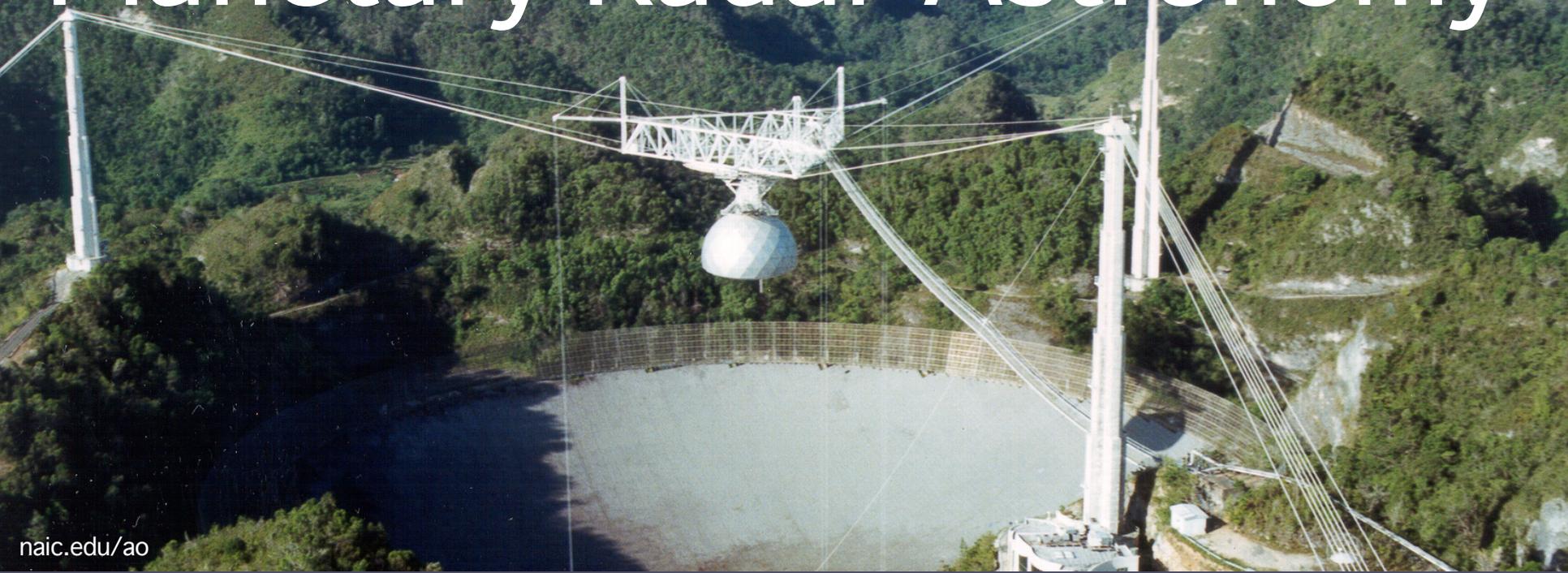


Radar Observing: Planetary Radar Astronomy



naic.edu/ao

Dylan Hickson and #TeamRadar
Postdoctoral Research Scientist
Arecibo Observatory & The University of Central Florida



UNIVERSITY OF
CENTRAL FLORIDA



ARECIBO OBSERVATORY
PUERTO RICO
UCF • YEI • UMET

GBO/AO Single Dish Training Workshop, August 22, 2019

Outline

- Why use Radar? What is it good for?
- Introduction to Radar Systems
- Radar at Arecibo
- Monostatic vs Bistatic
- Science Returns – Applications



Image credit: Lynn Carter (LPL)



Arecibo Observatory - Green Bank
NASA/NSF

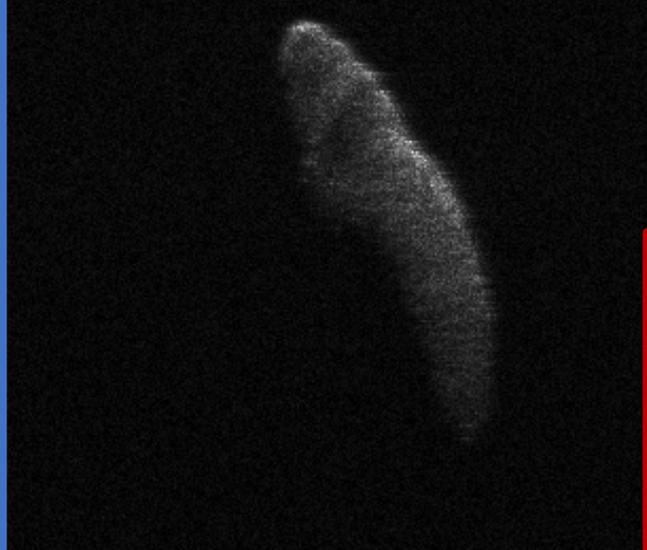
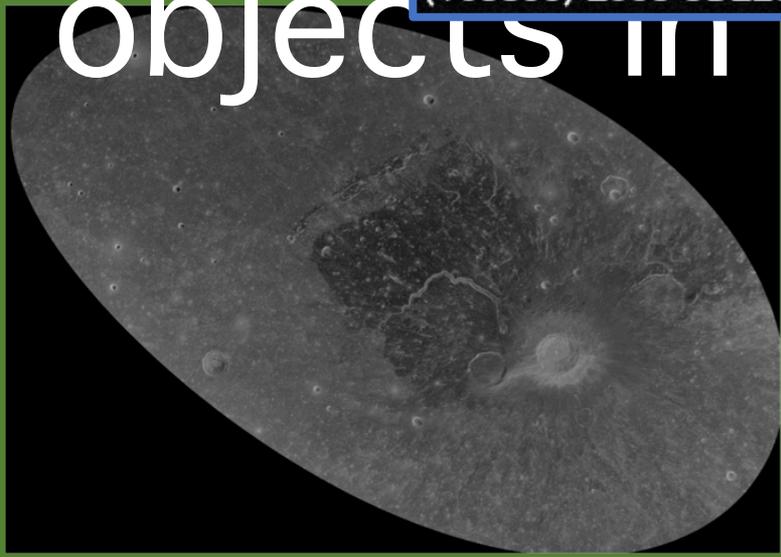


Image at
resolutions
comparable to
space missions

Why use objects in space

Penetrate
through
atmospheres



(163899) 2003 SD220 18 Decemb

Reveal
buried
features

Use
polarimetry
to detect
surface
properties

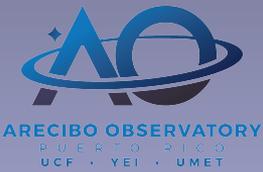
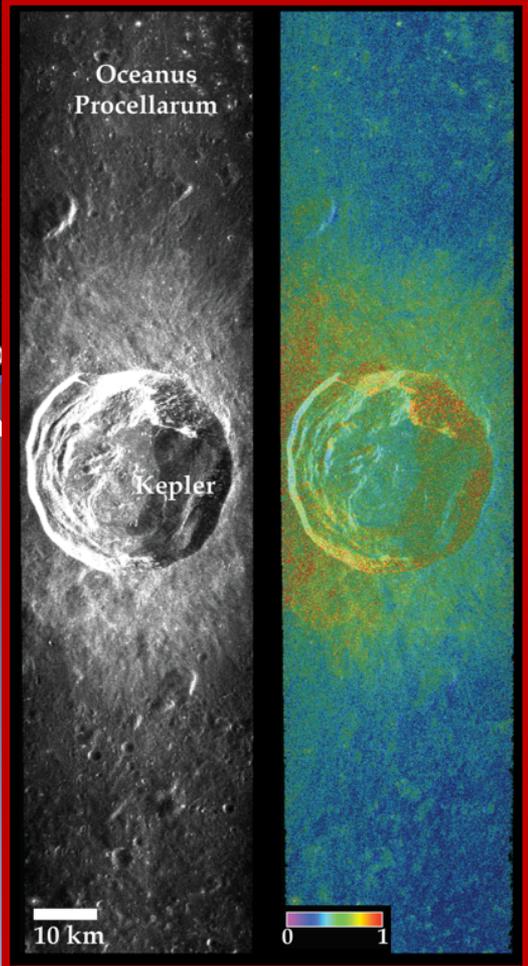
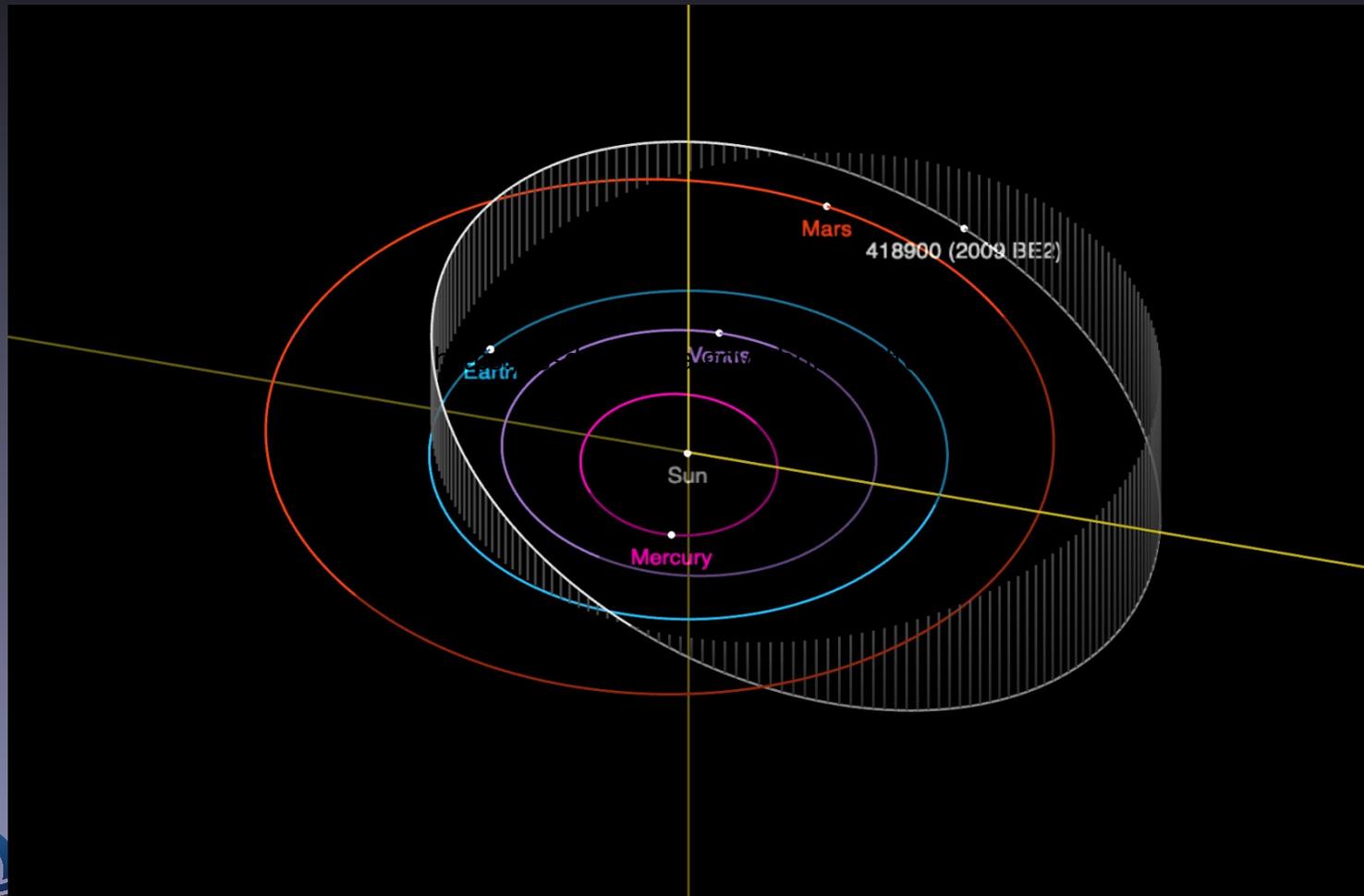


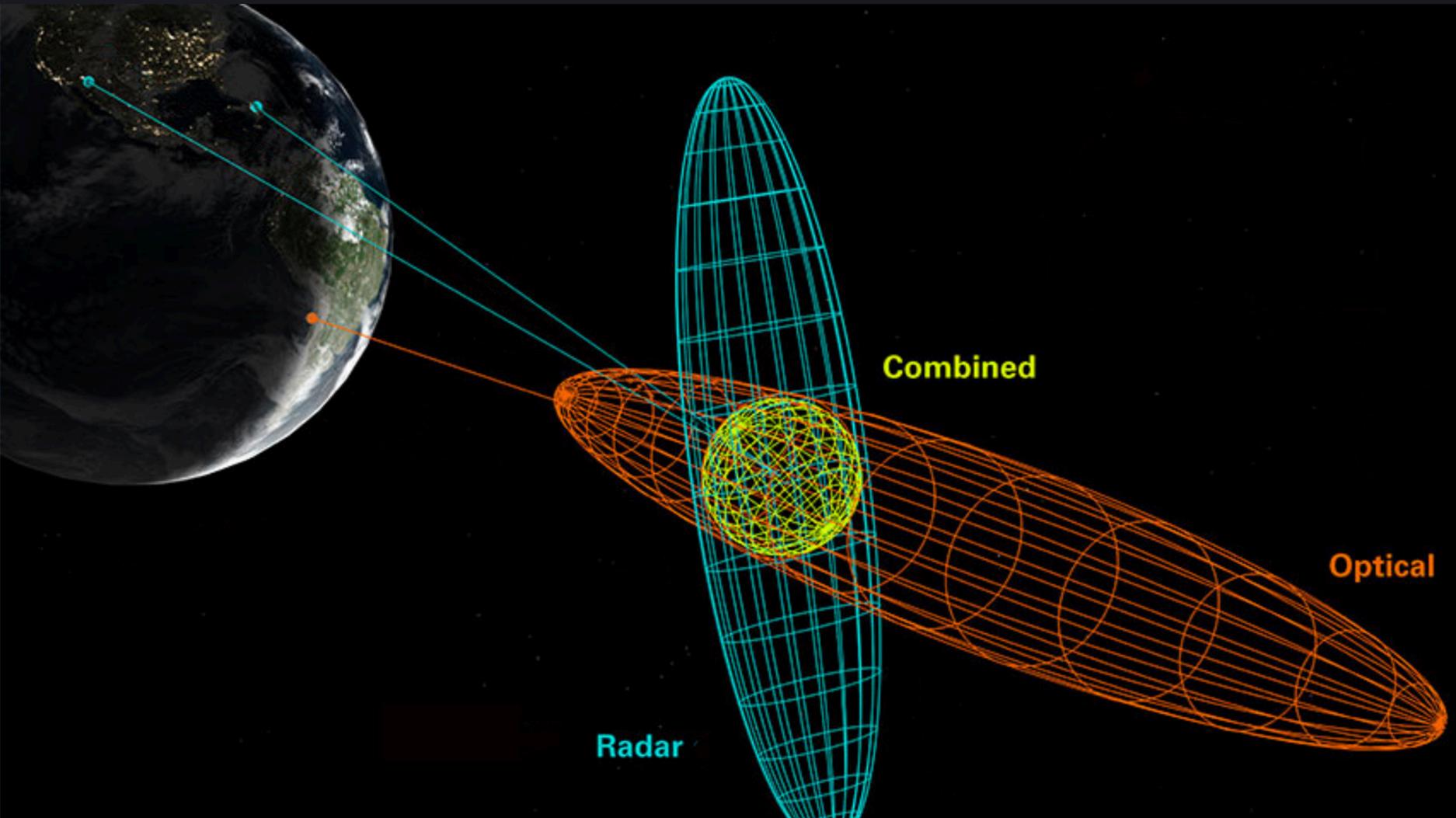
Image credit: Bruce Campbell (SI)

Image credit:
G. Wes Patterson (JHU/APL)

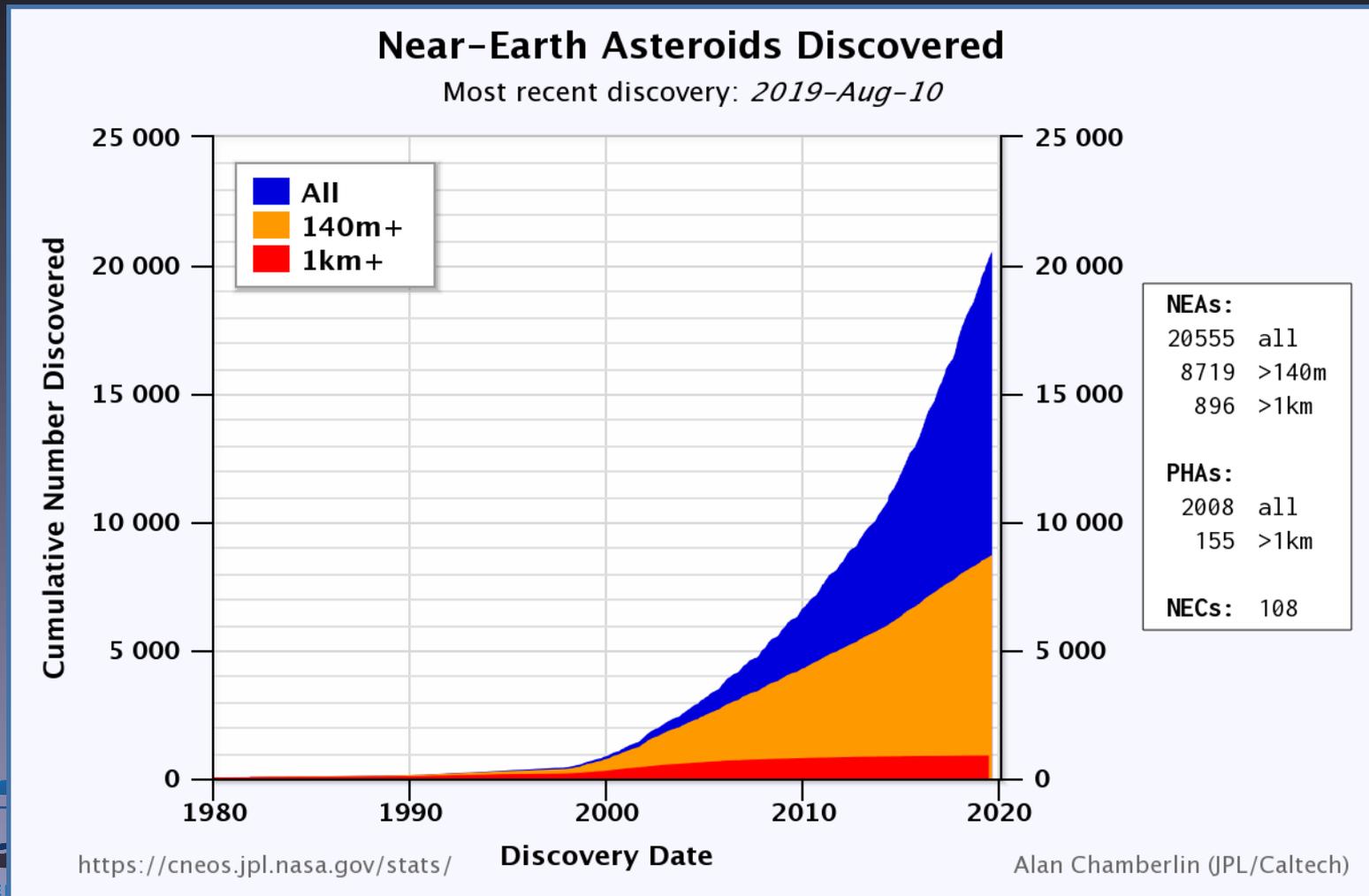
Astrometry: refining orbits of celestial bodies



Astrometry: refining orbits of celestial bodies

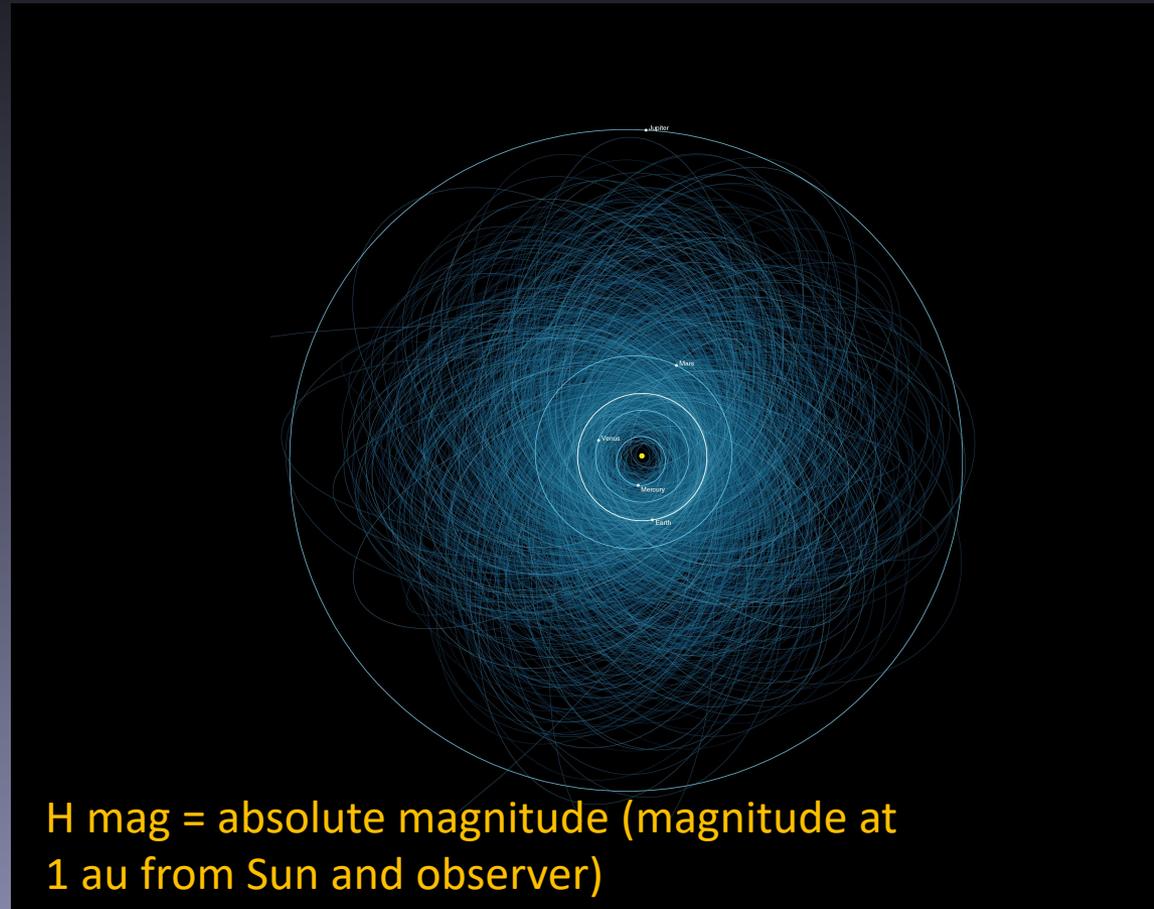


NASA has congressional mandate to search and track all near-Earth asteroids (NEAs) larger than 140 m (~ 1/3 known to date)



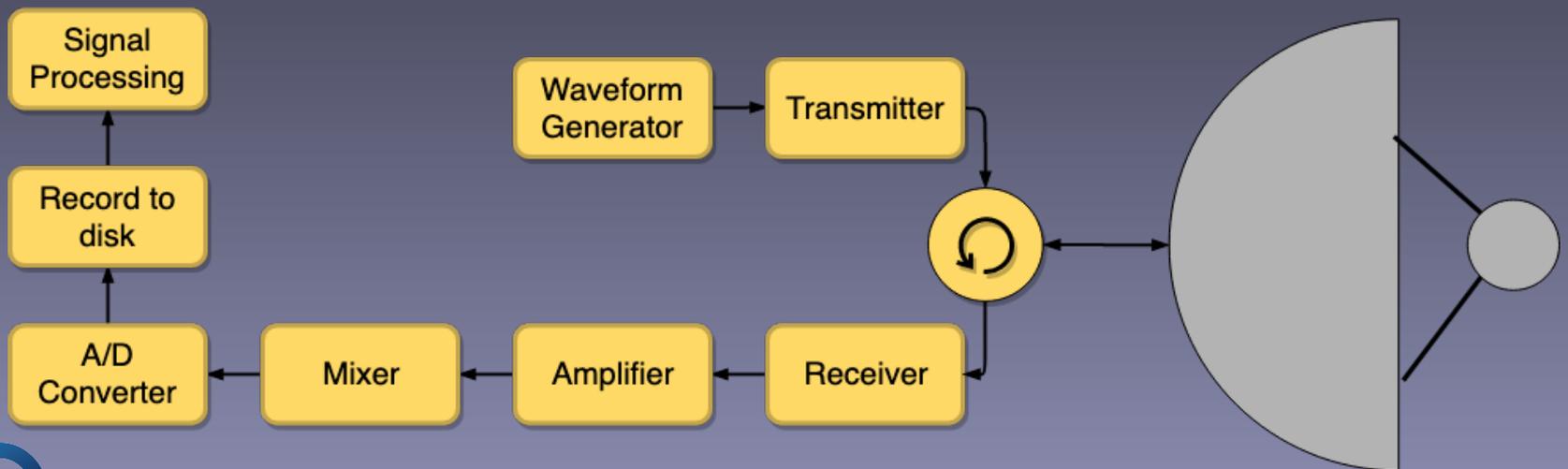
NEO priorities

- Potentially Hazardous Asteroid (PHA): asteroids >140 m (H mag = 22) in diameter and can get closer than ~ 19.5 LD (0.05 au)
- Near-Earth Object Human Space Flight Accessible Targets Study (NHATS): asteroids that are favorable targets for human space exploration [$\Delta v < 12$ km/s, 450 days]

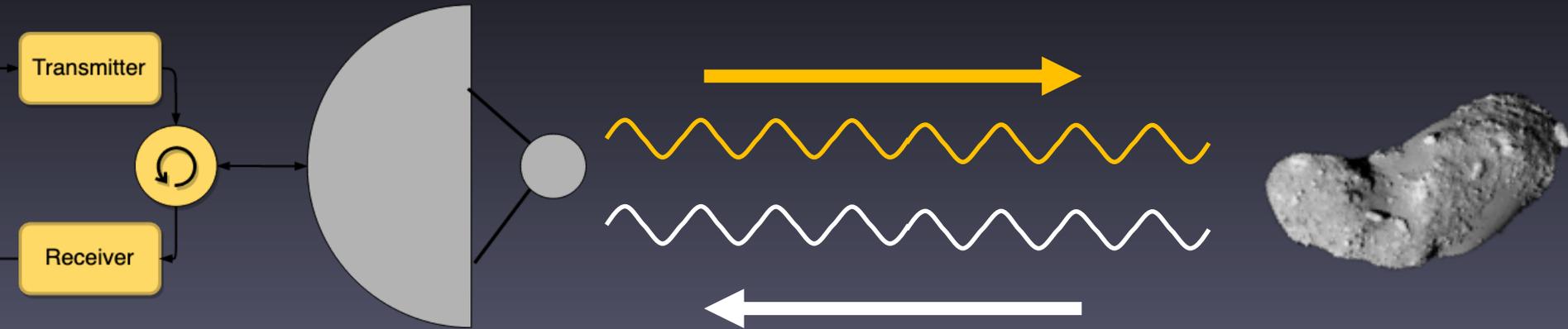


What is **RADAR**?

- **RA**dio **D**etection **A**nd **R**anging
- Active remote sensing – we control the signal!
- Maximize signal properties to enhance SNR
- Measure reflected radio waves (so targets must be reflective)



The Radar Equation



$$P_{rx} = [P_{tx}] [G_{tx}] \left[\frac{1}{4\pi r^2} \right] [\sigma] \left[\frac{1}{4\pi r^2} \right] [A_{eff}]$$

Received Power Transmitted Power Transmitter Gain Radar Cross Section Geometric Spreading Effective Aperture



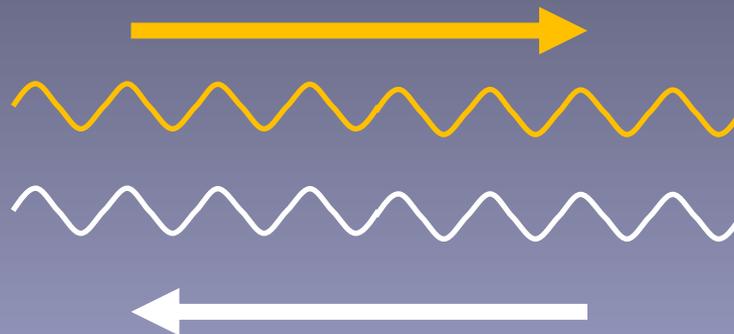
EM Reflection

- Radar albedo is the cross section normalized by the projected area
- Derive Fresnel reflectivity from radar albedo through scattering theory
- Fresnel reflectivity dependent on constitutive parameters of near-surface material

$$\hat{\sigma} = \frac{\sigma}{A_{proj}} \quad \hat{\sigma} \propto R_f$$

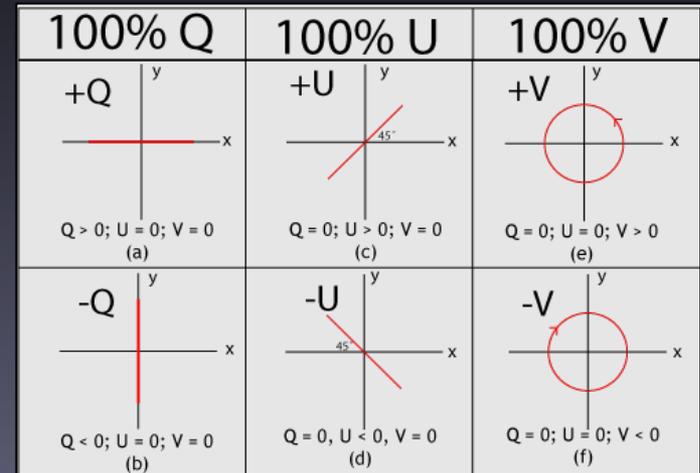
$$R_f = \left[\frac{\sqrt{n} - 1}{\sqrt{n} + 1} \right]^2$$

$$n = \sqrt{\tilde{\epsilon}_r \tilde{\mu}_r}$$



Radar Polarimetry

- Transmit a circularly polarized signal
- Receive in both handedness
 - Same sense as transmitted, SC
 - Opposite sense, OC
- Circular polarization ratio (CPR), μ_C
- Stokes vector – target decomposition



$$\mu_C = \frac{\sigma_{SC}}{\sigma_{OC}}$$

$$\vec{S} = \begin{bmatrix} I \\ Q \\ U \\ V \end{bmatrix} = \begin{bmatrix} \langle V_L^2 \rangle + \langle V_R^2 \rangle \\ 2\langle V_L V_R \cos \delta \rangle \\ 2\langle V_L V_R \sin \delta \rangle \\ \langle V_L^2 \rangle - \langle V_R^2 \rangle \end{bmatrix}$$



SNR: Detectability

- Target's doppler bandwidth depends on size and spin state:

$$B = \frac{4\pi D \cos\phi}{\lambda_0 P_{spin}}$$

- RMS noise power depends on bandwidth, integration time, and system temperature:

$$N_{rms} = kT_{sys} \sqrt{\frac{B}{\tau}}$$

- Need SNR of ~ 6 for detection, but much higher SNR for imaging

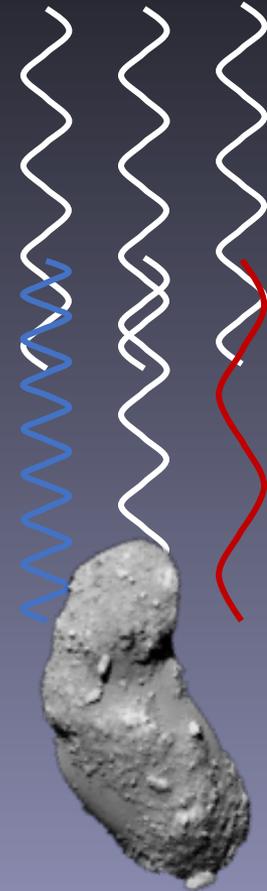
$$SNR = \frac{P_{rx}}{N_{rms}}$$

$$P_{rx} = \frac{P_{tx} G_{tx} \sigma A_{eff}}{(4\pi)^2 r^4}$$

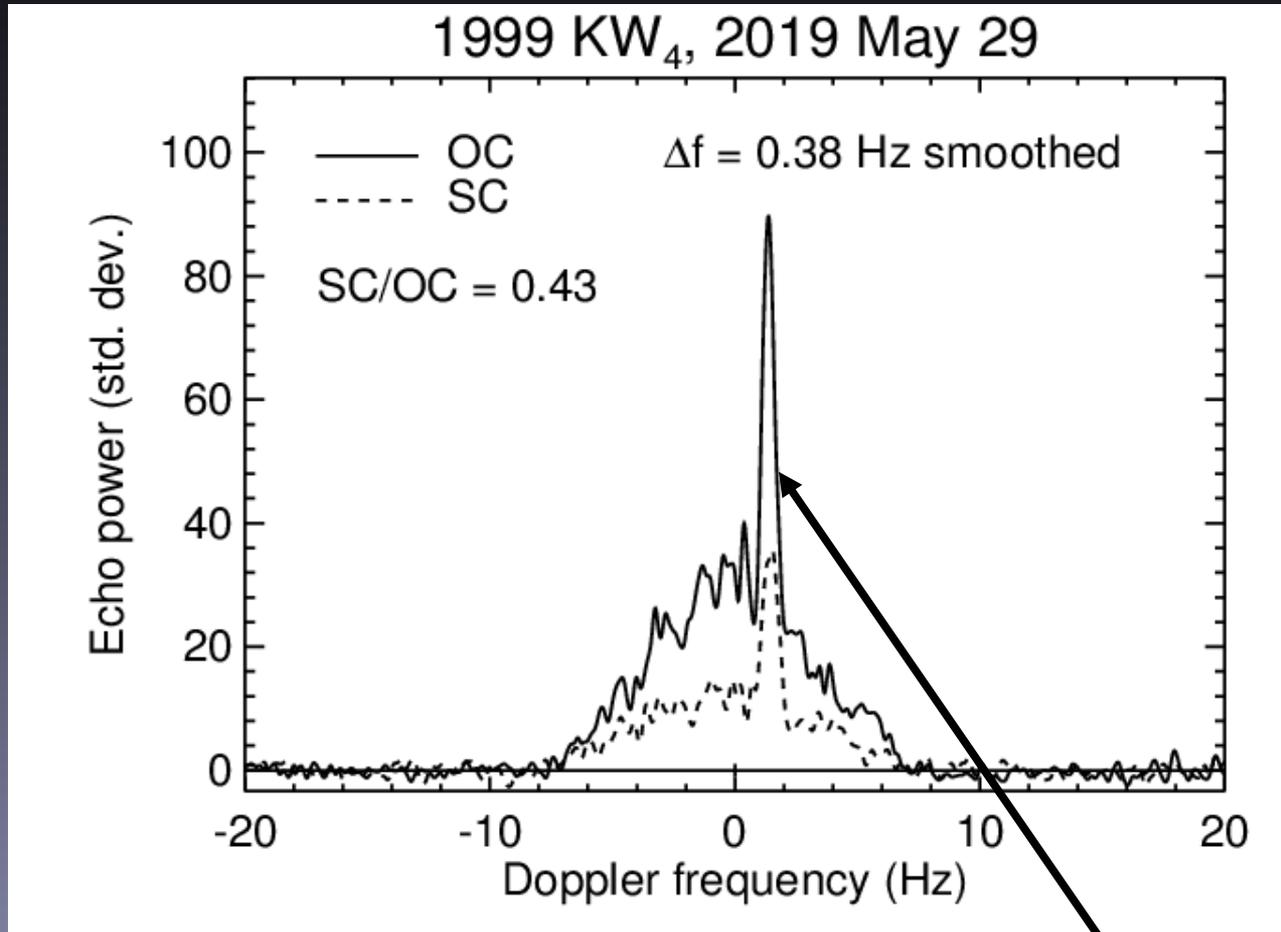


Continuous Wave (CW)

- Constant amplitude/frequency radio wave transmitted
- Advantages:
 - Maximizes power in reflected signal
 - Doppler shift in received signal indicates target motion and rotation
 - Good for finding binaries!
- Disadvantages:
 - Cannot provide ranging information
- Often used initially to confirm correct ephemeris in targeting NEOs



Continuous Wave (CW)



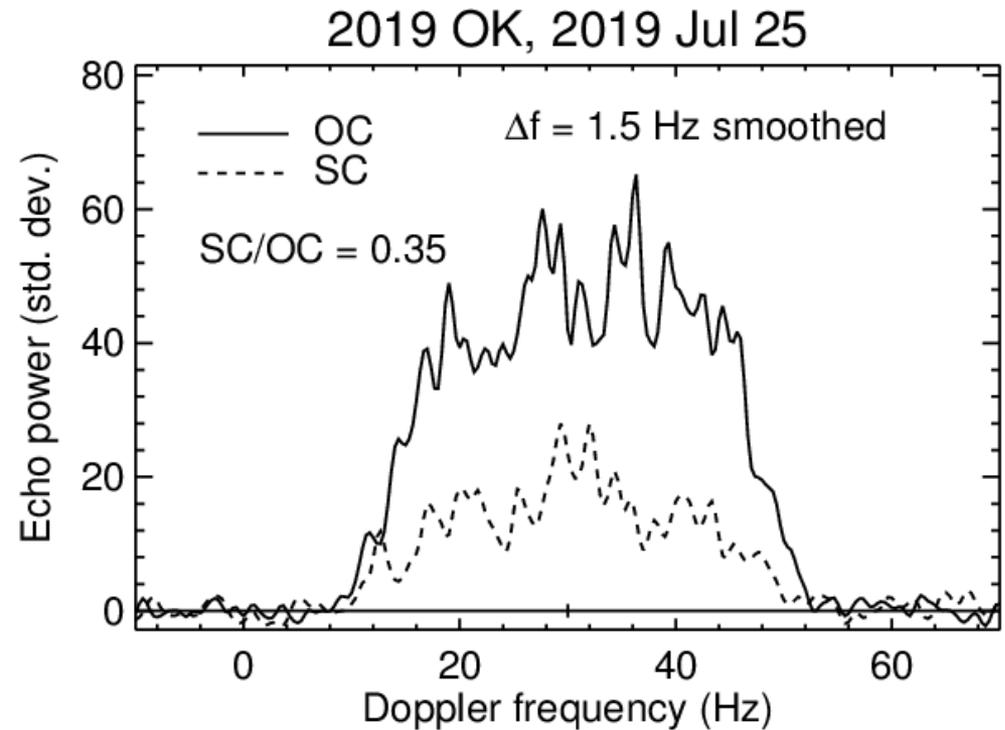
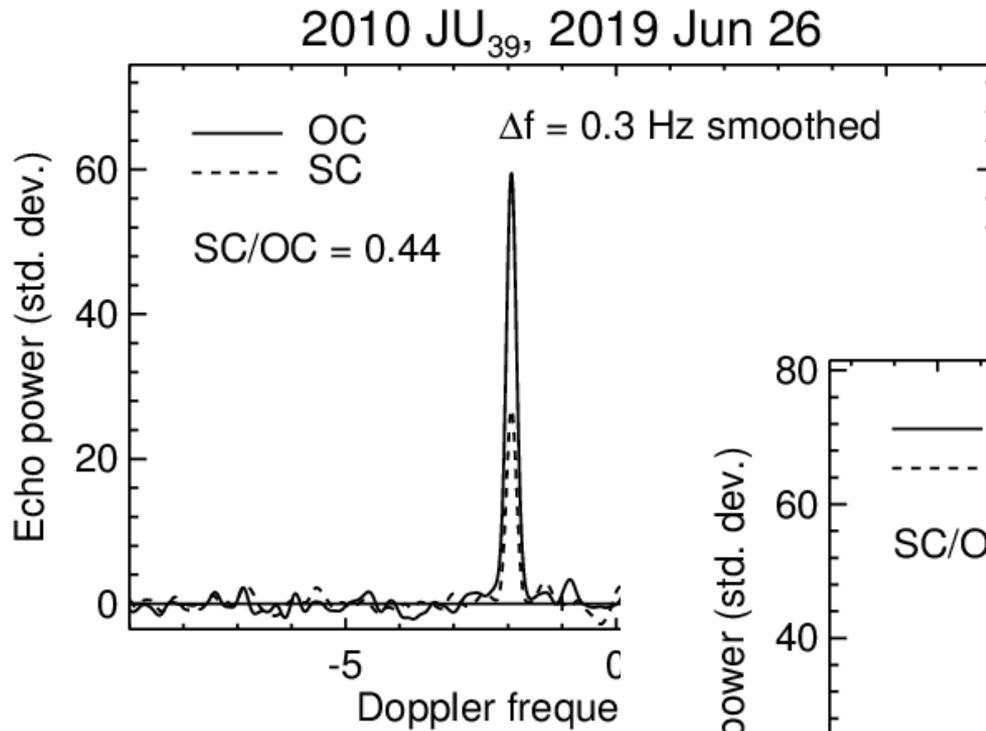
- H mag = 16.5
- $r = 0.03$ au

Secondary of
binary system!

Continuous Wave (CW)

~ 5.5 Earth diameters!!!

- H mag = 23.3
- $\Delta = 0.00048$ AU



- H mag = 19.6
- $\Delta = 0.06$ au



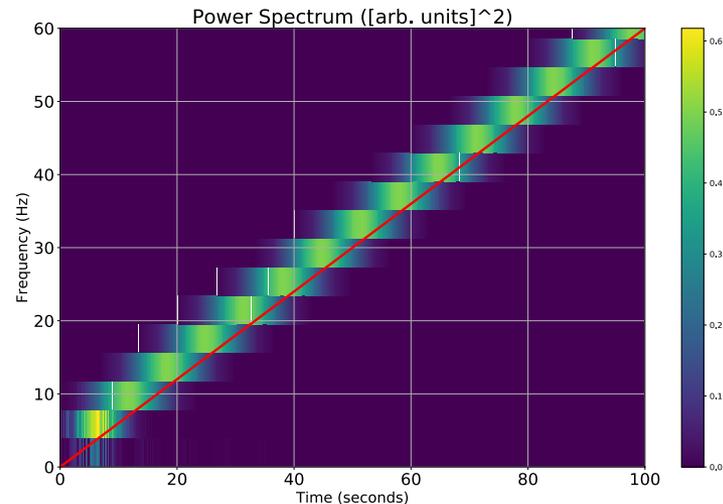
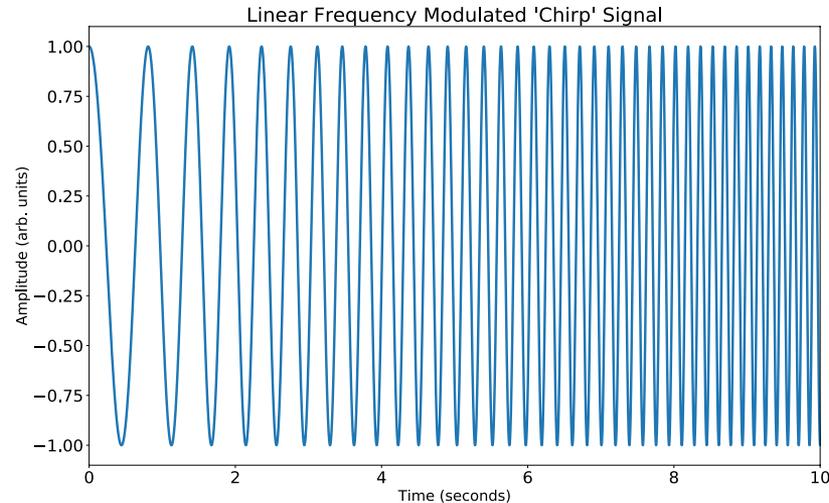
Modulated Waveforms

- Pulsing transmitted signal allows range determination
- Fine resolution requires narrow pulse width, T
- Signal bandwidth inverse of pulse width, $B = 1/T$
- Trade off:
 - For fine range resolution we desire short pulse width, but this decreases P_{rx}
 - For increased SNR we desire long pulse width, but this decreases range resolution
- A way around this is to modulate the signal in amplitude, frequency, or phase in order to increase B
- Range determination requires time structure in transmitted signal

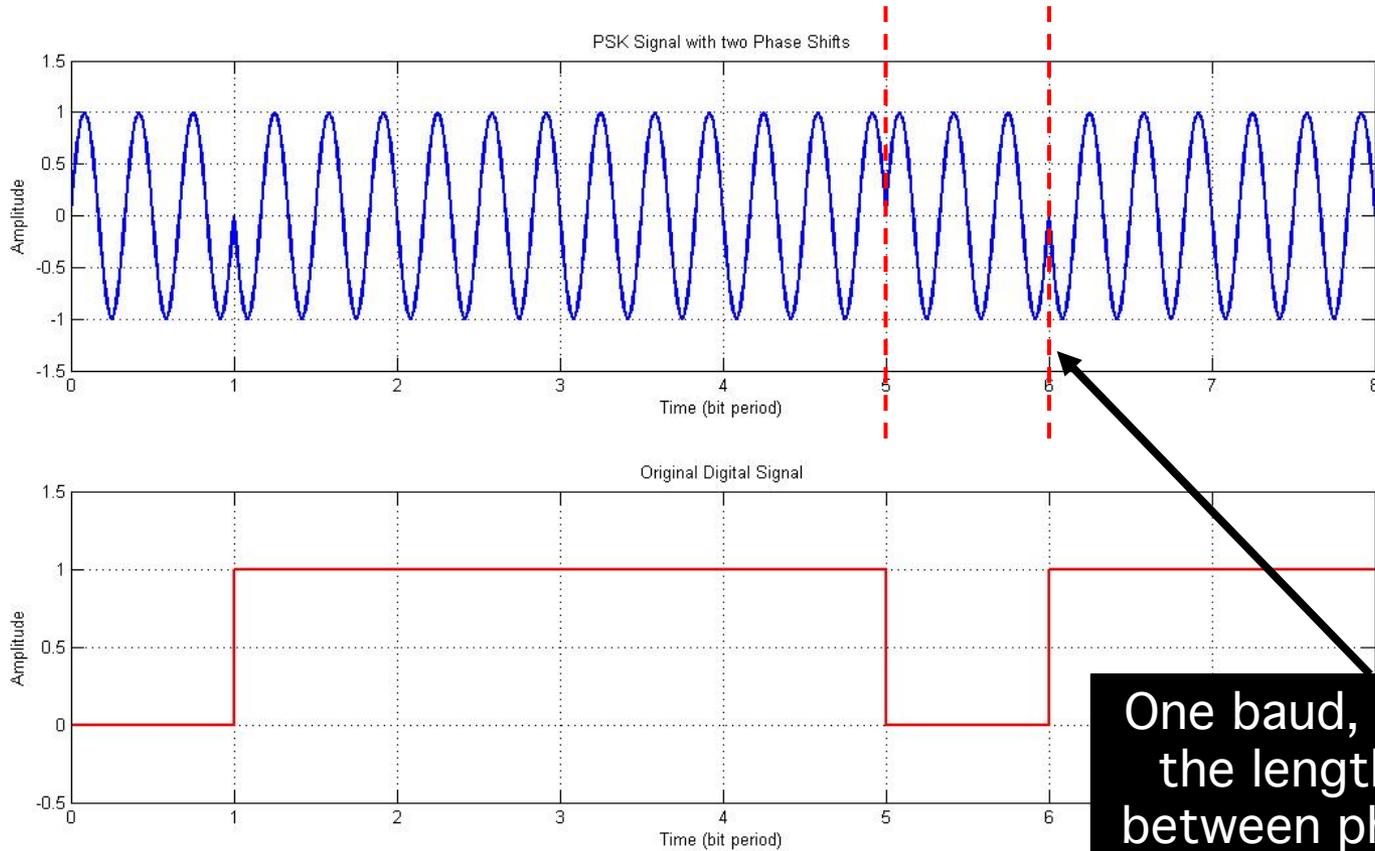


Linear Frequency Modulation

- Bandwidth = $f_2 - f_1$
- Matched filter maximizes SNR
- Convolve received signal with transmitted signal



Binary Phase Coded Waveform



One baud, defined as the length of time between phase shifts

- Code Bandwidth = $1 / [\text{baud}][\text{codelength}]$

$$\Delta r = \frac{c \cdot \text{baud}}{2}$$

- Convolve received signal with transmitted signal



Planetary Radar: Goldstone (JPL)

- Declination range: -35 – 90
(79% of the whole sky)
- Several antennas (the largest, DSS-14: 70 m)
- Transmitter frequency: 8560 MHz (3.5 cm)
- Power up to 500 kW
- ~ 70 objects/year attempted, ~ 60 detected



Image credit: NASA/JPL-Caltech



Planetary Radar: Arecibo

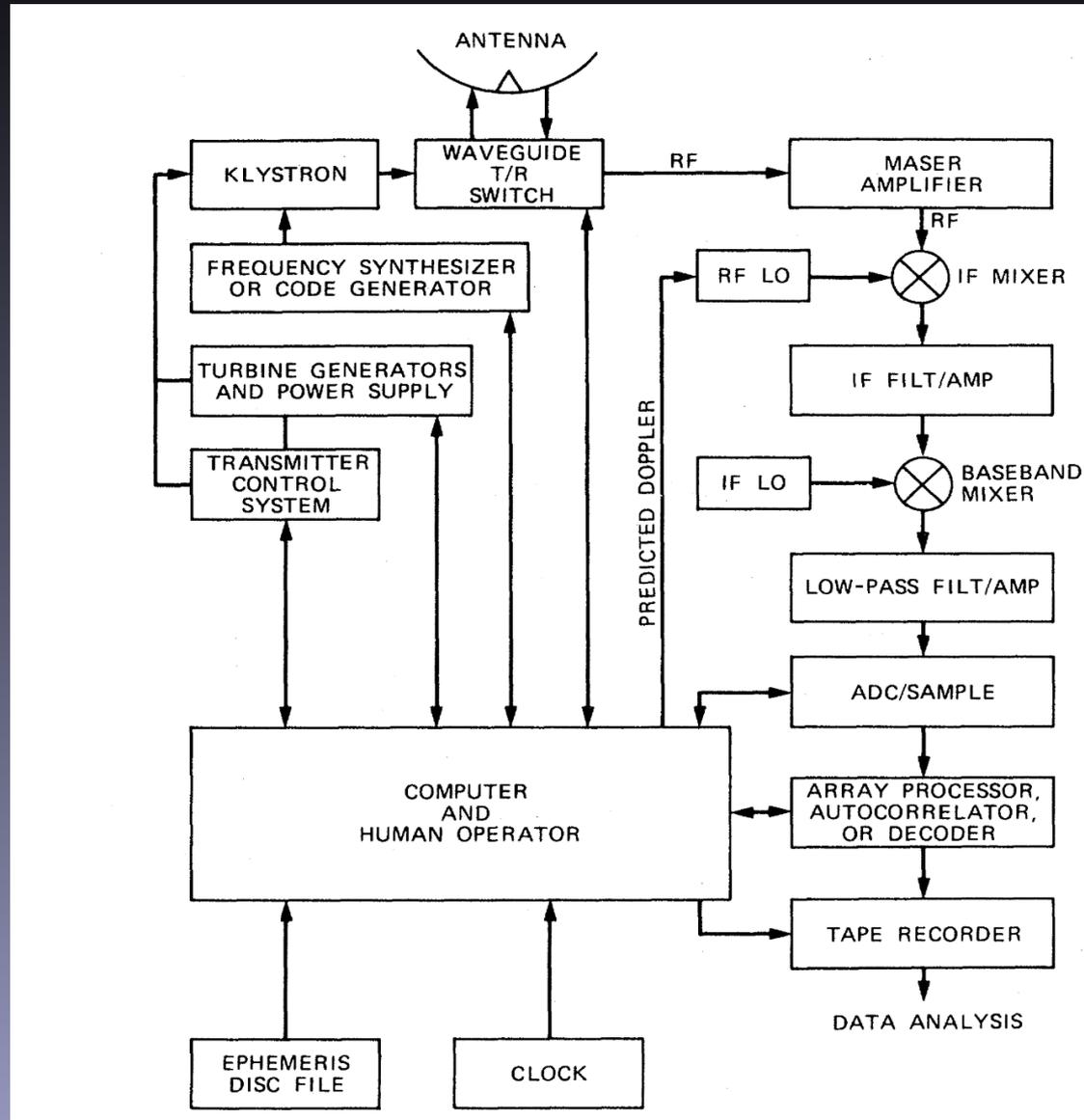
- Declination range: $-1-38$
(32% of the whole sky)
- 305 m antenna
- Transmitter frequency:
2380 MHz (12.6 cm)
- Power up to 1 MW
- ~ 100 objects/year
attempted, ~ 80 detected

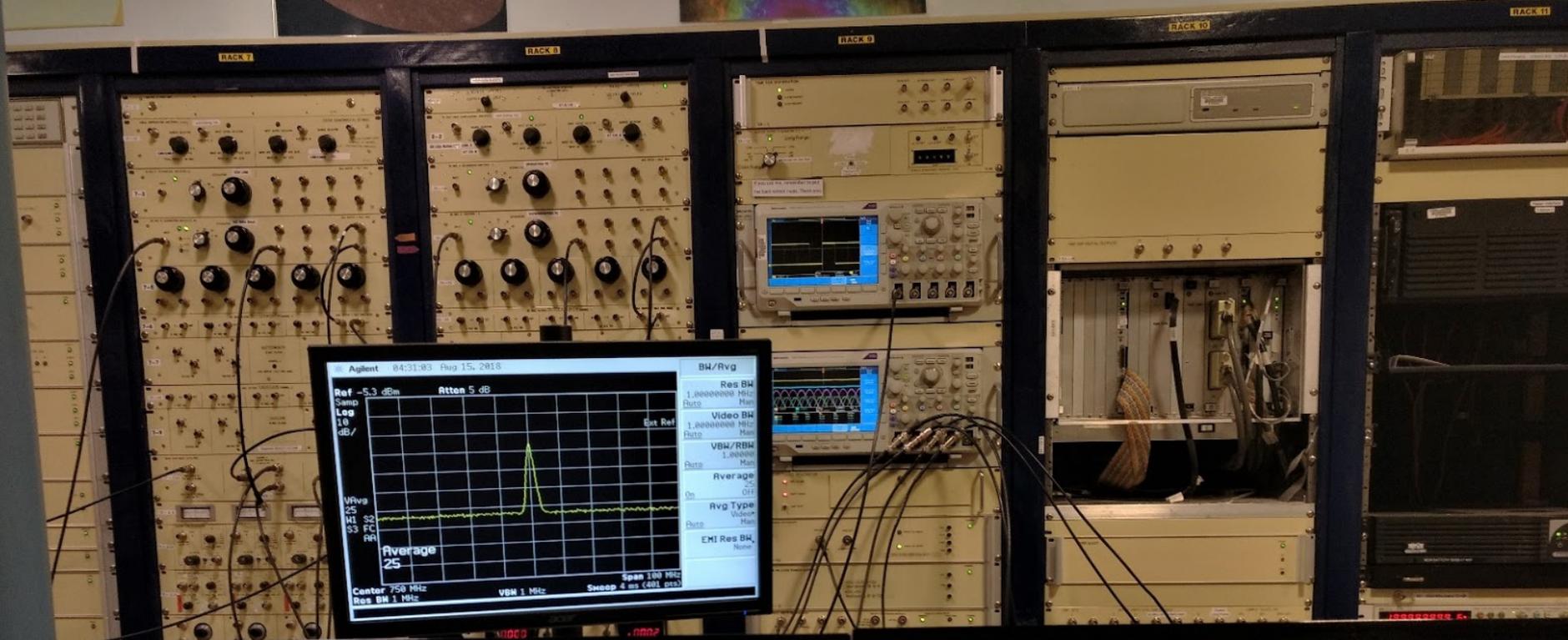


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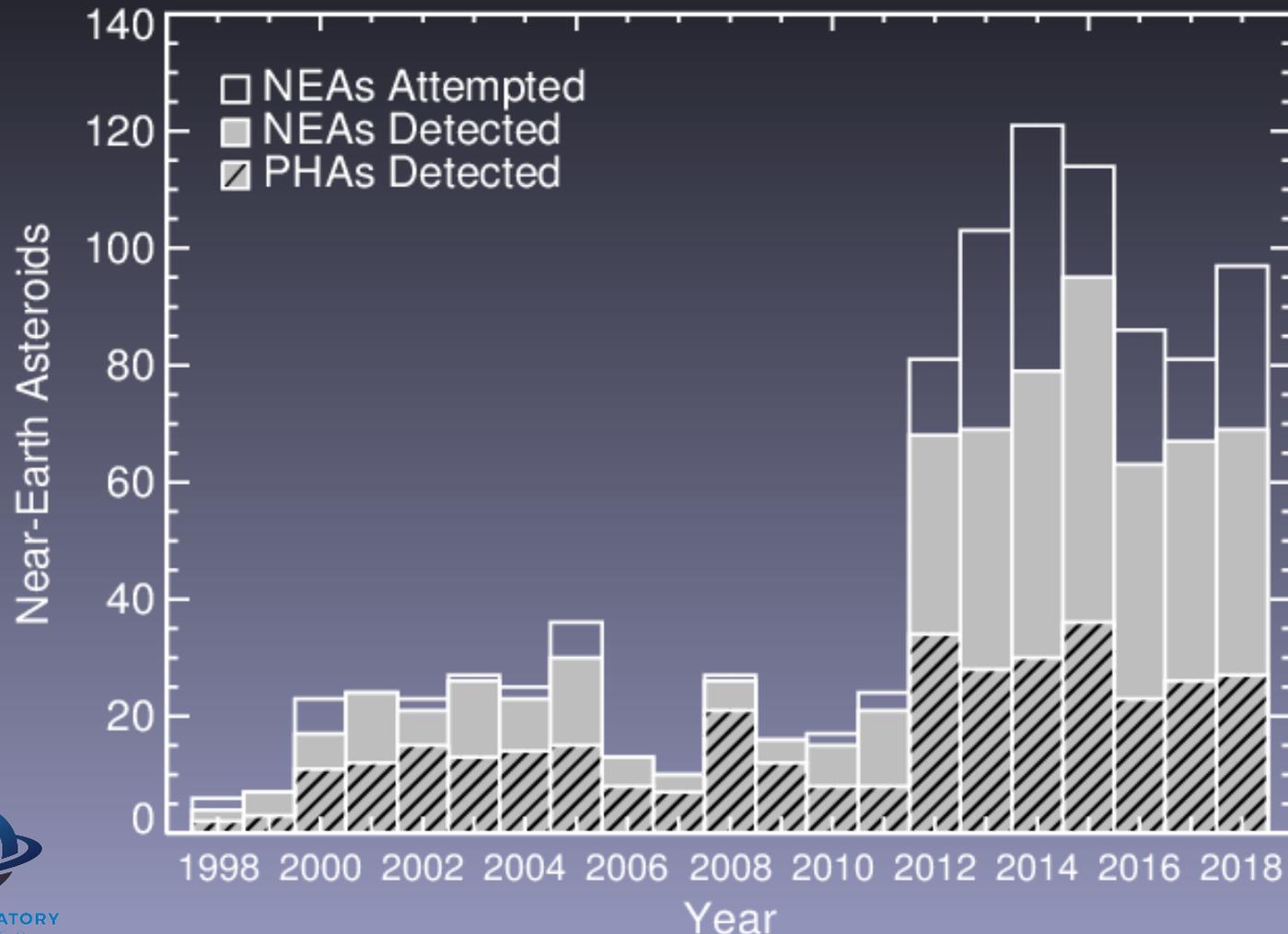
Planetary Radar: Arecibo





Courtesy Flaviane Venditti (AO/UCF)

Arecibo Observatory detects and characterizes ~ 100 near-Earth objects (NEOs) per year



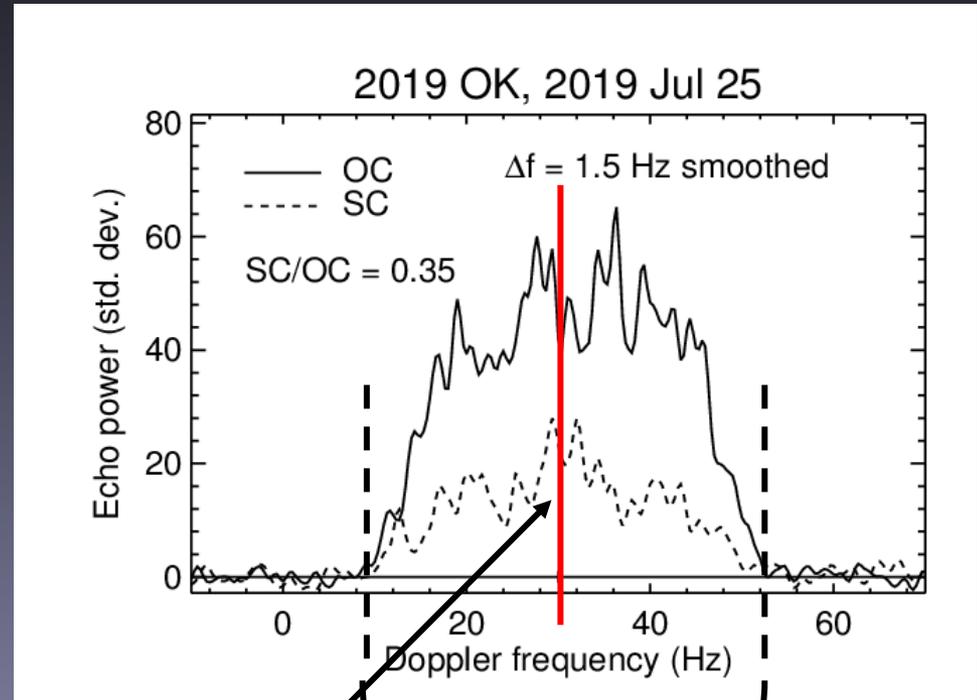
For every detection we learn:

- **Astrometry:** ~ 30 Hz offset in line-of-sight velocity of target

- **Rotation rate:** estimate from bandwidth and size

$$B = \frac{4\pi D \cos\phi}{\lambda_0 P_{spin}}$$

- **CPR:** related to surface roughness and composition



Ephemeris
offset

Bandwidth



Delay-Doppler Imaging



Time Delay: Distance

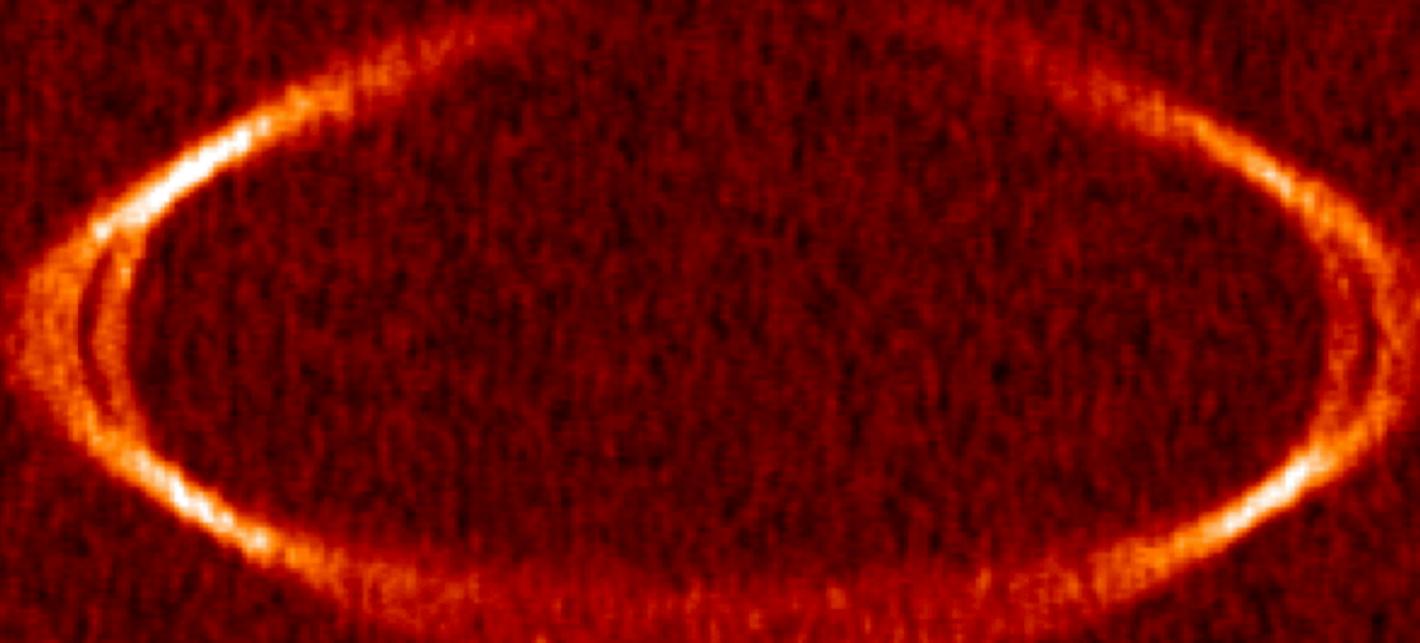
- Vertical axis
- Increasing downward
- Points at the top are closest to the observer

Doppler Frequency: Velocity

- Horizontal axis
- Increasing to the right
- Points on the right are approaching the observer

- Splitting signal into discrete range & frequency bins
- Requires high SNR

What Solar System Body is This?



S-band radar image, Oct 1999

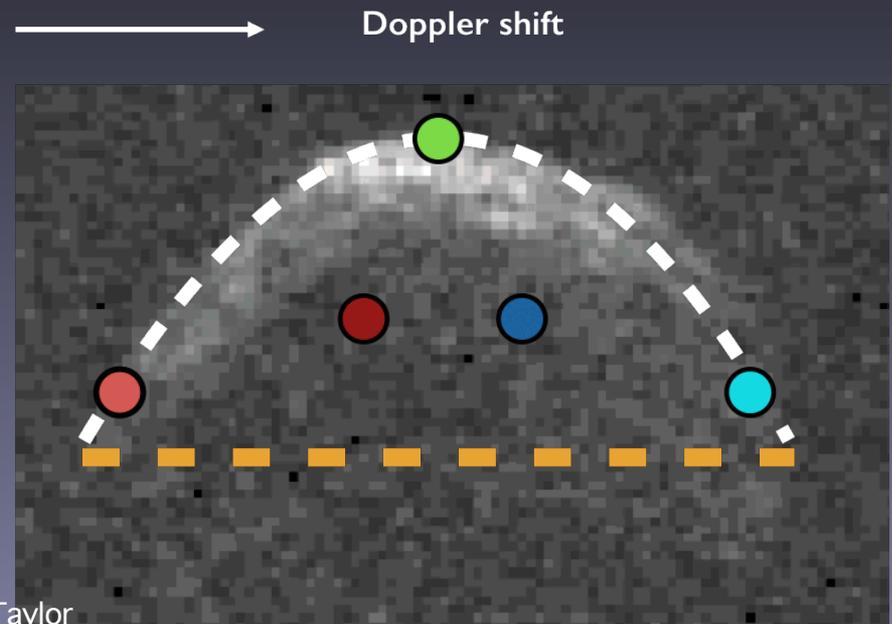
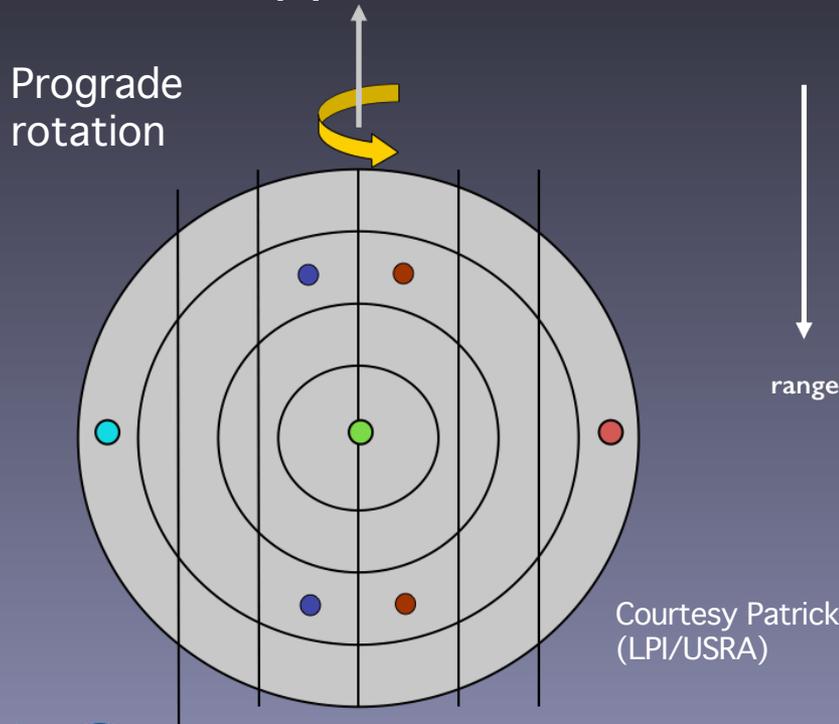
The peculiarities of radar imaging!
What two things are strange about this image?

3D – 2D ambiguity

Circles: points at the same distance (range) from observer

Vertical Lines: points of constant Doppler shift

Blue dots are blue shifted, red dots are red-shifted, green dots are not Doppler shifted



Courtesy Patrick Taylor (LPI/USRA)

The two blue and red dots map to the same point in a radar image (north/south ambiguity)



2017 YE5

- Equal mass binary
- 7.5 m/pixel
- 20-24 hr period
- Albedo difference between bodies

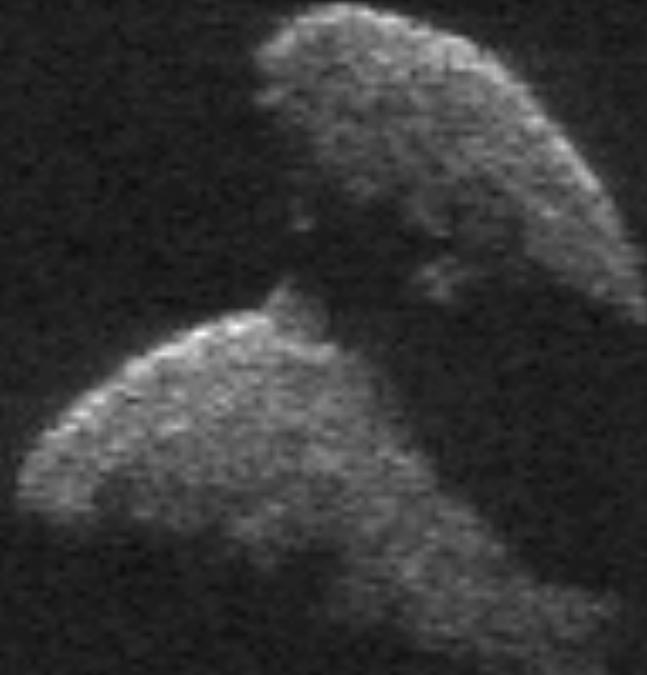
Bistatic
Observation
between AO
and GBT!



2014 JO25

- PHA
- Contact binary
- 7.5 m/pixel
- ~ 870 m
- 4.5 hr rotation period

Arecibo Observatory/NASA/NSF



2014 JO25

19 Apr 2017



Arecibo Observatory/NASA/NSF



Arecibo Observatory/NASA/NSF

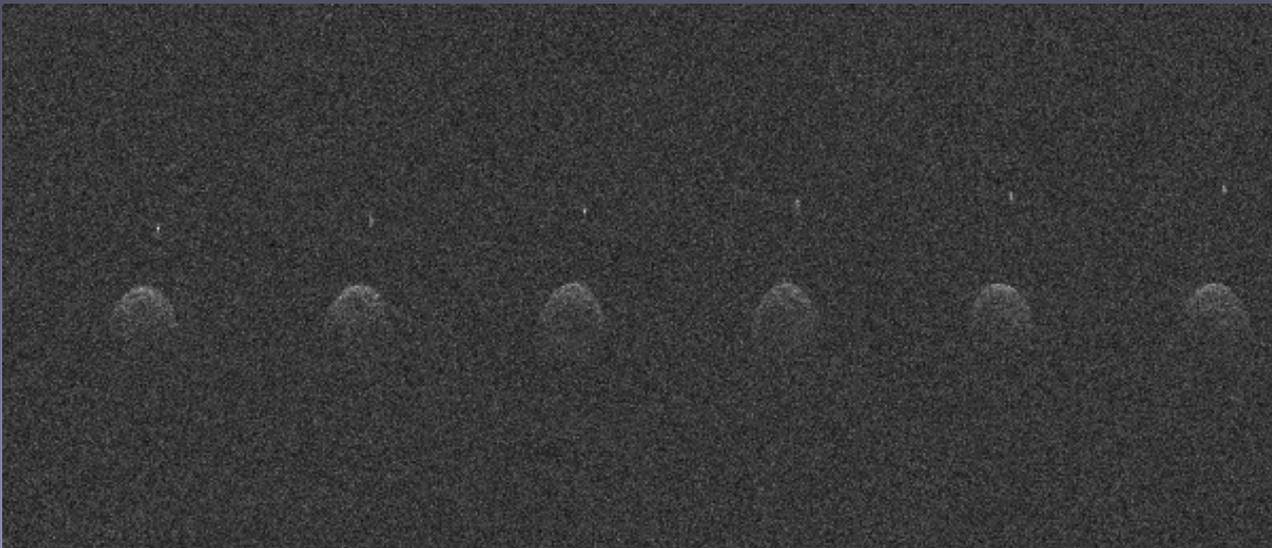


3200 Phaethon

- 2nd largest PHA known
- 75 m/pixel
- ~ 6 km
- 3.6 hr rotation period
- Surface features visible (crater or boulder?)
- Target of JAXA's
Destiny+ mission set to launch 2022

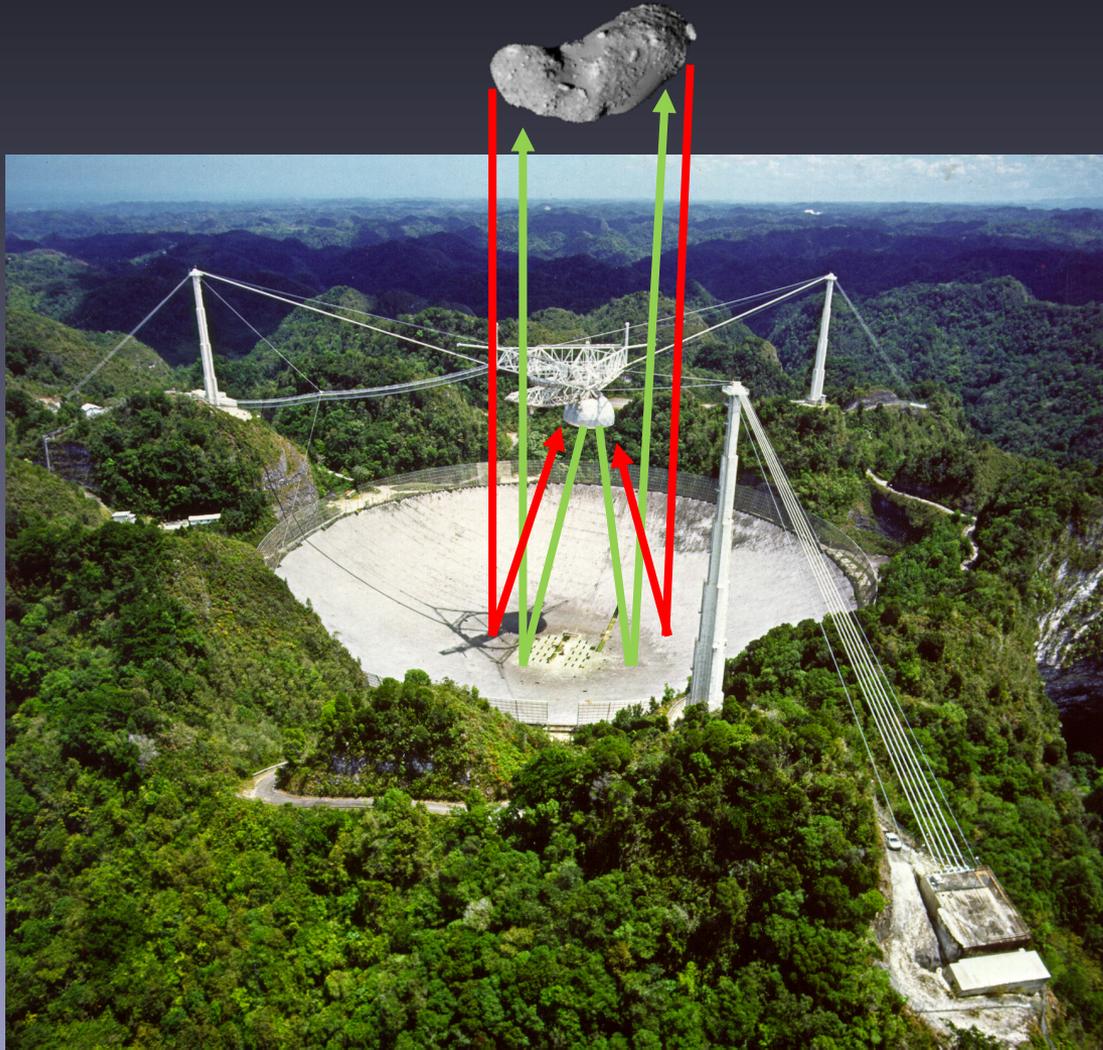
Didymos

- PHA
- Binary system
- 7.5 m/pixel (2 spb)
- ~ 760 m
- 2.3 hr rotation period
- Target of NASA's DART mission
- Arecibo to play important role



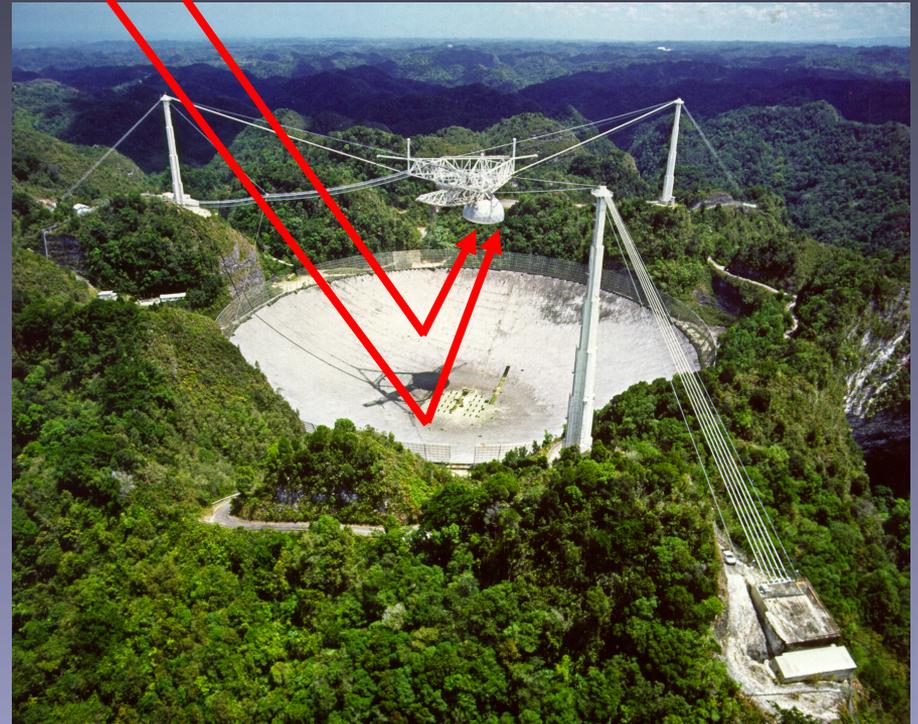
Monostatic vs. Bistatic

- Transmitter and receiver are at the same location



Monostatic vs. **Bistatic**

- **Transmitter and receiver offset from one another**
- Can utilize complementary aspects of different systems
- Close targets
- Speckle Interferometry



Monostatic vs. **Bistatic**

- **Transmitter and receiver offset from one another**
- Can utilize complementary aspects of different systems
- Close targets
- Speckle Interferometry

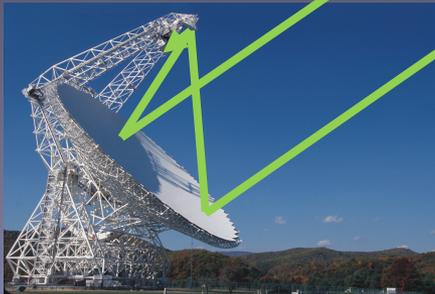
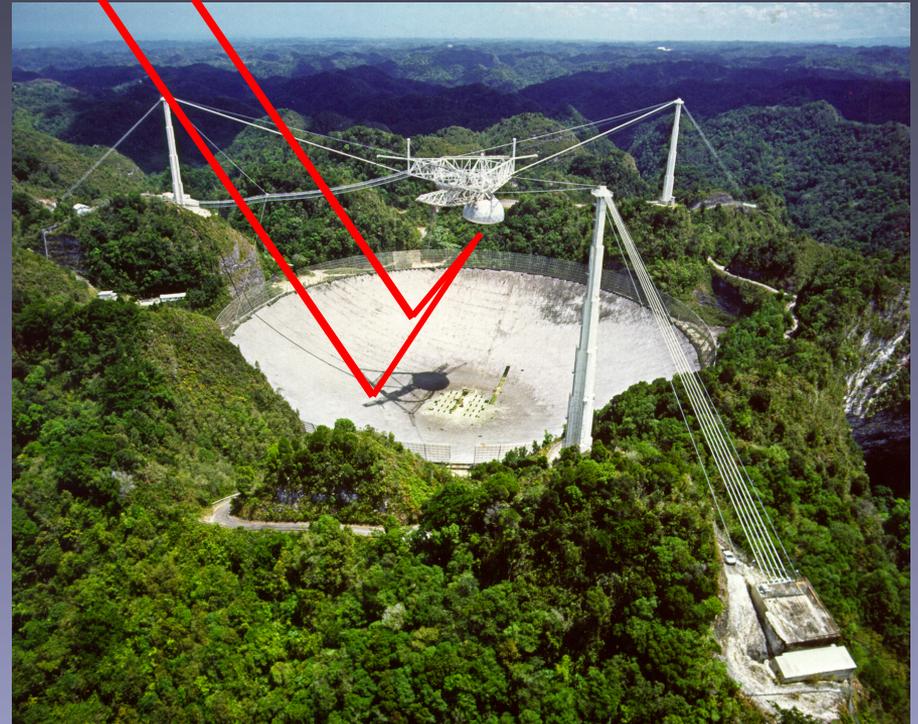


Image credit: NRAO/GBO



Science Return

- Refine orbits:
 - reduce uncertainty in orbital parameters by five orders of magnitude for newly discovered objects

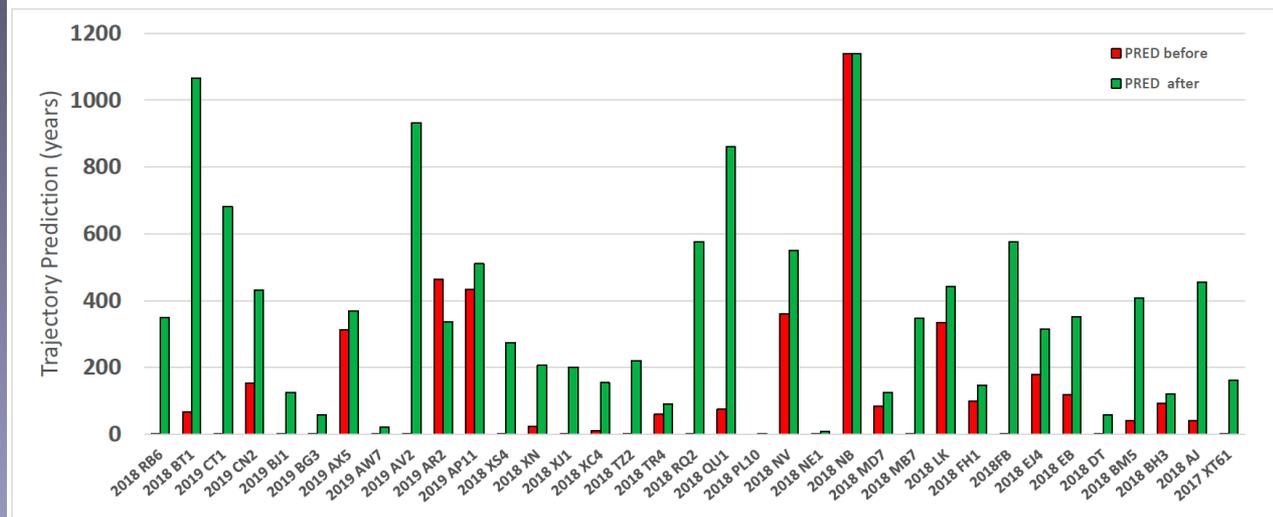
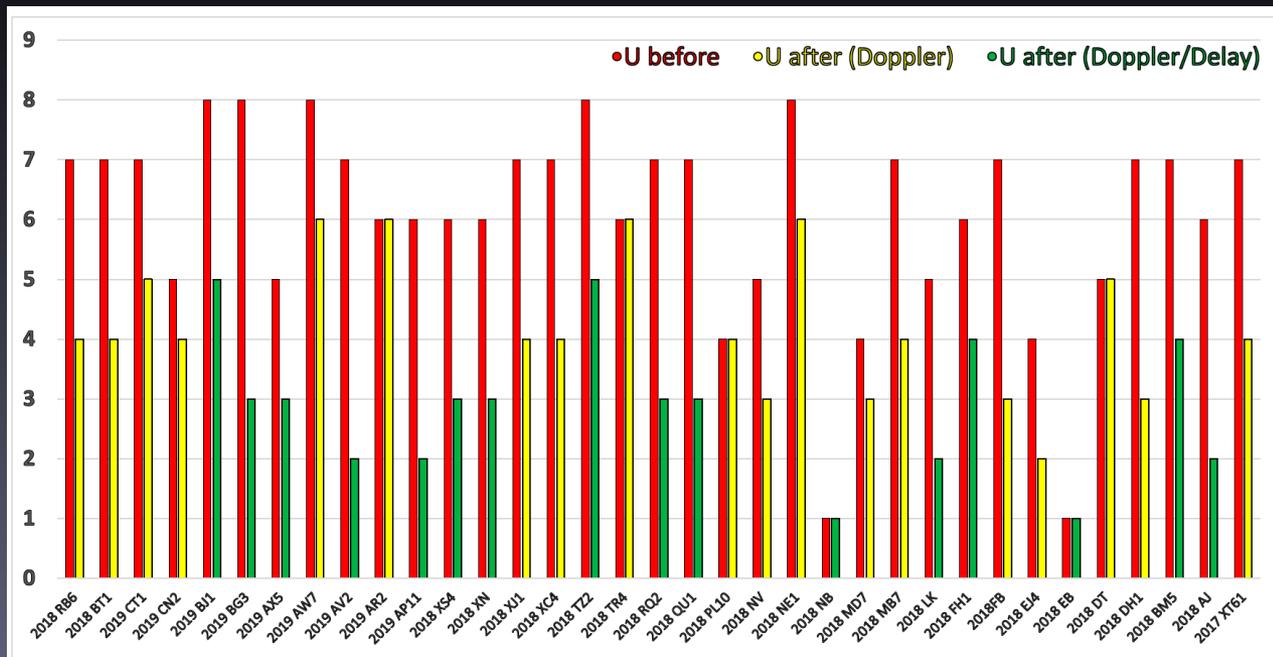


Image Credit: Flavianne Venditti (AO, UCF)



Science Return

- Size and shape:
delay-Doppler
images can
produce images
comparable to
spacecraft
encounters



4719 Toutatis

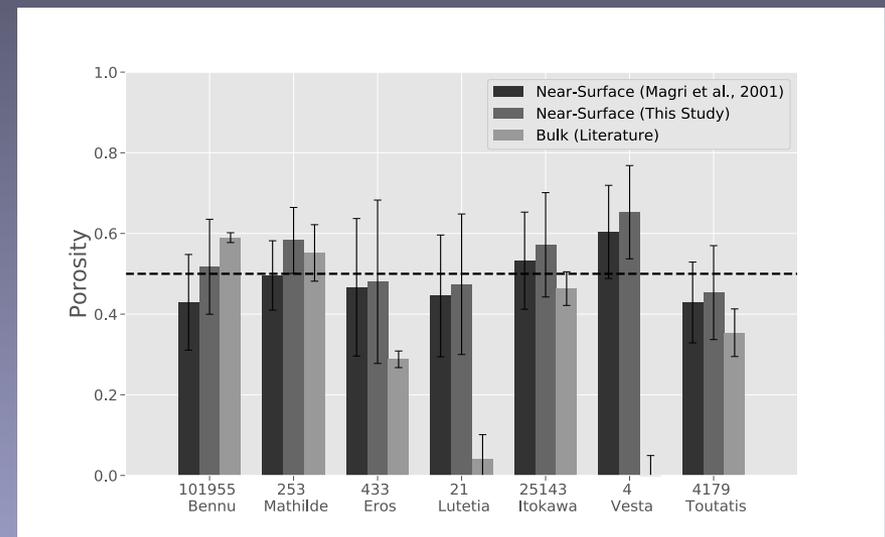
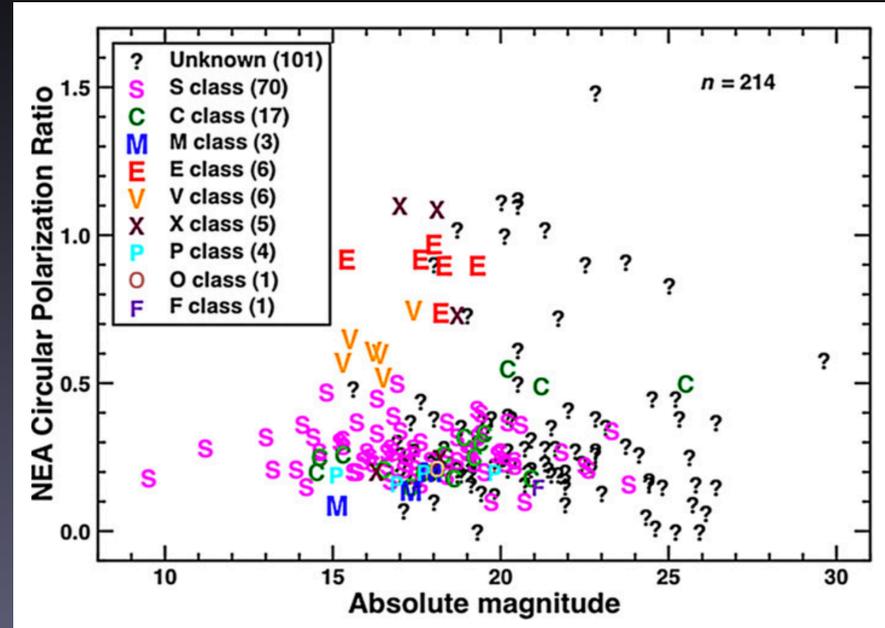
Radar shape model

Chang'e spacecraft image
taken during flyby



Science Return

- **Surface characterization:**
 - Comparison of polarimetric properties shows correlation among taxonomic types, i.e. Benner et al. (2008)
 - Comparison with laboratory experiments constrain surface structure, i.e. Hickson et al. (2019)



Science Return

- Solar system processes:
 - Asteroids are primitive objects that reflect the conditions of the early solar system
 - Evolutional history of asteroids sheds light on the evolution of different regions of the solar system.

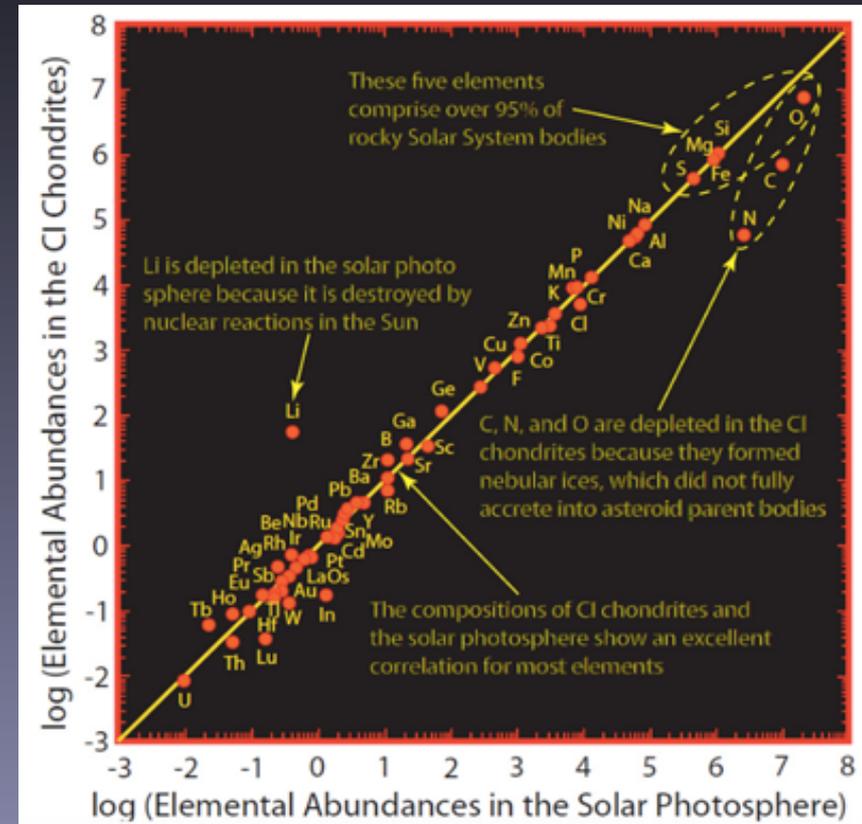


Image credit: PLANETSC 9603 Module 6 Planetary Materials Lecture, Audrey Bouvier (UWO)



Comet 103P/Hartley 2 imaged by
Deep Impact (EPOXI) in 2010

- Solar system processes:
 - Asteroids vs comets? Origins of water and organics in solar system?

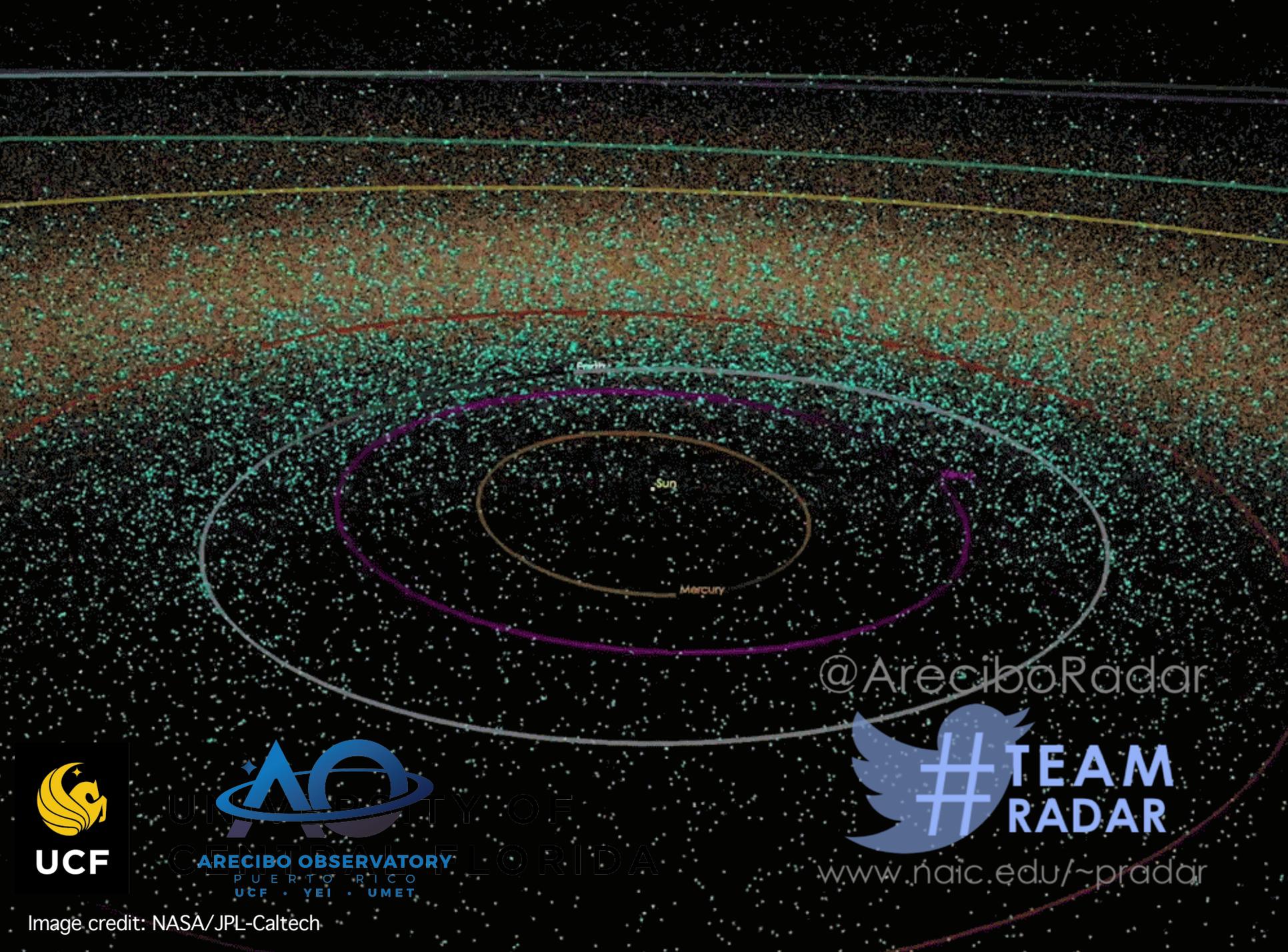


Image credit: (Top)
NASA/JPL/CalTech/UMD (Bottom)
NASA/Goddard/University of
Arizona/Lockheed Martin

101955 Bennu imaged
by OSIRIS-Rex in 2019



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Earth

Sun

Mercury

@AreciboRadar



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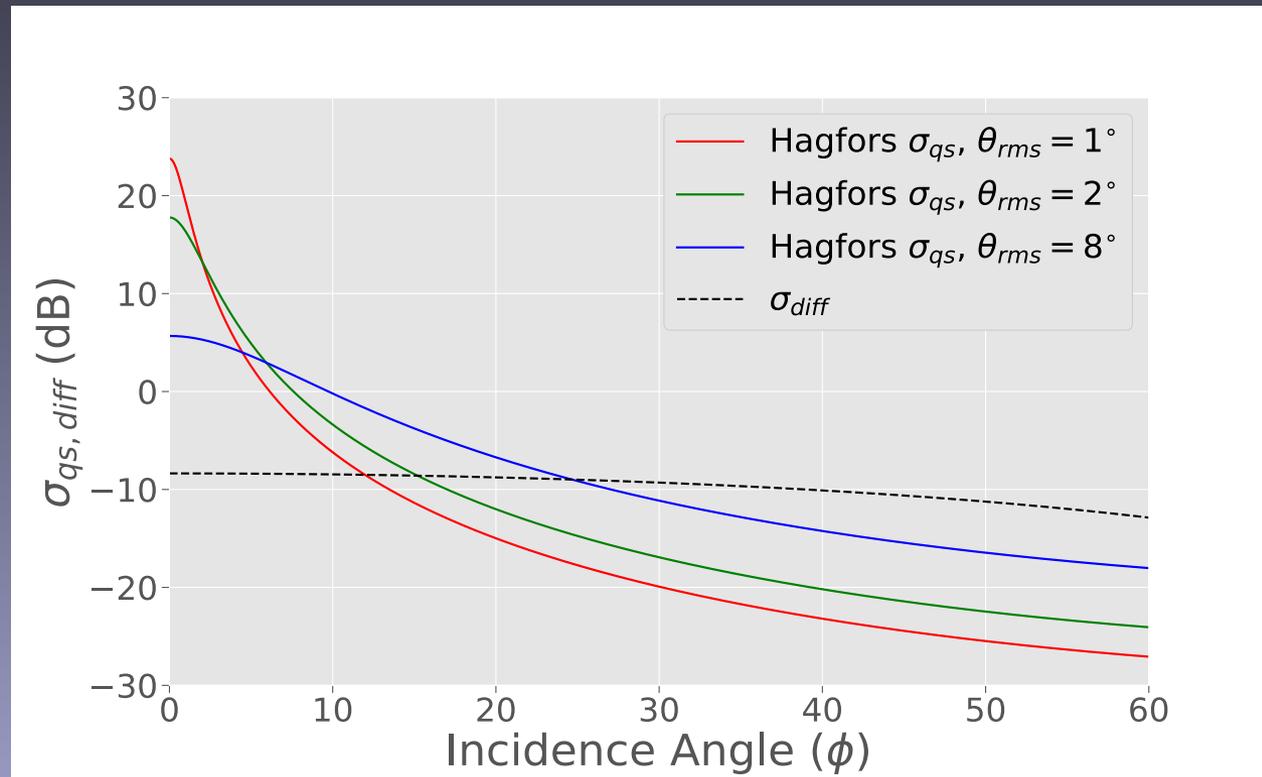
Image credit: NASA/JPL-Caltech

Backup Slides



Radar Scattering Laws

- Describe the radar cross section of a target as a function of incidence angle, ϕ , surface roughness, C , and empirical parameters
- Hagfor's Law:
 - $\sigma_{qs}(\phi) = \left(\frac{RC}{2}\right) (\cos^4 \phi + C \sin^2 \phi)^{-3/2}$
- Cosine Law:
 - $\sigma_{diff} = R \cos^n(\phi)$



Surface and Subsurface Scattering Scenarios

Smooth surfaces

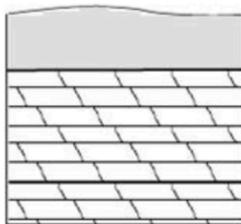
$$(\sigma_d \rightarrow 0)$$

(a)



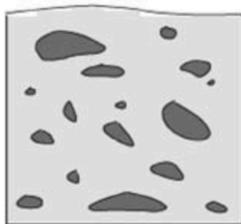
low μ_c ; low m_l
no subsurface scattering

(b)



low μ_c ; high m_l
Quasi-specular scattering from subsurface gives high m_l

(c)

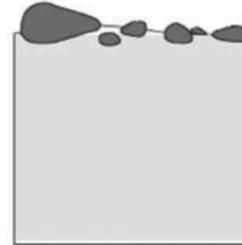


mod.-high μ_c ;
mod.-high m_l
Diffuse subsurface scattering generates lower m_l than case b

Rough surfaces

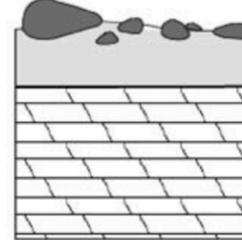
$$(\sigma_{qs} \rightarrow 0)$$

(d)



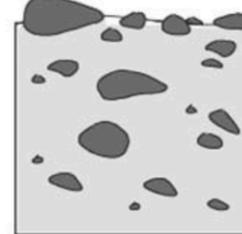
high μ_c ; low m_l
no subsurface scattering

(e)



high μ_c ; low-mod. m_l
Radar wave may not penetrate into rough surface.

(f)



high μ_c ; low-mod. m_l
Radar wave may not penetrate into rough surface.



