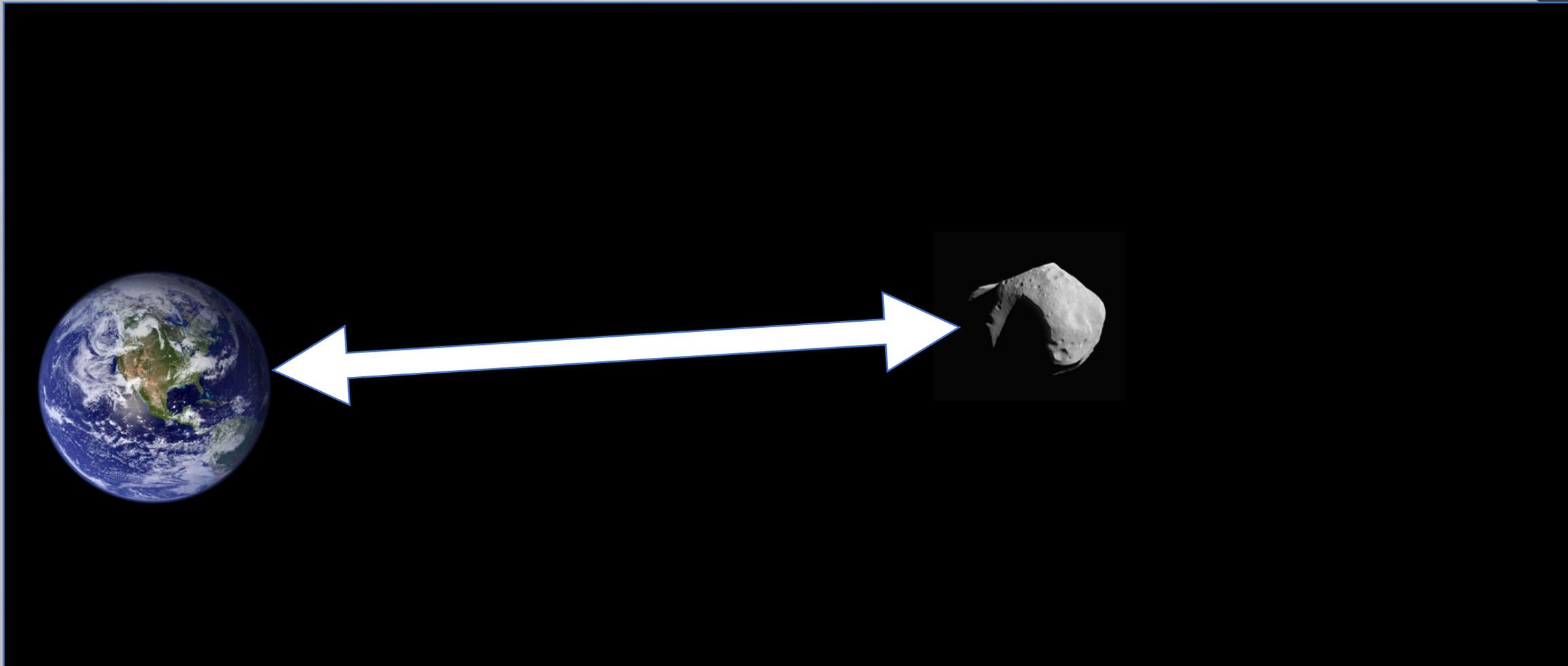


Image credit: Jon Giorgini (JPL)



Astrometry: refining orbits of celestial bodies

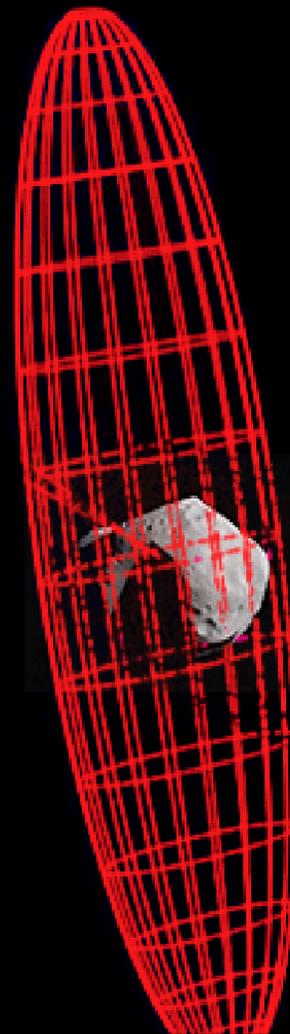


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Astrometry: refining orbits of celestial bodies

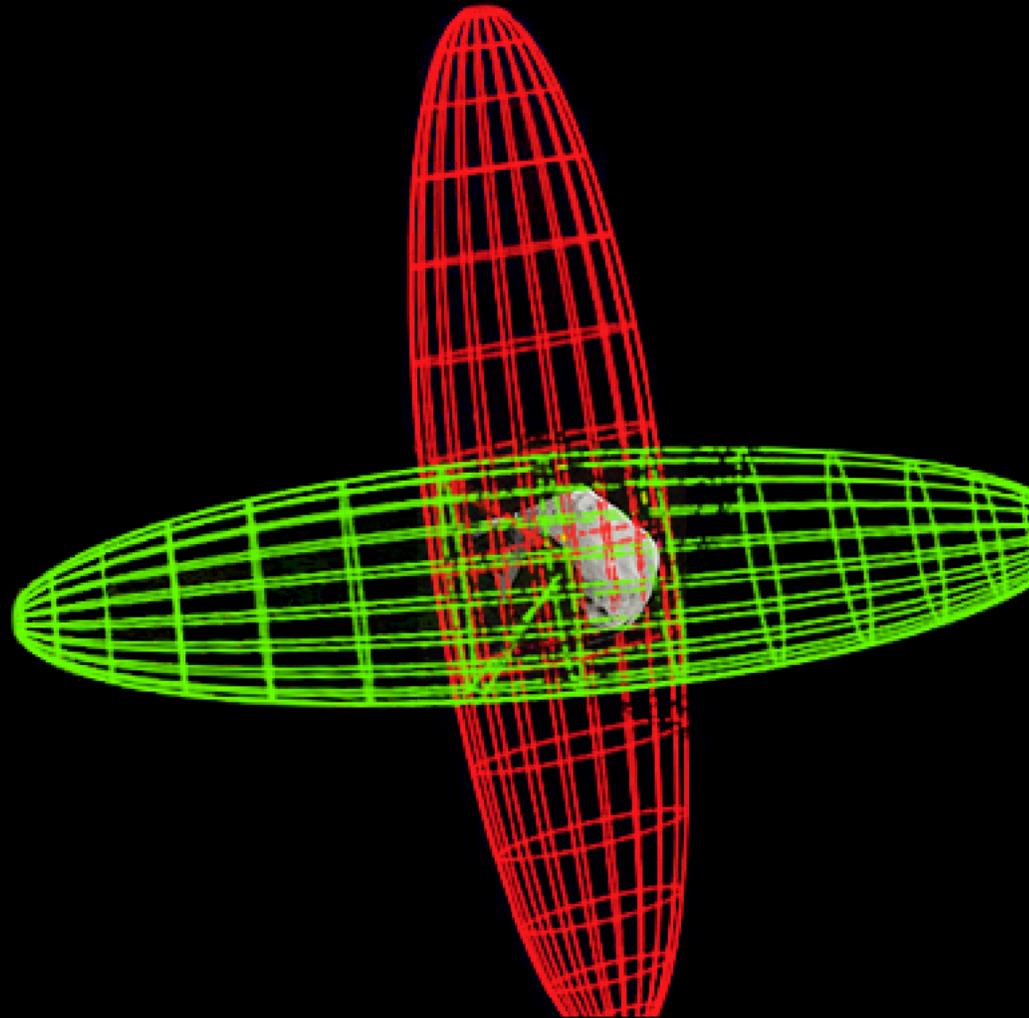


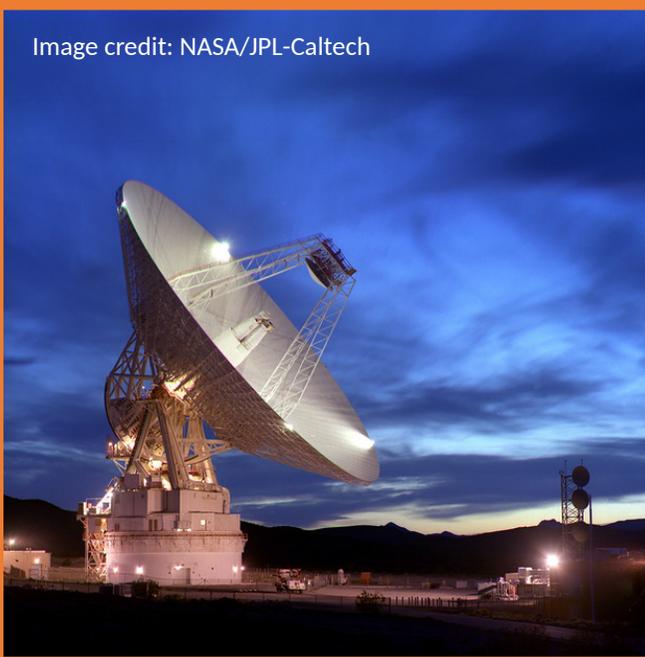
Image credit: Jon Giorgini (JPL)



Arecibo, Goldstone, GBT



Image credit: NASA/JPL-Caltech



- Declination range: -35° – 90° (79% of the whole sky)
- Several antennas (the largest, DSS-14: 70 m)
- Transmitter frequency: 8560 MHz (3.5 cm)
- Power up to 500 kW
- ~ 70 objects/year attempted, ~ 60 detected

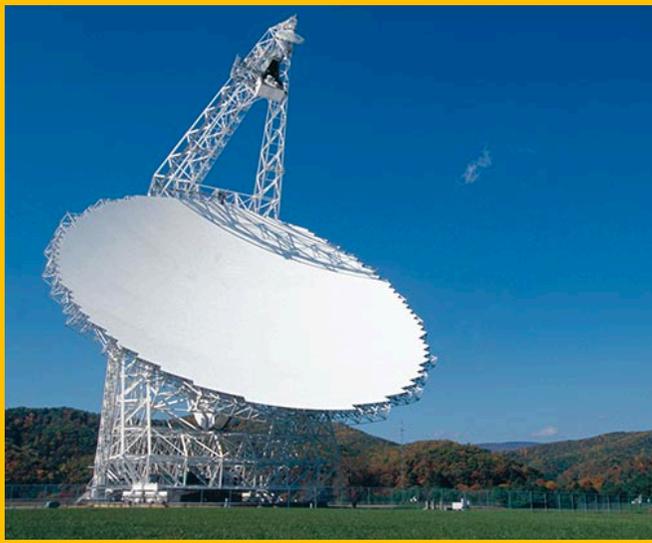
Goldstone Solar System Radar

Arecibo Observatory

- Declination range: -1 – 38 (32% of the whole sky)
- 305 m antenna
- Transmitter frequency: 2380 MHz (12.6 cm)
- Power up to 1 MW
- ~ 100 objects/year attempted, ~ 80 detected



Arecibo, Goldstone, GBT



- Declination range: -46° – 90° (86% of the whole sky)
- 100m antenna

Green Bank

The Radar Equation



P_{rx}
Received Power

$= [P_{tx}] [G_{tx}]$
Transmitted Power Transmitter Gain

$\left[\frac{1}{4\pi r^2} \right]$
Geometric Spreading

Geometric Spreading

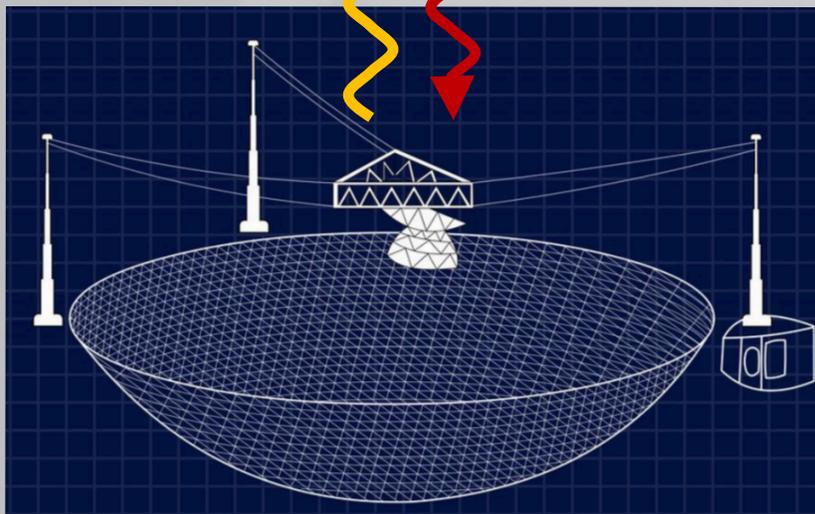
$[\sigma]$
Radar Cross Section

Radar Cross Section

$\left[\frac{1}{4\pi r^2} \right]$

$[A_{eff}]$
Effective Aperture

Effective Aperture



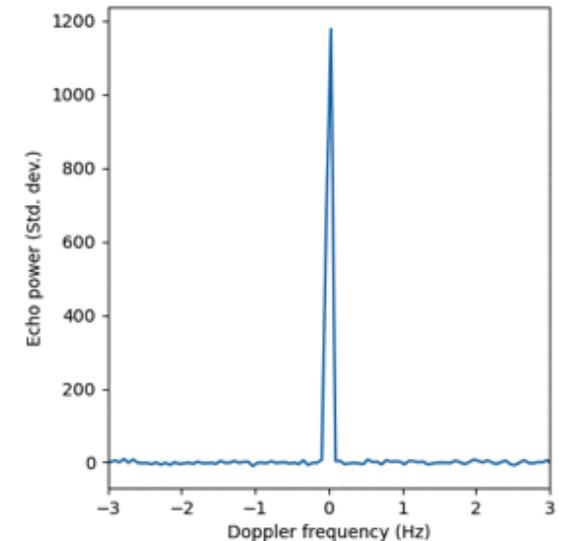
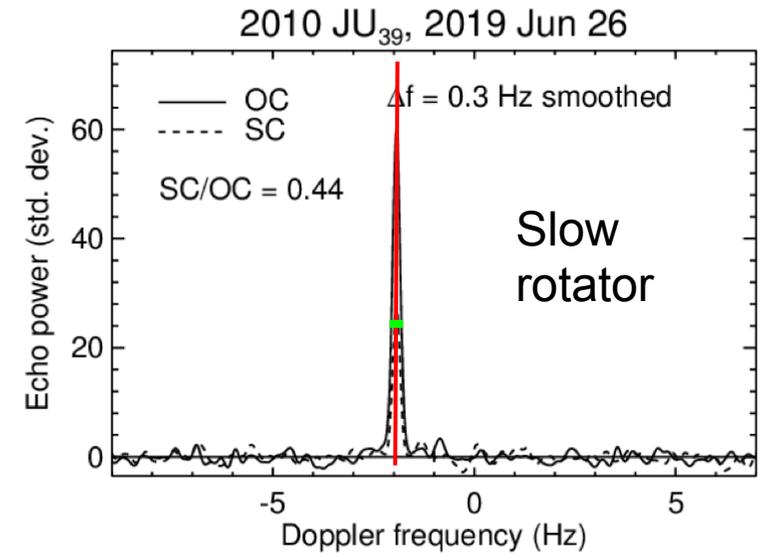
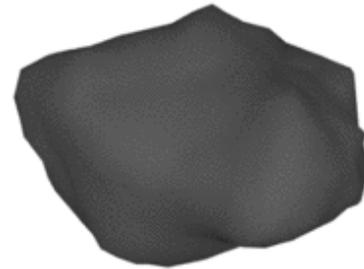
Continuous Wave (CW)



- **Continuous Wave (CW) signals:**
 - This is when we transmit a continuous signal with a **constant amplitude, phase, and frequency**.
 - We cannot differentiate signals based on when they arrive (**no range information**). This **only gives us information on the shift in frequency, or Doppler shift of the reflected signal**, based on the motion of the target.

Continuous Wave (CW)

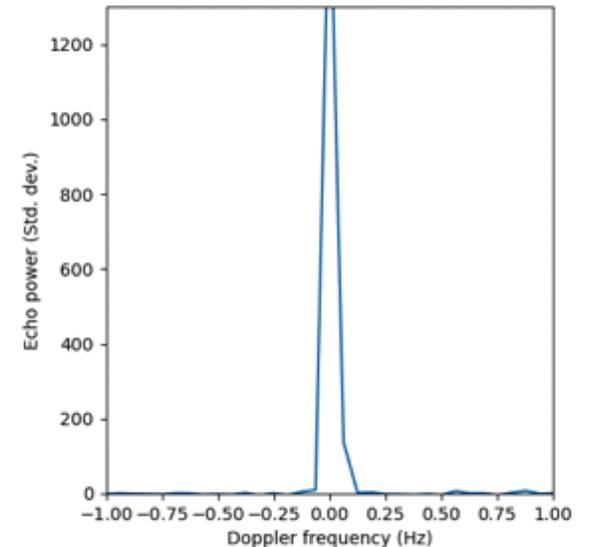
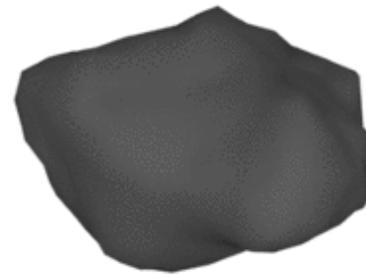
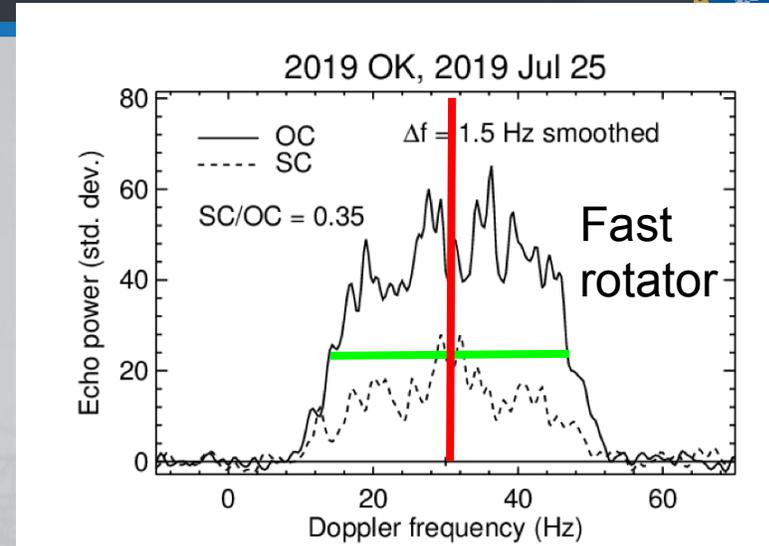
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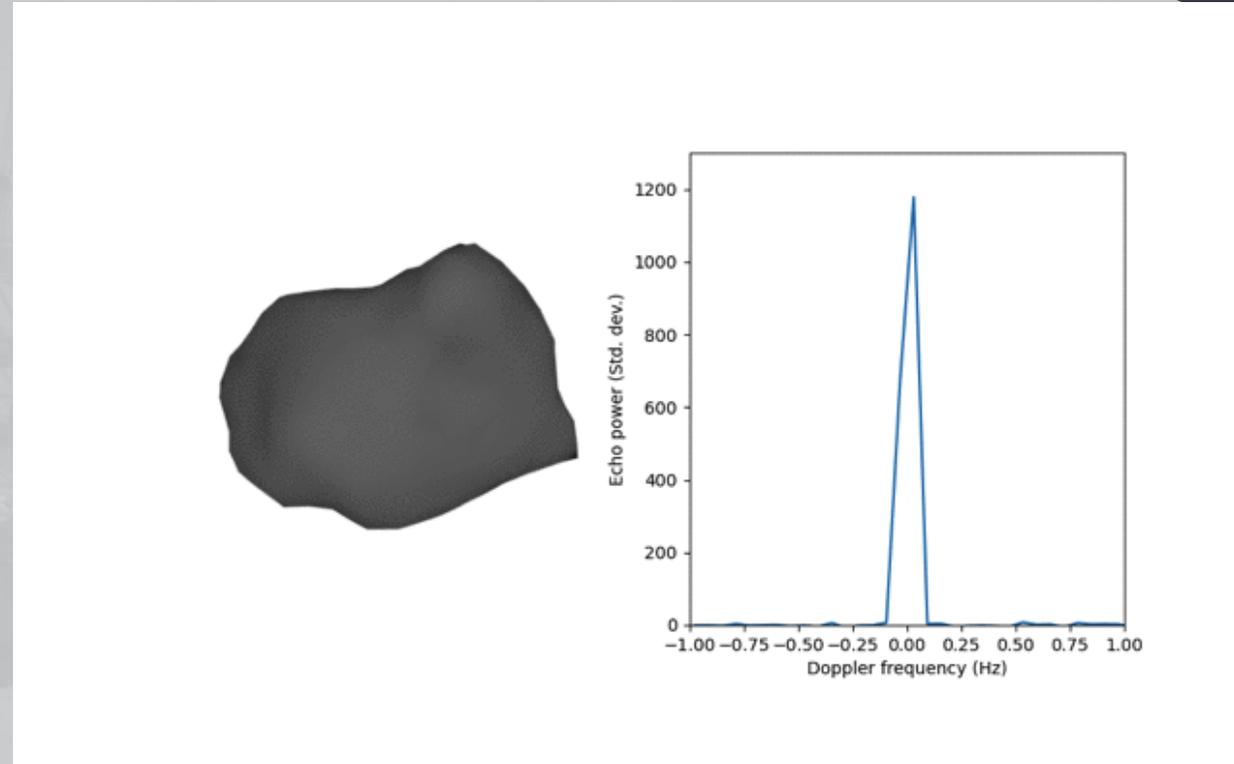


SNR: Detectability



- Target's doppler bandwidth depends on size and spin state:

$$B = \frac{4\pi D \cos\phi}{\lambda_0 P_{spin}}$$



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$$\Delta f = -\frac{2v}{c} f_e$$



$$\Delta f = \frac{2v}{c} f_e$$

Doppler equation: $f_o = \left(1 \pm \frac{2v}{c}\right) f_e$

$$v = \frac{\pi D}{P} \quad f_e = \frac{c}{\lambda}$$

$$B = \frac{2v}{c} f_e - \left(-\frac{2v}{c} f_e\right)$$

$$B = \frac{4\pi D}{\lambda P}$$

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- RMS noise power depends on bandwidth, integration time, and system temperature:

$$N_{rms} = kT_{sys} \sqrt{\frac{B}{\tau}}$$

k = Boltzmann's constant

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- Need SNR of ~6 for detection, but much higher SNR for imaging

$$SNR = \frac{P_{rx}}{N_{rms}}$$

$$P_{rx} = \frac{P_{tx} G_{tx} \sigma A_{eff}}{(4\pi)^2 r^4}$$

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$$P_{rx} = [P_{tx}] [G_{tx}] \left[\frac{1}{4\pi r^2} \right] [\sigma] \left[\frac{1}{4\pi r^2} \right] [A_{eff}]$$

σ is constant

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$$SNR \sim (\text{System factor})(\text{Target factor}) \sqrt{\Delta t}$$

$$\text{System factor} \sim \frac{P_{tx} G_{ant} A_{eff}}{T_{sys} \lambda^{1/2}}$$

$$\text{Target factor} \sim \frac{\hat{\sigma} D^{3/2} P^{1/2}}{r^4} \quad \hat{\sigma} = \text{radar albedo}$$

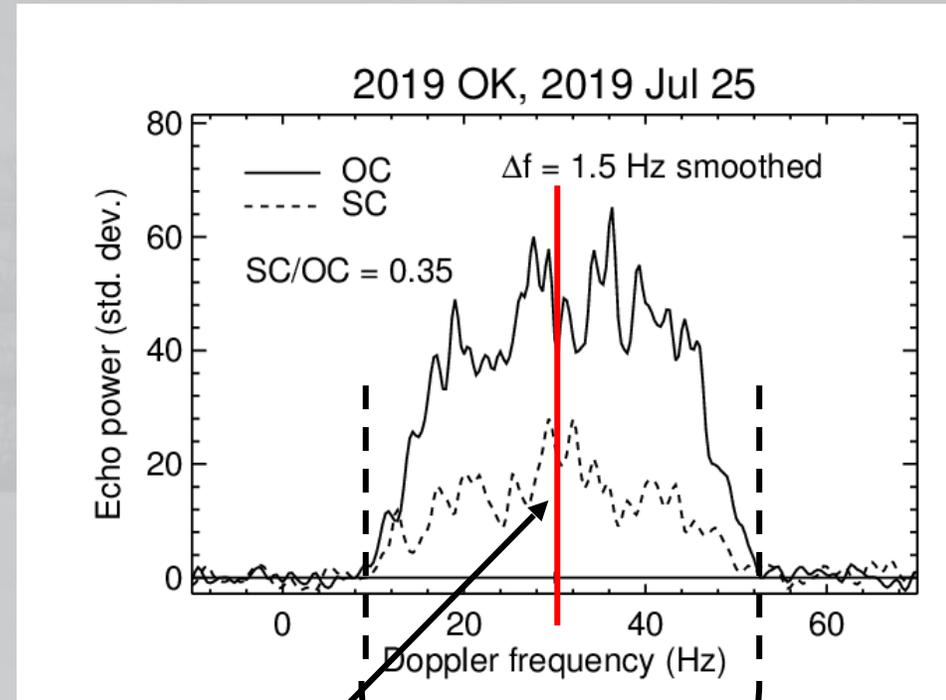
For every CW detection we learn:



- **Astrometry:** ~ 30 Hz offset in line-of-sight velocity of target
- **Rotation rate:** estimate from bandwidth and size

$$B = \frac{4\pi D \cos\phi}{\lambda_0 P_{spin}}$$

- **CPR:** related to surface roughness and composition



Ephemeris offset

Bandwidth

Coded Waveforms

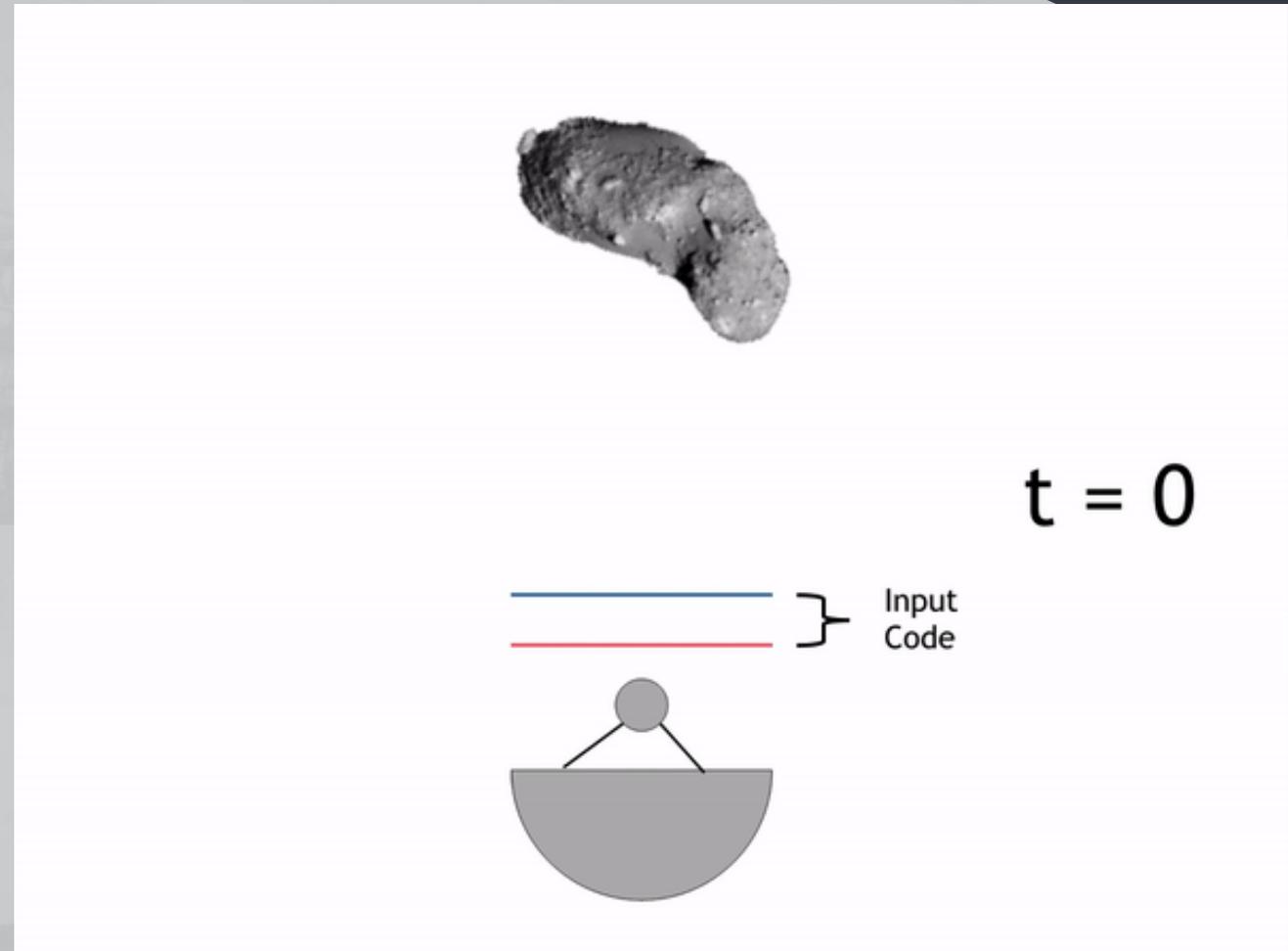


- **Coded (modulated) signals:**
 - By adding some code, or time structure, to the transmitted signal, either **by varying the frequency, phase, or amplitude**, we can **determine ranges of targets**, or what distances from the telescope different portions of the signal were reflected from.
 - Convolve received signal with transmitted signal in **matched filter**.

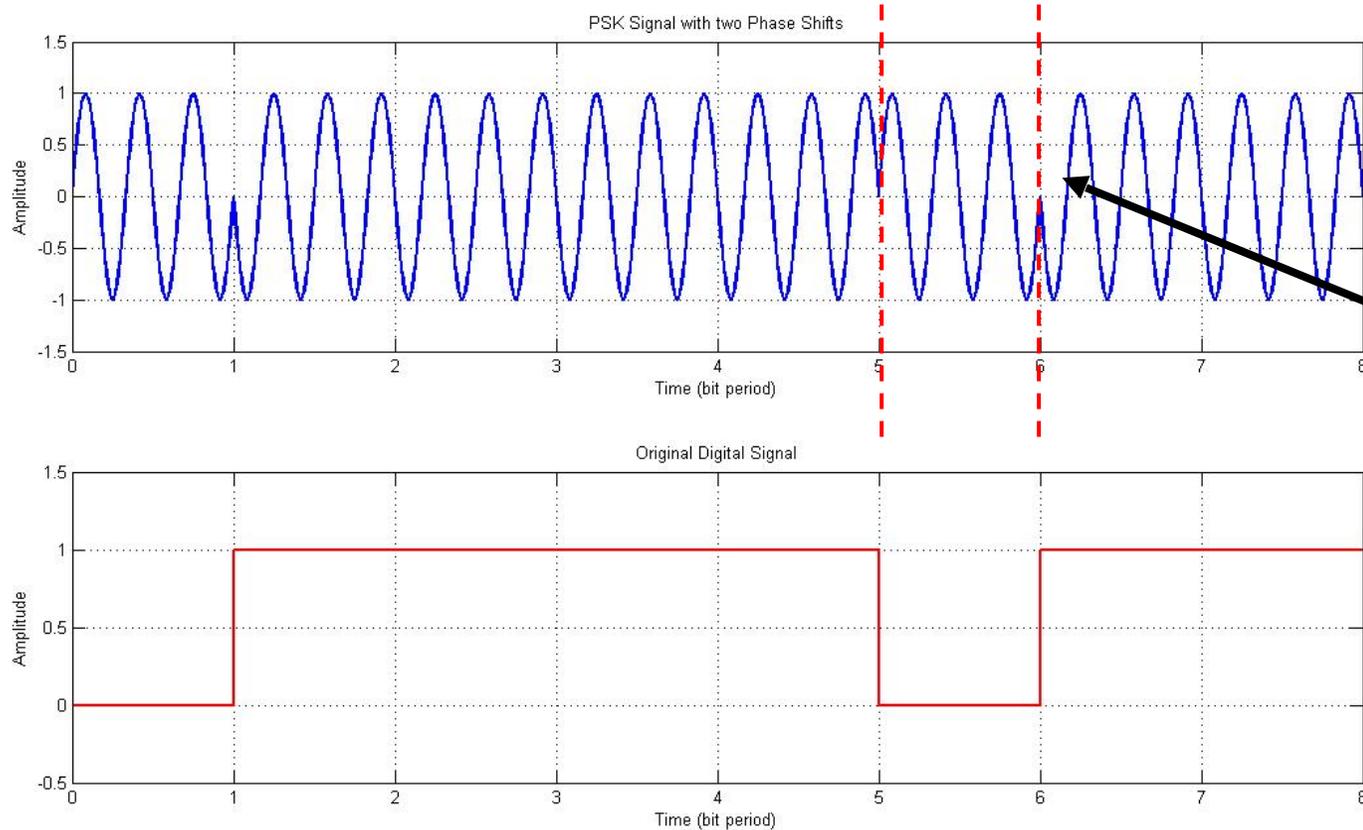
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Binary Phase Coded Waveform

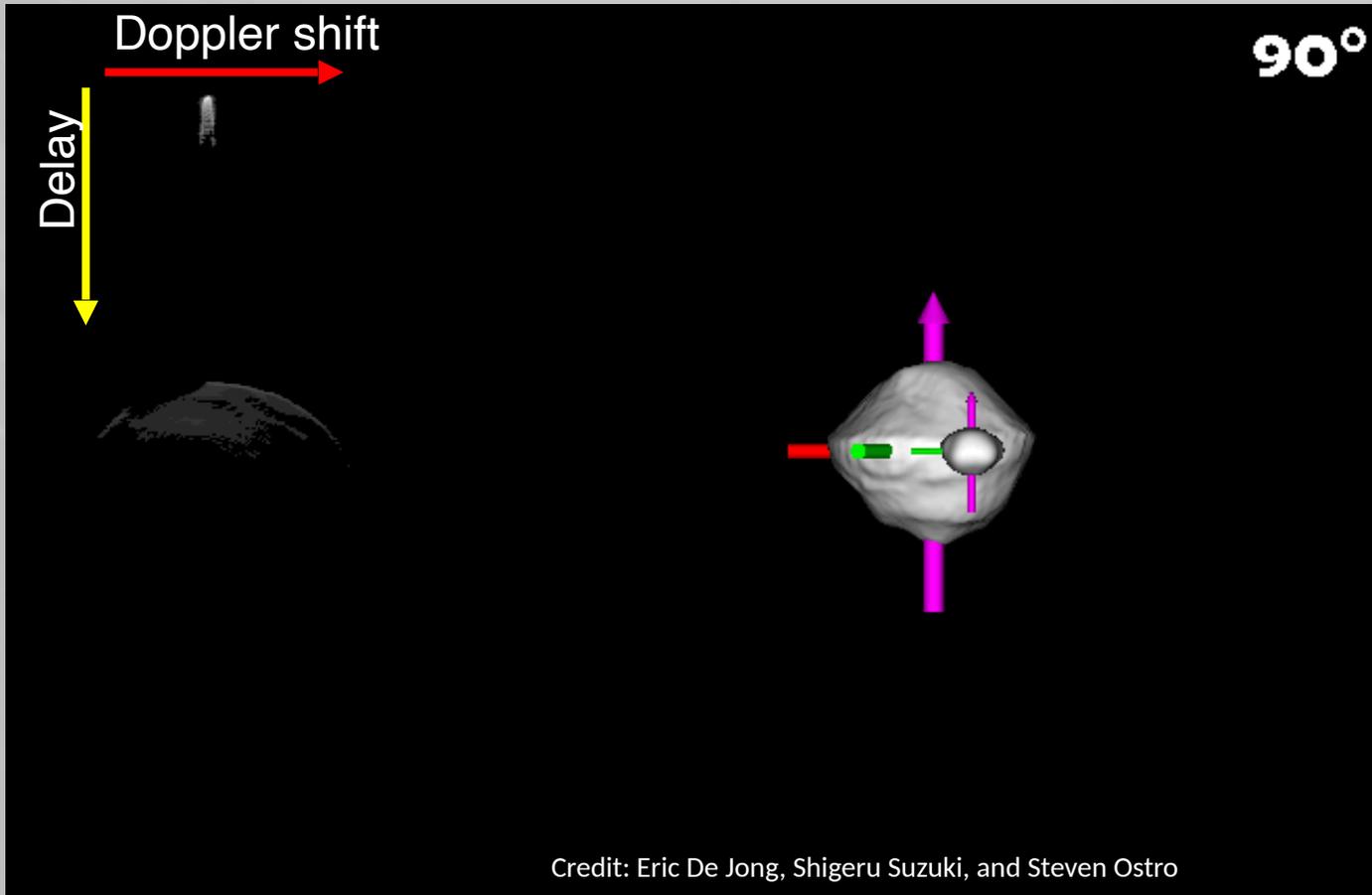


One baud, defined as the length of time between phase shifts

$$\Delta r = \frac{c \cdot \text{baud}}{2}$$

- Code Bandwidth = 1/[baud][codelength]





Time Delay: Distance

- Vertical axis
- Increasing downward
- Points at the top are closest to the observer

Doppler Frequency: Velocity

- Horizontal axis
- Increasing to the right
- Points on the right are approaching the observer

- Splitting signal into discrete range & frequency bins
- Requires high SNR

3D – 2D ambiguity

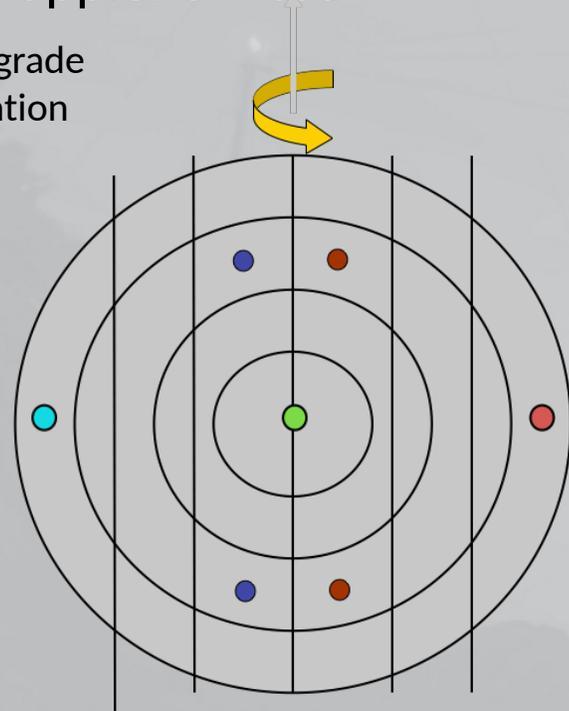


Circles: points at the same distance (range) from observer

Vertical Lines: points of constant Doppler shift

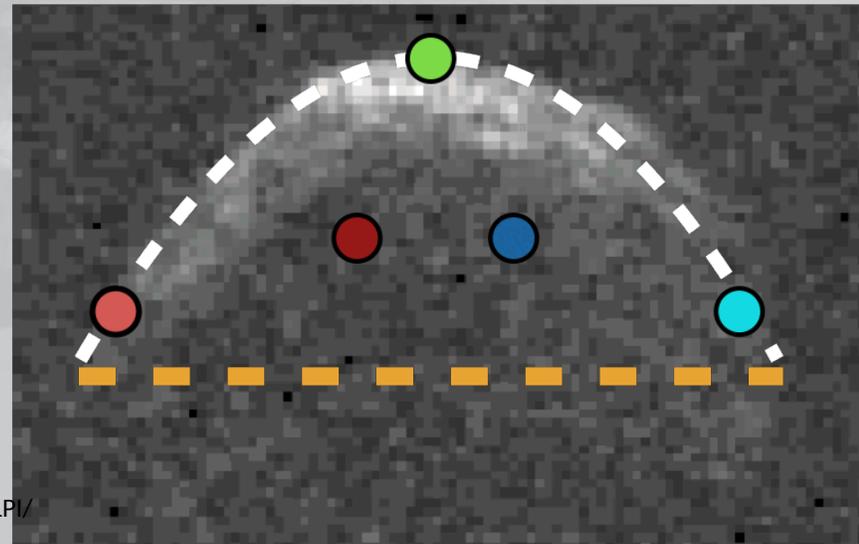
Blue dots are blue shifted, red dots are red-shifted, green dots are not Doppler shifted

Prograde rotation



Doppler shift

range



Courtesy Patrick Taylor (LPI/USRA)

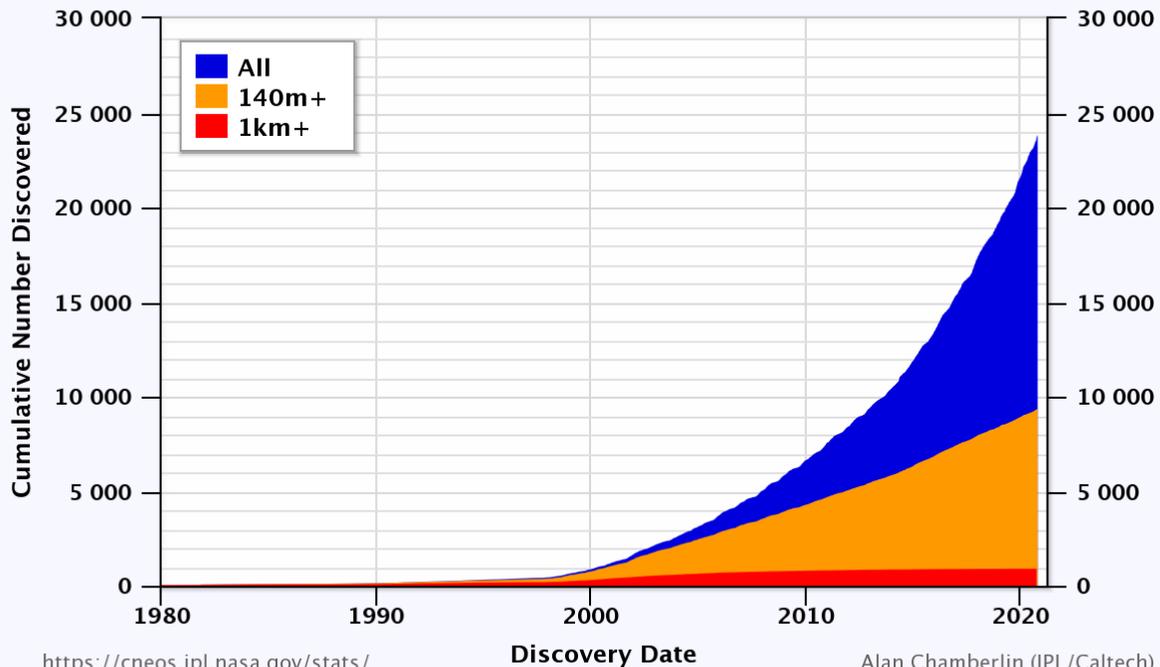
The two blue and red dots map to the same point in a radar image (north/south ambiguity)



Arecibo Observatory detects and characterizes ~100 near-Earth objects (NEOs) per year

Near-Earth Asteroids Discovered

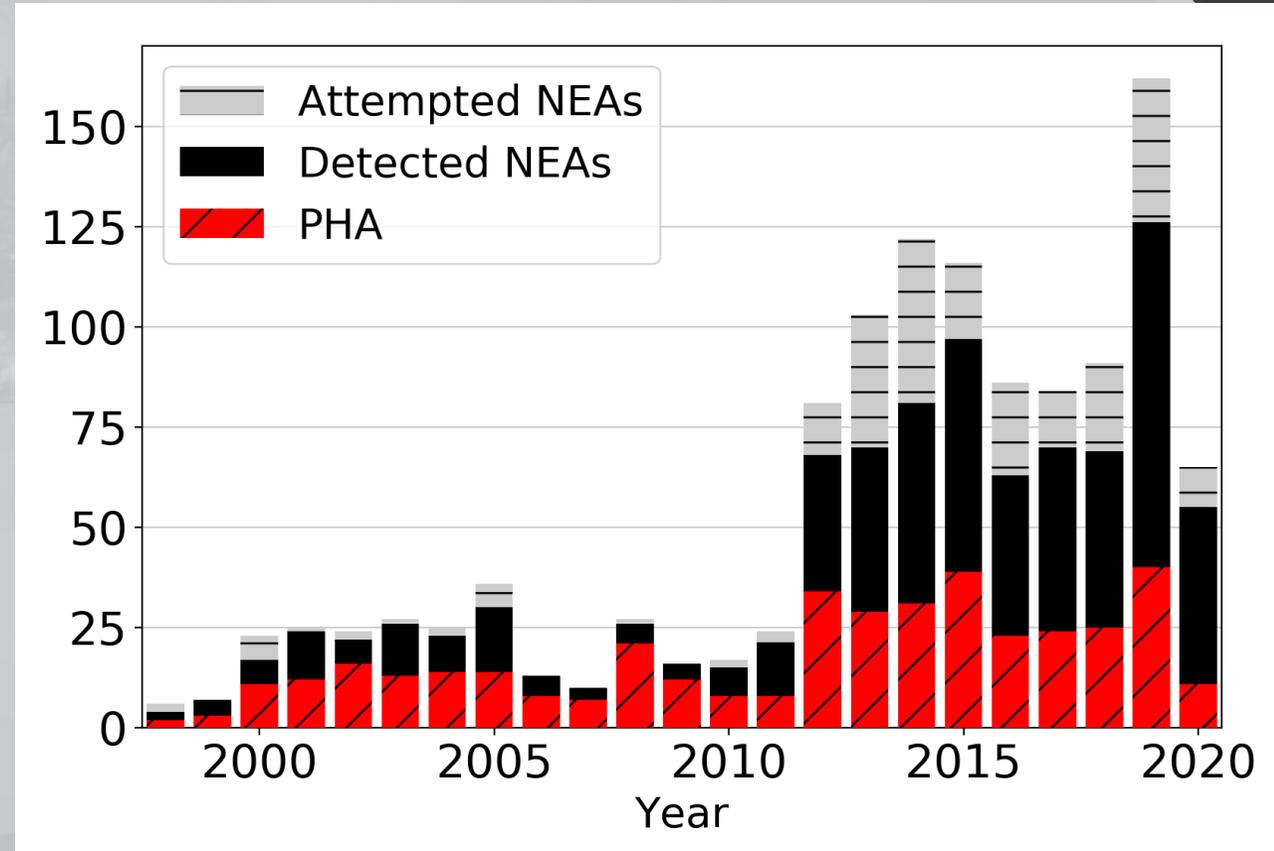
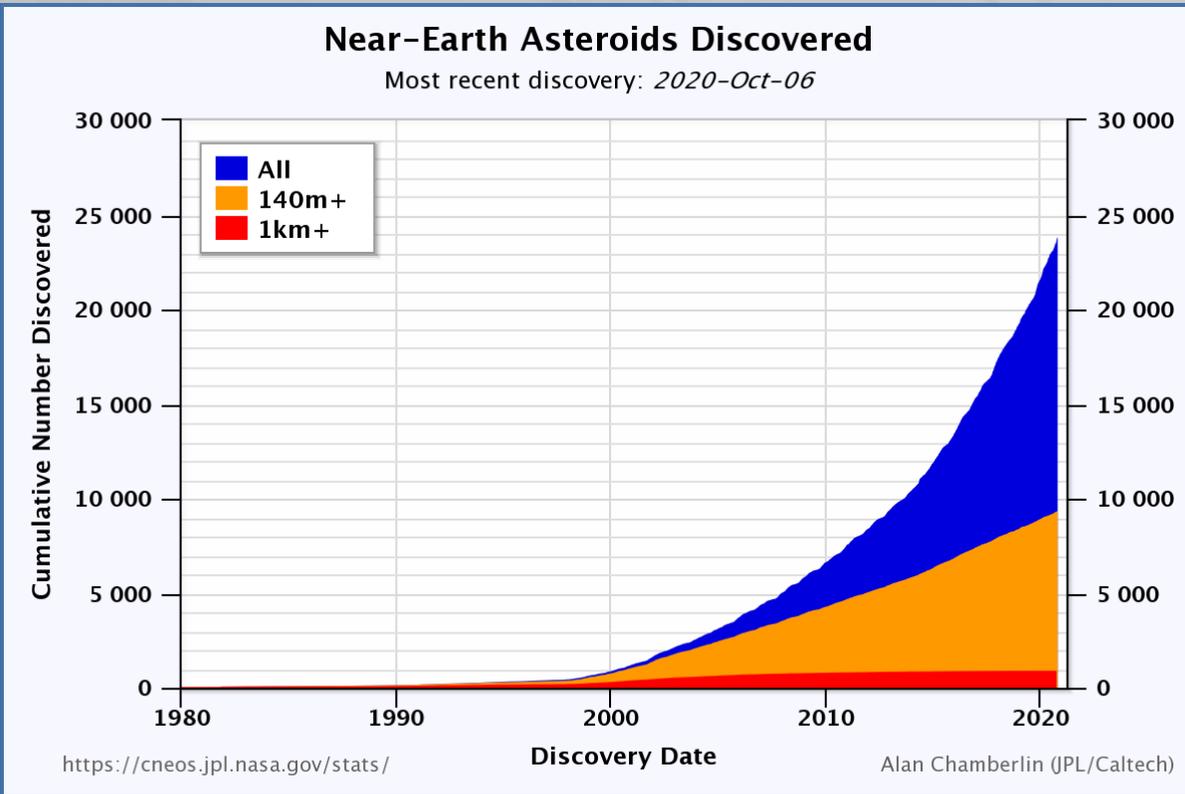
Most recent discovery: 2020-Oct-06



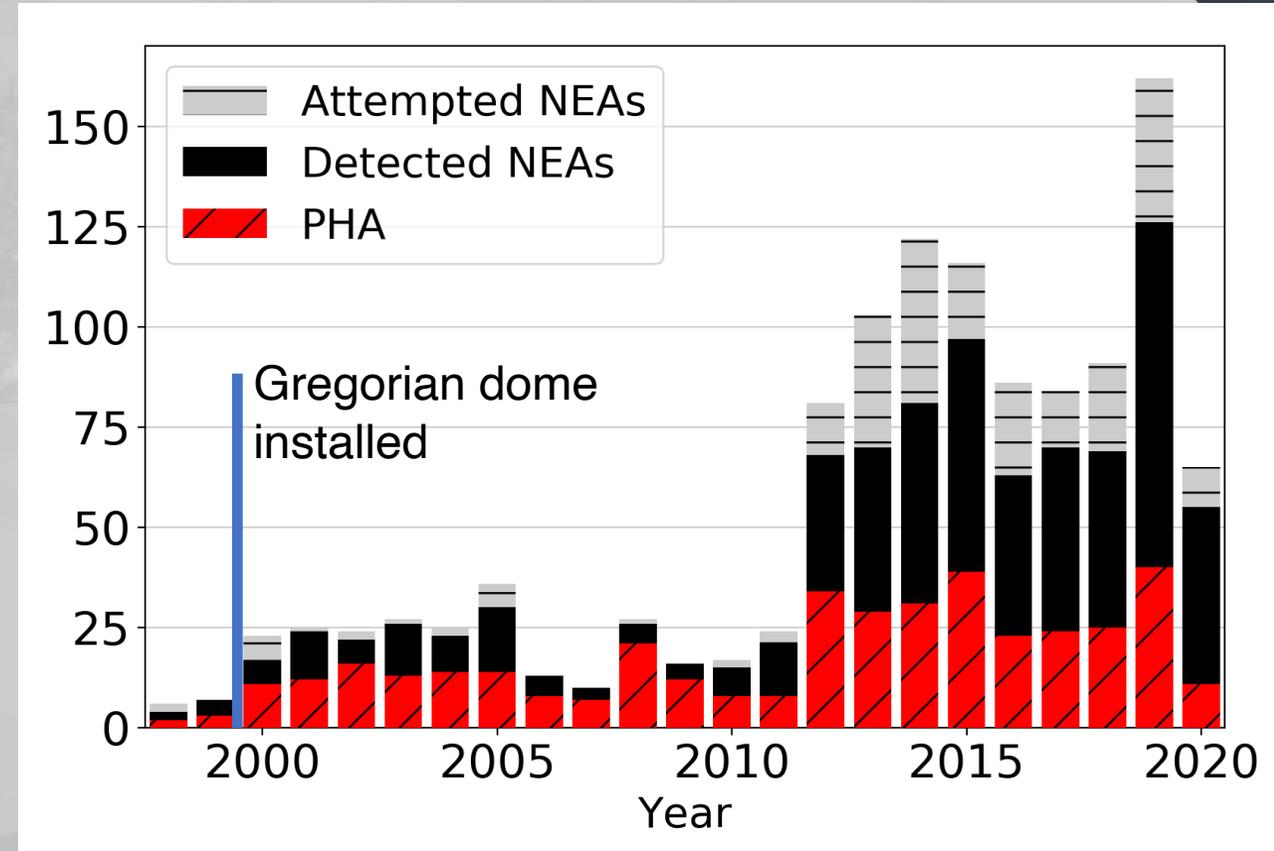
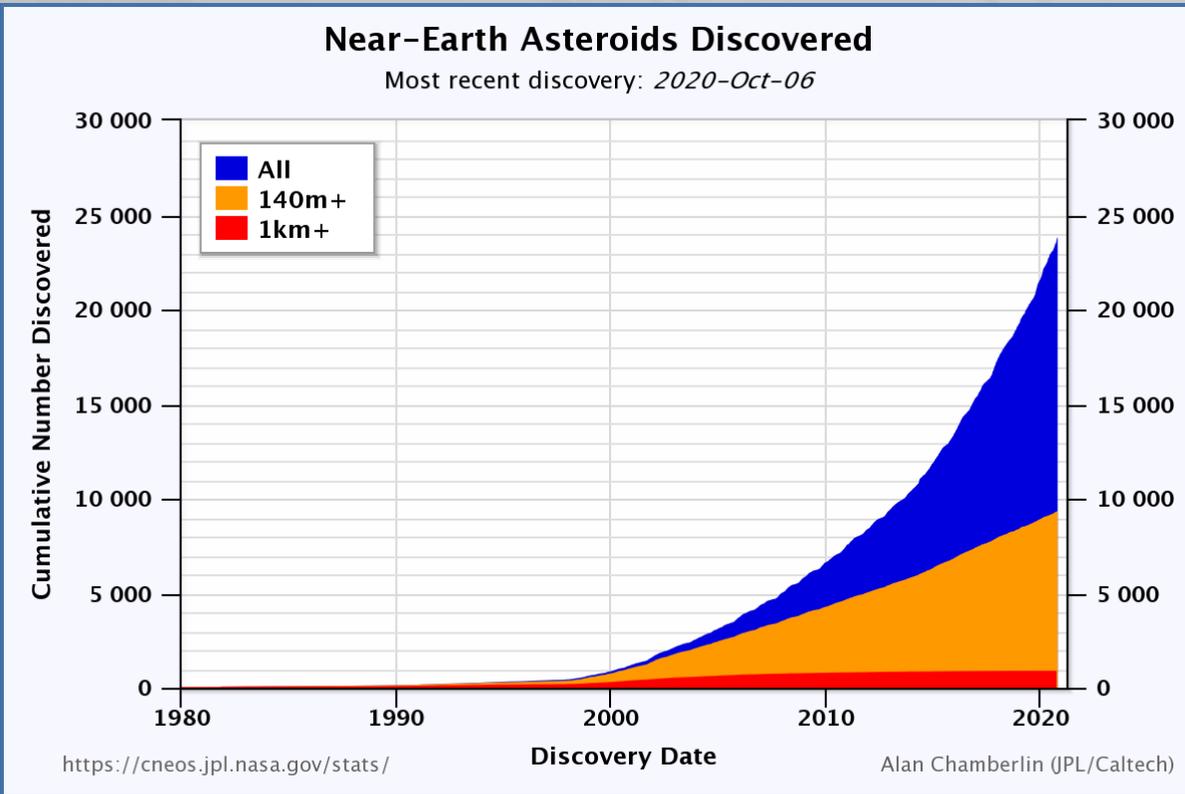
<https://cneos.jpl.nasa.gov/stats/>

Alan Chamberlin (JPL/Caltech)

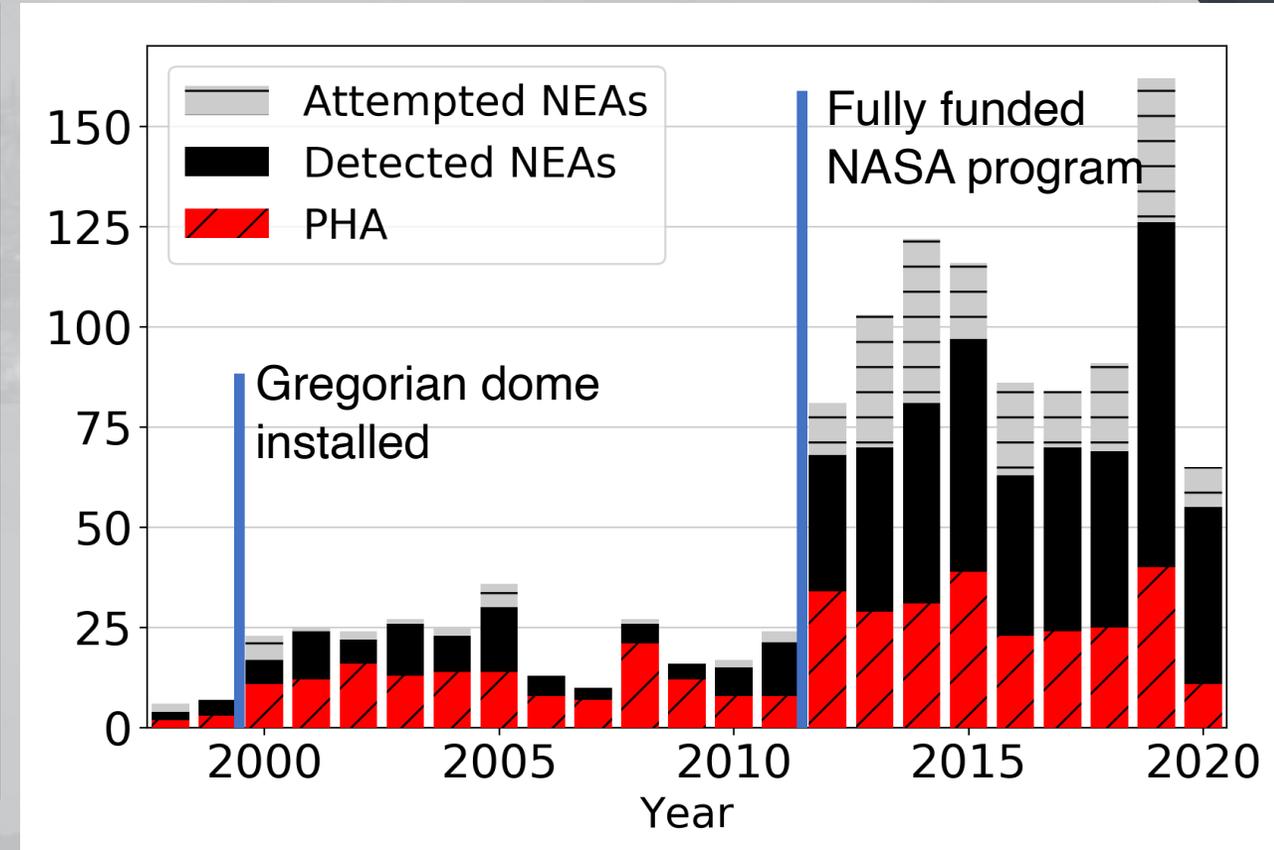
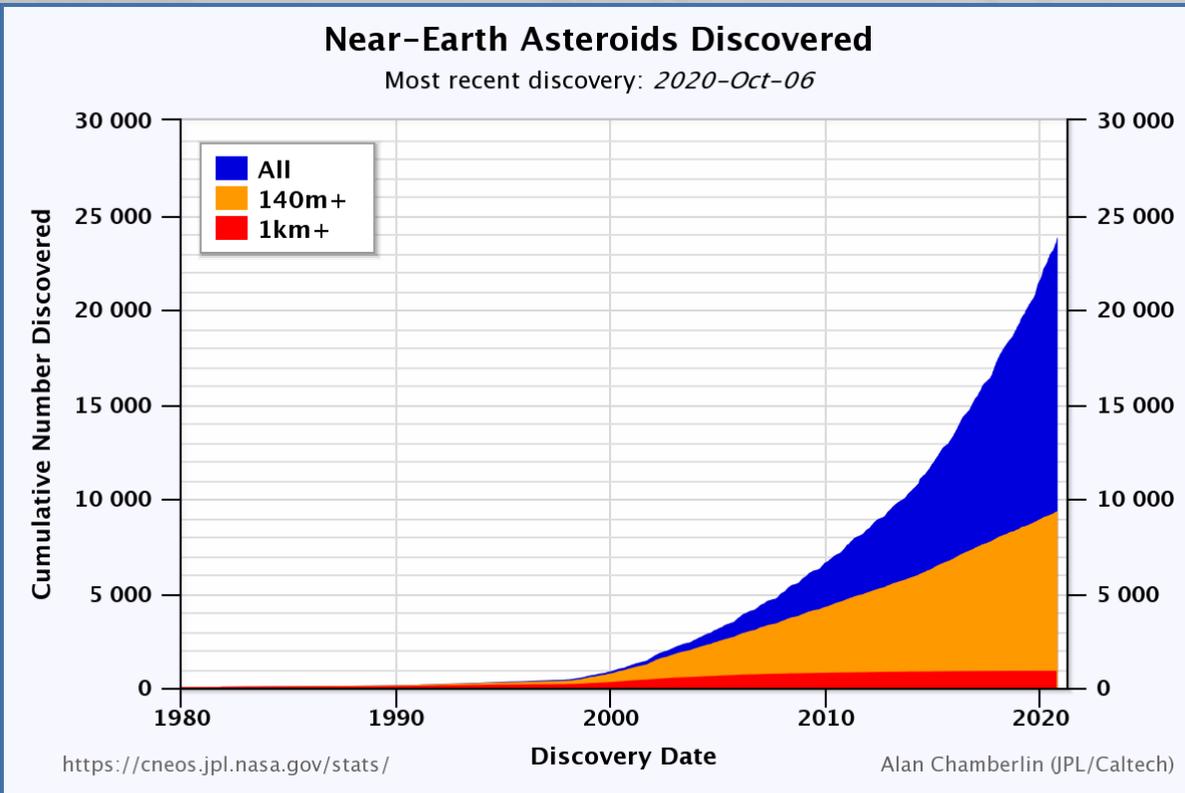
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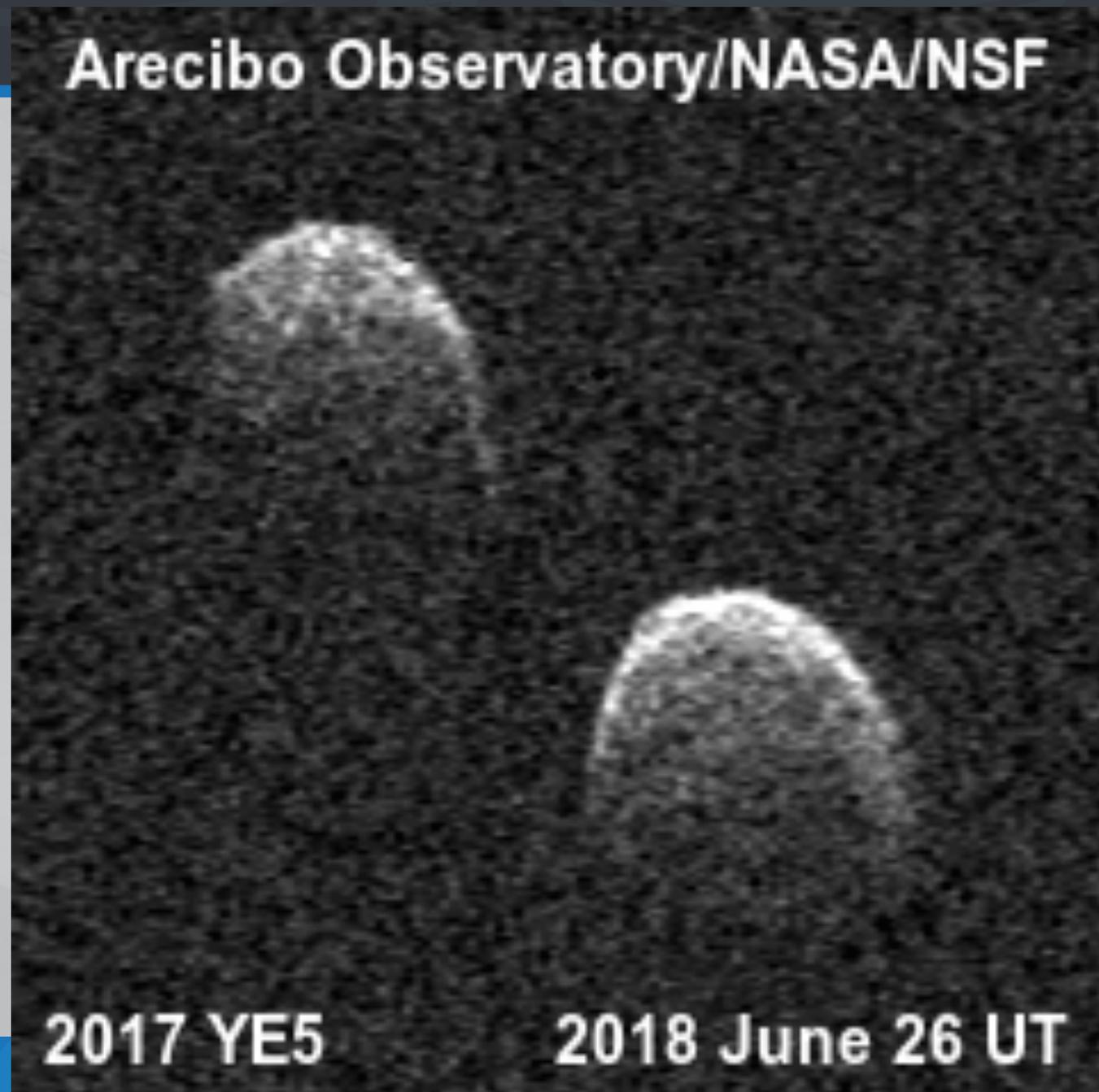
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2017 YE5

- Equal mass binary (only four known NEAs!)
- 7.5 m/pixel
- 20-24 hr period
- Albedo difference between bodies

Arecibo Observatory/NASA/NSF



2017 YE5

2018 June 26 UT



2014 JO25

Arecibo Observatory/NASA/NSF



- PHA
- Contact binary
~15 % of NEAs
- 7.5 m/pixel
- ~ 870 m
- 4.5 hr rotation
period



2014 JO25

19 Apr 2017



3200 Phaethon



Didymos

- PHA
- Binary system
- 7.5 m/pixel
- ~ 760 m
- 2.3 hr rotation period
- Target of NASA's DART mission

- 2nd largest PHA known
- 75 m/pixel
- ~ 6 km
- 3.6 hr rotation period
- Surface features visible (crater or boulder?)
- Target of JAXA's DESTINY+ mission set to launch 2022



1998 OR2

Arecibo Observatory/NASA/NSF



- Observed April 2020
- PHA
- 7.5 m/pixel
- ~2.3 km
- 4 hr rotation period
- Prominent crater visible in the "leading edge"

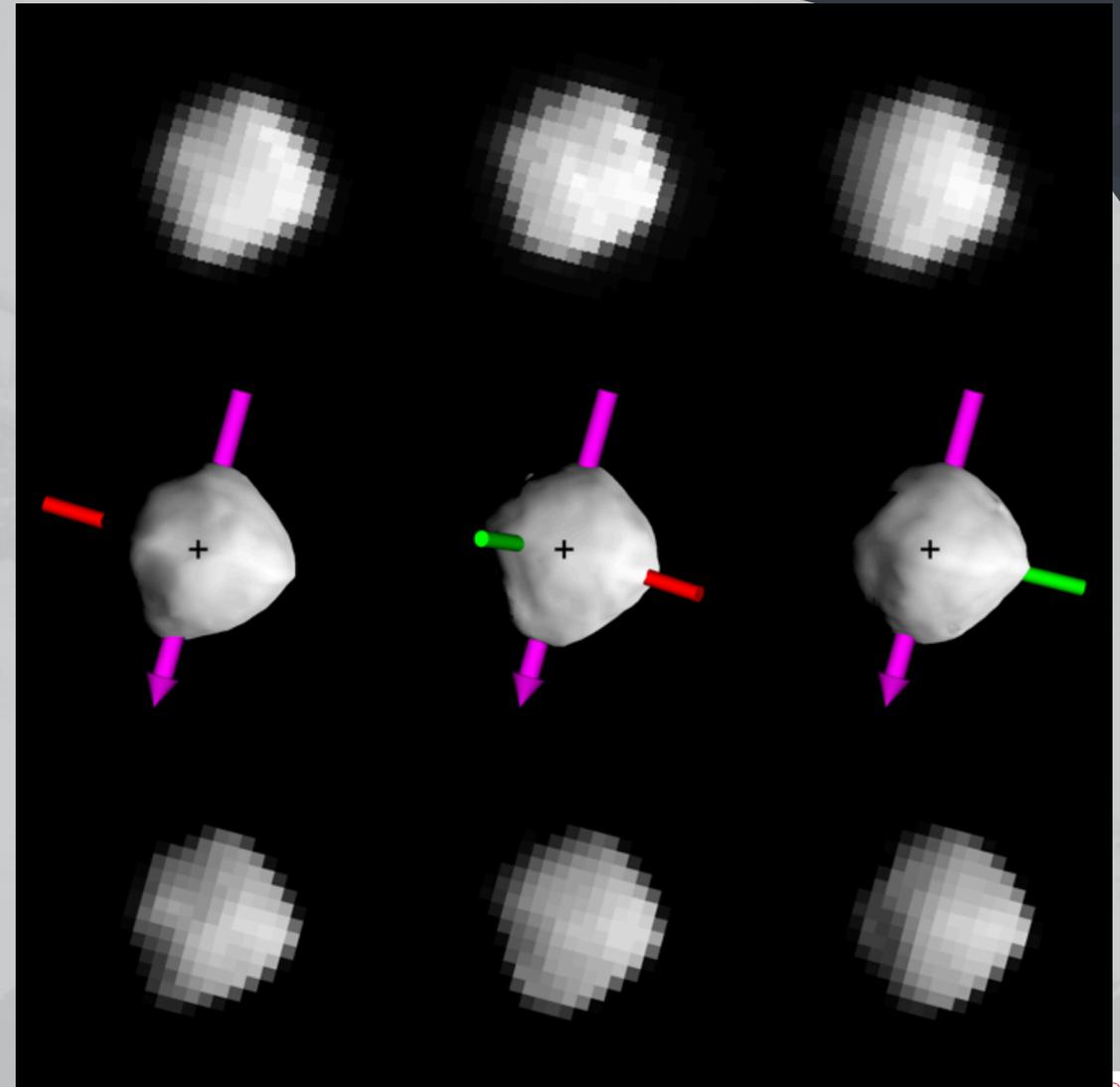


(52768) 1998 OR2

2020 Apr 18 UT



- Precise astrometry
- Surface Properties
- Discover binary asteroids
- Shape and spin state
 - Recently confirmed by NASA's OSIRIS-REx mission to 101955 Bennu



Mercury

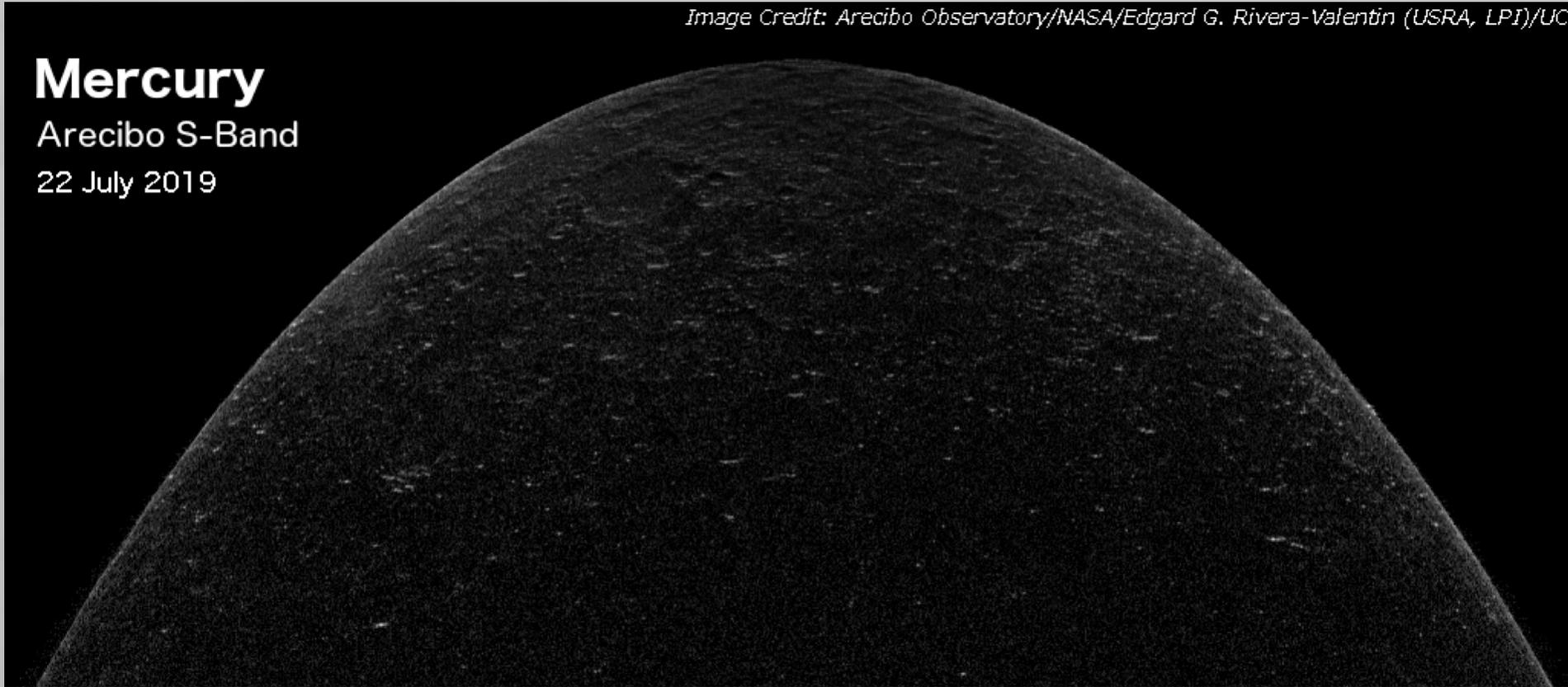


Image Credit: Arecibo Observatory/NASA/Edgard G. Rivera-Valentin (USRA, LPI)/UCF

Mercury

Arecibo S-Band

22 July 2019



- In the late 1960's Arecibo data determined the rotation rate to be 59 days, as opposed to 88 days previously accepted!
- Strong reflections from craters at the poles indicate water ice.

Venus

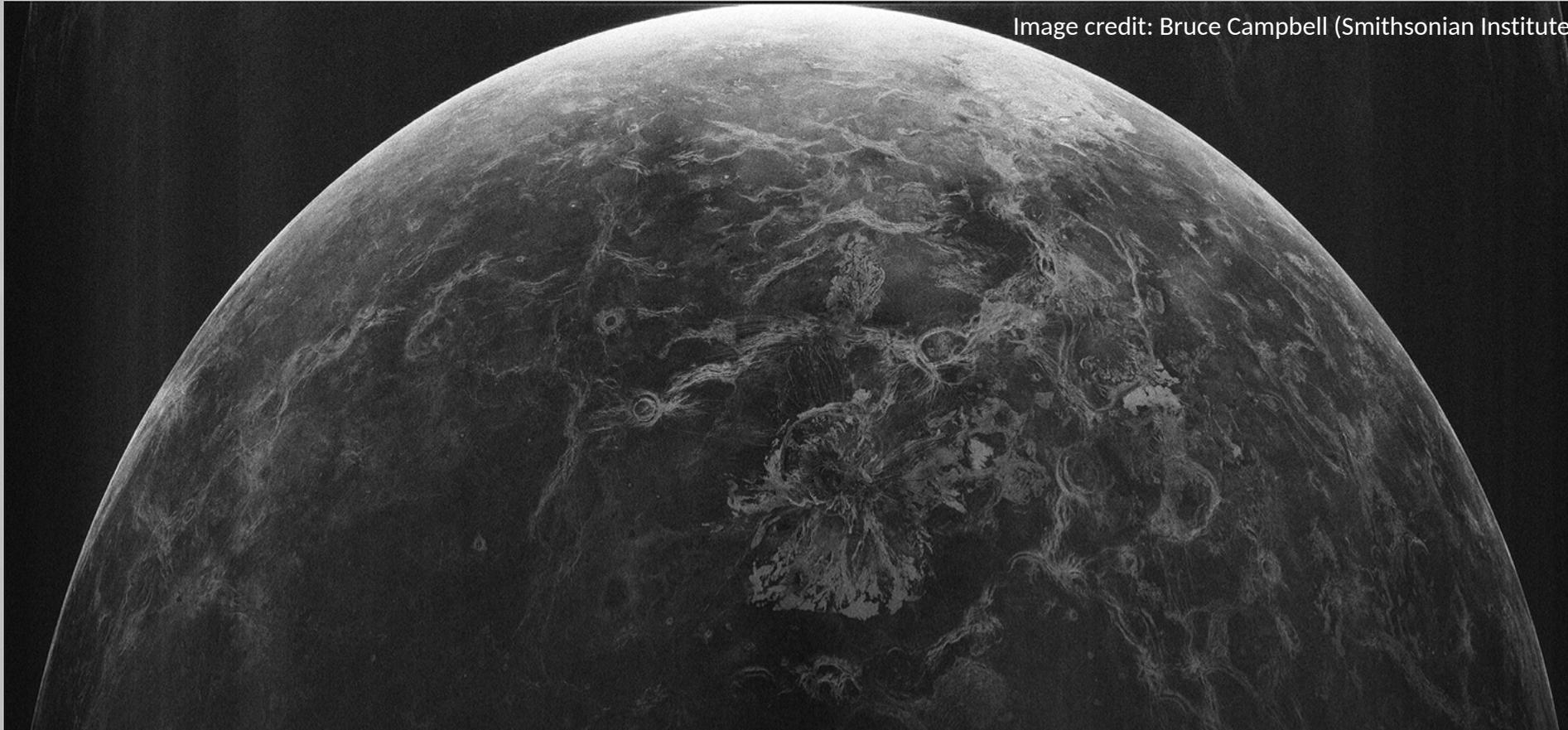


Image credit: Bruce Campbell (Smithsonian Institute)

- Thick cloudy atmosphere and intense pressure and temperature at surface makes optical/infrared remote sensing and landing missions difficult.
- Radar penetrates clouds, revealing surface and sub-surface features.



Venus

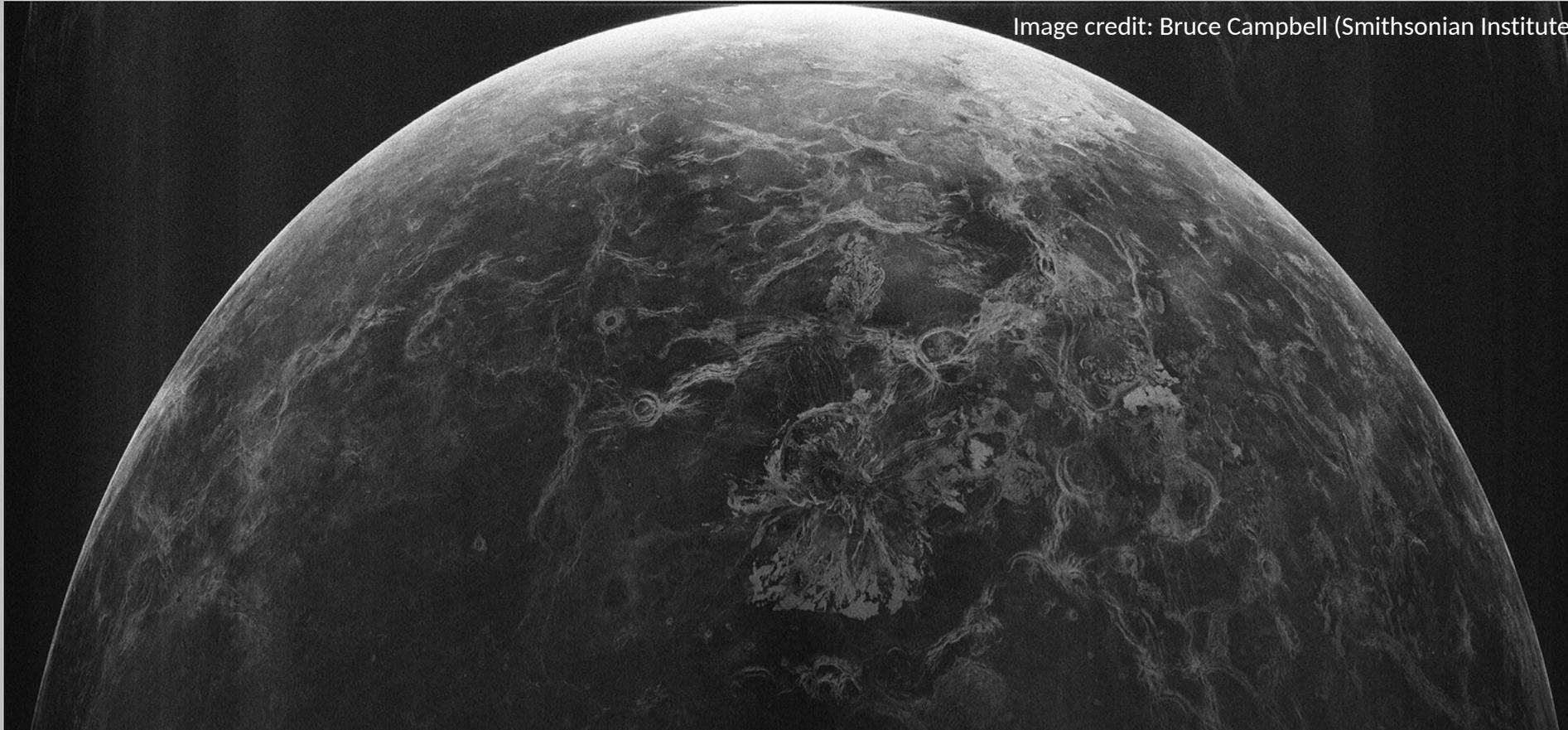
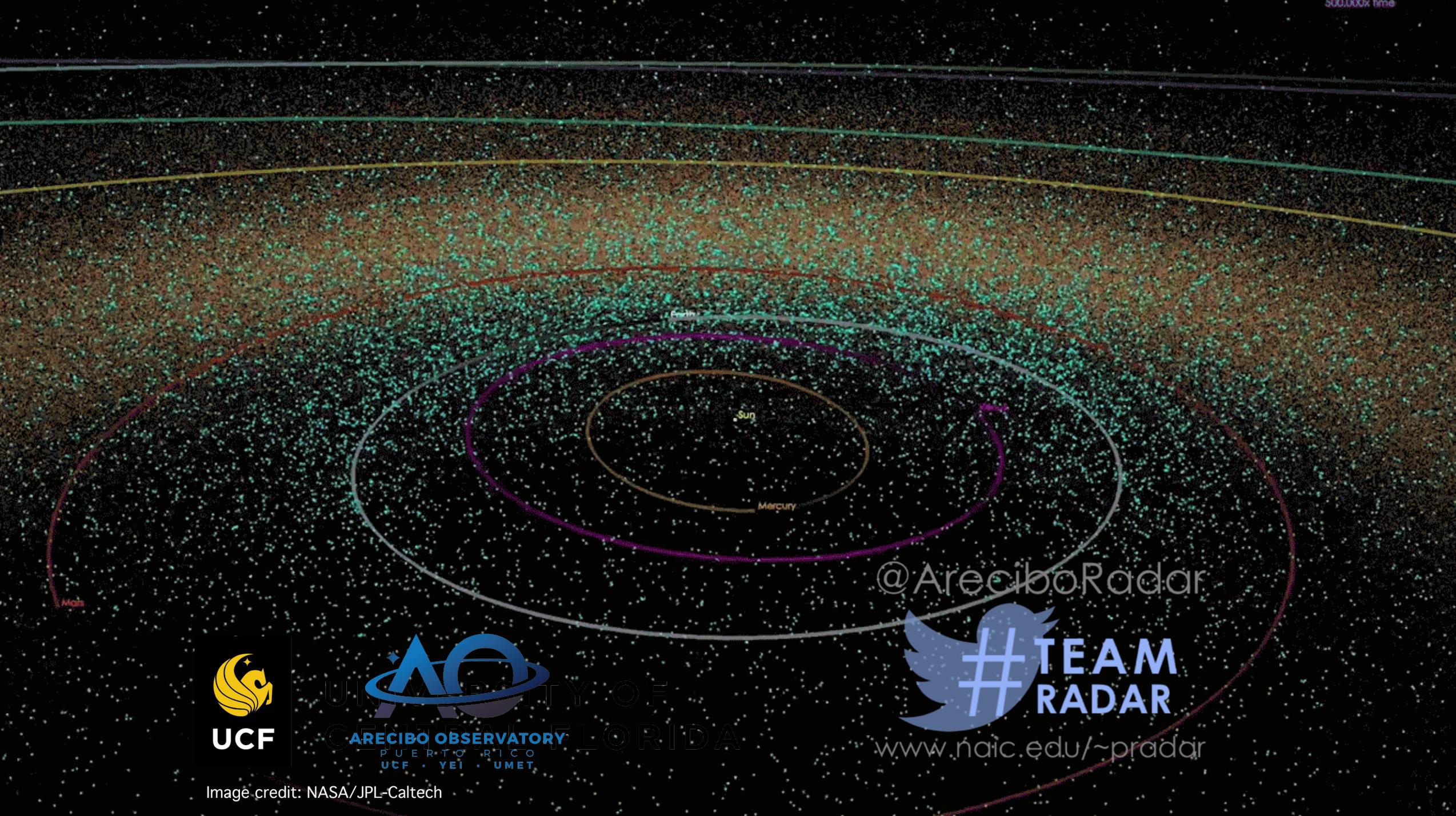


Image credit: Bruce Campbell (Smithsonian Institute)

- Determination of the core size, spin period, spin period variation, precession rate
Spin state and moment of inertia of Venus (Margot et al. 2021)



Earth

Sun

Mercury

Mars

@AreciboRadar



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PUERTO RICO
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RADAR

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