

NATIONAL RADIO ASTRONOMY OBSERVATORY  
GREEN BANK, WEST VIRGINIA

ELECTRONICS DIVISION INTERNAL REPORT No. 198

300-FOOT INDUCTOSYN READOUT SYSTEM

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MAY 1979

NUMBER OF COPIES: 150

## 300-FOOT INDUCTOSYN READOUT SYSTEM

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### 1. Introduction

This report describes the electronics necessary to derive a binary number using the inductosyn readout system, present this data to the H316 computer, and provide a coarse readout independent of the computer.

### 2. Programming

- OCP 550 This is a system reset; output this command at initialization and periodically while the program is running. The program should wait 300 ms after this command is executed, before trying to read the inductosyn.
- OCP 450 This command holds the inductosyn reading for 2 ms while the computer inputs the data.
- INA 1450 Execute this command to input the inductosyn data. Two data words are required as shown below.

Bit ..	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Word 1	0	2 <sup>3</sup>	2 <sup>2</sup>	2 <sup>1</sup>	2 <sup>0</sup>	0	0	0	0	0	0	0	0	0	0	0
Word 2	2 <sup>19</sup>	2 <sup>18</sup>	2 <sup>17</sup>	2 <sup>16</sup>	2 <sup>15</sup>	2 <sup>14</sup>	2 <sup>13</sup>	2 <sup>12</sup>	2 <sup>11</sup>	2 <sup>10</sup>	2 <sup>9</sup>	2 <sup>8</sup>	2 <sup>7</sup>	2 <sup>6</sup>	2 <sup>5</sup>	2 <sup>4</sup>

This count is 0 to 3777777<sub>8</sub> for 360° rotation.

### 3. Inductosyn

"Inductosyn" is a registered trademark of Inductosyn Corporation for "electrical measurement apparatus". The inductosyn was developed by Mr. C. L. Farrand, Sr., President of Farrand Controls, Inc.

Inductosyn's were first used at NRAO on the 140-ft telescope. Later we used inductosyns on the 45-ft telescope. Impressed by their reliability it was decided to buy an inductosyn for the 300-ft to replace the present optical encoders.

The inductosyn at the 300-ft is different in that the only parts of the inductosyn that we purchased from Farrand were the rotor and stator. The rest of the housing was designed and built by NRAO.

An inductosyn consists of two parts: inductosyn for a fine readout and a resolver for a coarse readout. The fine and coarse reading is combined in the electronics.

#### 4. Resolver to Digital Conversion

Three cards of logic are necessary to derive a coarse and fine binary number using the inductosyn and associated resolver. These three cards were designed by Ron Weimer and are identical to the ones used on the 45-ft telescope. Two of these cards are the same except for some jumper plugs. These plugs should remain with the card slot. These two cards will be referred to as digital cards.

The two digital cards are located in slots 8 and 10. Slot 10 contains the card used by the inductosyn and the other card is used by the resolver. The two jumper plugs select frequency of operation and phasing. The phasing should be adjusted so that with the inductosyn or resolver in "open loop" the error signal should be in phase with the reference. Four test points are provided on the analog card for this adjustment. This adjustment should only be necessary when changing inductosyns.

The other card in this group is referred to as the analog card and is located in slot 9. Both resolver and inductosyn use this card.

The operation of the resolver to digital conversion is quite complicated and I will not attempt to explain it in this report. A brief explanation can be found in EDIR #149, page 8.

#### 5. 300-ft Inductosyn Card

This card (built on a Shalloway card) combines the coarse and fine binary numbers from the resolver to digital converters to form a 20-bit binary number. This number can be indexed for the proper position, then fed to the computer. This card also contains the logic to generate a coarse local readout independent of the computer.

The logic that combines the coarse and fine counts involves the use of adders located in chip locations 11F, 11E, 10E, 9B and 9A. The dip switch in 11C positions 6, 7, and 8 are used to adjust the "crossover" between the coarse and fine count. This adjustment is made by setting the display select switch to separate. The dip switches should be adjusted such that the two middle digits in the display have a difference of four.

Indexing is accomplished by the adders in chip locations 10A, 10B, 10C, 10D and 11D. the dip switches in chip locations 11A, 11B and switches 1, 2, 3, and 4 in 11C are opened or closed to obtain the proper position readout as displayed by the computer.

The logic on pages 2 and 3 of the "300-ft inductosyn card" is used for the readout on the front panel. This logic enables the selection of three possible displays. The three displays that can be selected are separate, combined and indexed. Separate is a display of coarse and fine independent of each other. Combined is a display of fine and coarse added together. Indexed is a display of the combined number with an index number added to it.

## 5. 300-ft Inductosyn Card (continued):

Pages 4 and 5 contain the logic necessary to convert the indexed number to degrees and tenths of degrees in BCD. The logic function on page 4 is to generate two clocks. The binary clock is generated by dividing a 2 MHz clock by  $225_{10}$ , and the BCD clock is generated by dividing by  $256_{10}$ . These two clocks perform the binary to degree conversion by counting down the binary number while a BCD counter is incrementing. This counting process continues until the binary counter reaches zero. These counters and a latch for the BCD number are located on page 5. Some short time after the binary counter goes to zero a new number will be loaded in the binary counter, and the process starts over. Conversion time depends on the magnitudes of the binary number.

## 6. Console Display Switch

When this system was originally designed it was planned to have two systems, such as we had with the encoders. After installation of the first system it was decided that only one system with a spare inductosyn was all that was necessary. This card therefore has some unnecessary logic.

This card contains four single-pole double-throw switches whose function was to switch between two inductosyn systems; this function is now not necessary.

The logic that is necessary are the markers. A latch was provided for the markers to help reduce the chatter of the dip relays when the position is on a transition point. Two markers are available -- one every even tenth of degree and one every ten degrees.

## 7. Balancing the Inductosyn

For optimum performance the drive to the inductosyn and resolver windings must be balanced.

The balancing of the resolver is more straightforward so I will attempt to explain it first. The telescope will have to be moved  $45^\circ$  to balance the resolver, so this should be kept in mind when positioning the telescope as the following describes. First the display select switch must be set to separate. The four digits to the left of the display are the coarse numbers. Position the telescope such that you are on a transition edge of one of the following in the coarse display:

3777-0000

777-1000

1777-2000

2777-3000

When one of these points has been reached, record the fine reading (4 digits to the right). The telescope must now be moved 32 cycles of fine (go through the fine number that was recorded 32 times). Stop on the same fine number the 32<sup>nd</sup> time. The coarse number should be 400 octal counts from the transition edge selected above. For

example, if the point chosen was 3777-0000 after 32 cycles of fine, it could be reading 377-400 or 3377-3400, depending on which direction the telescope was moved. The resolver adjustment should be adjusted for this number.

The coarse balance of the inductosyn (fine readout system) should be performed when changing inductosyn packages. The fine balance should be checked when changing inductosyn packages or the fine digital card (J10). The fine balance procedure should be attempted on a fairly calm day since wind can affect this procedure.

The coarse balance of the inductosyn requires the use of a digital ohm meter. This meter should be used to read resistance between pins in slot 10 (card removed) as shown below:

J10-3	to	J10-4	Fixed resistance.
J10-5	to	J10-6	Adjust resistance equal to the resistance measured from J10-3 to J10-4.

The fine balance of the inductosyn (fine readout) will require the use of a chart recorder with the capability to "buck off" 10 V DC. The chart recorder should be connected to the output of the variable speed drive D/A converter. The telescope will have to be doing wobbles at a high rate (we used 130 min/min). The gain of the chart recorder should be such that the AC error component can be displayed. The chart recording should be examined for a periodicity to fit the formula:

$$\frac{42}{\text{wobble rate (min/min)}} = \text{time between peaks in min.}$$

If this period is evident, the balance will have to be adjusted slightly. Observe the chart record carefully for changes of phase, using the direction change edge as a reference point. If this periodicity is still evident, but the phase has changed, the balance point was passed. This adjustment will probably require making a slight adjustment, then observing several wobble cycles. When it is balanced, the AC error component will still be evident but it will not have a periodicity. This error is affected by wind and telescope balance.

## 8. Credits

Credit should be given to the following people:

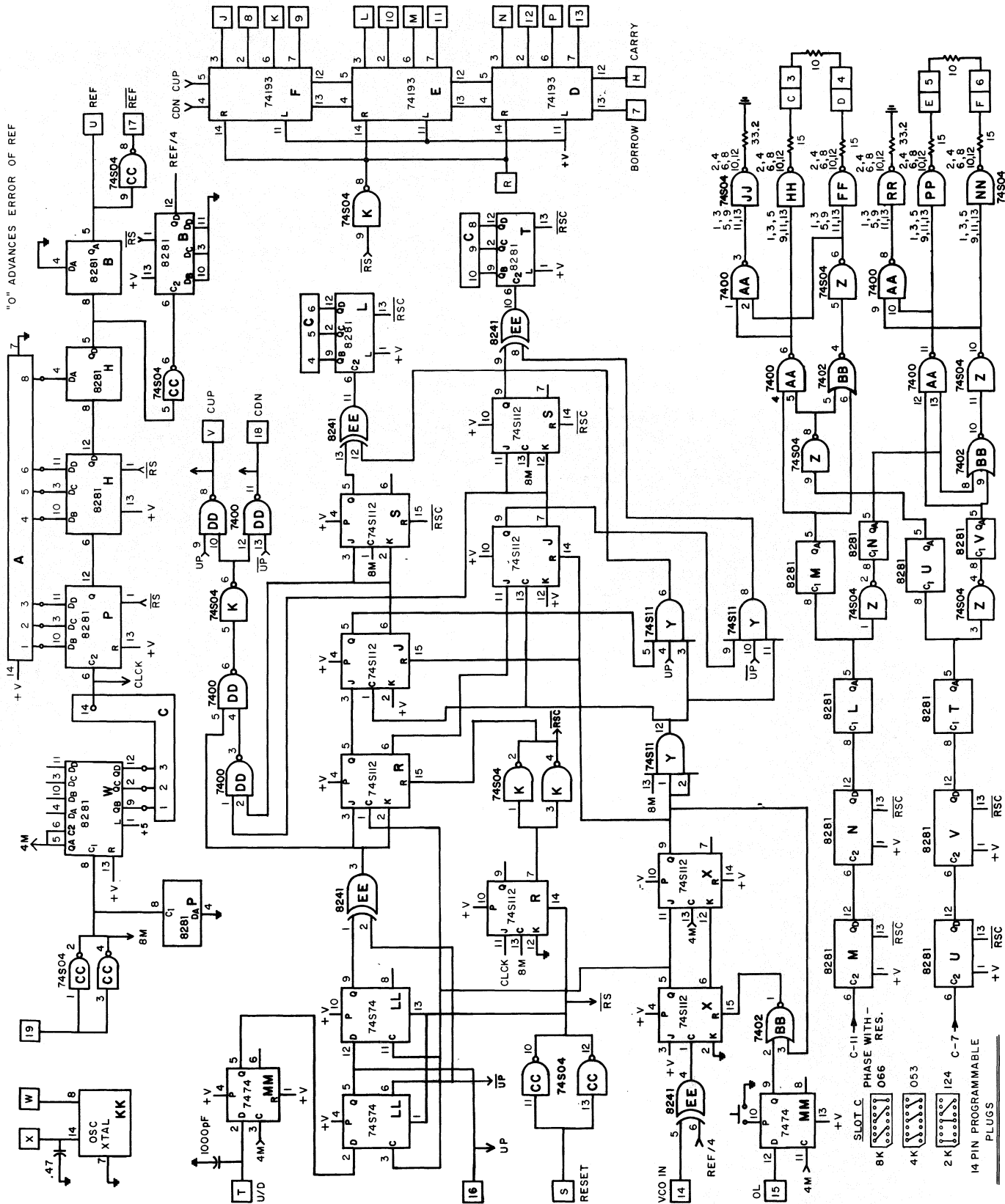
Ron Weimer for the design of the resolver to digital converter cards and the balancing procedure.

Engineering for the design of all the hardware for the inductosyn housing and mounting the inductosyn to the telescope.

Machine Shop for all the precision machine work necessary for the inductosyn.

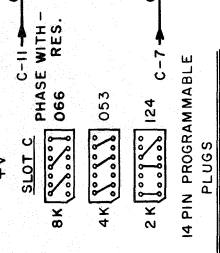
Jerry Turner for wiring the digital chassis for this project.

"0" ADVANCES ERROR OF REF

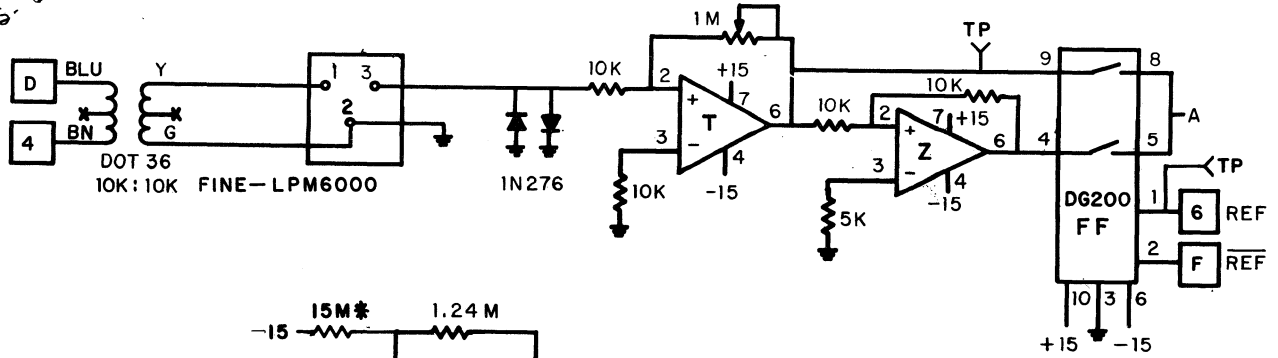


POSITION READOUT, RESOLVER TO DIGITAL CONVERTER  
DIGITAL COUNTER / DRIVER CIRCUITS

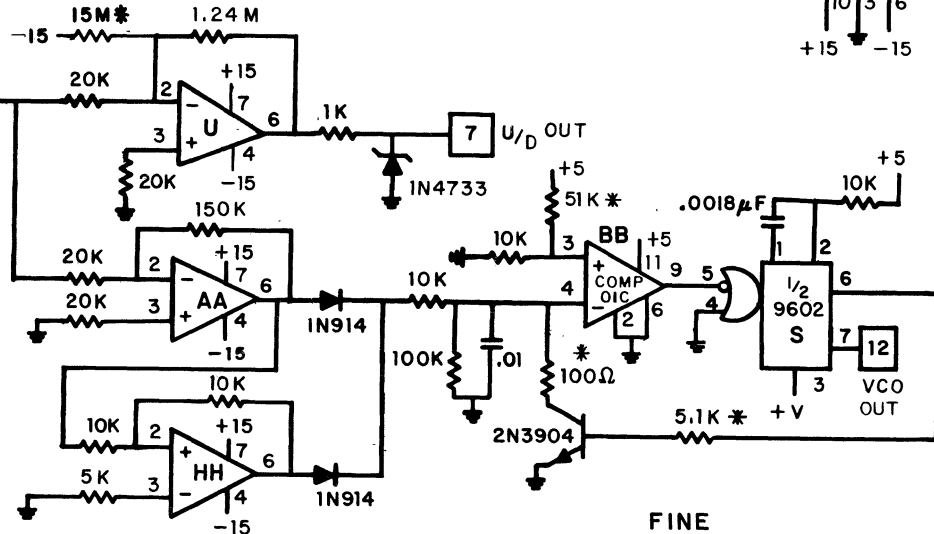
COURSE — SLOT 8  
FINE — SLOT 10



PI 60  
5'

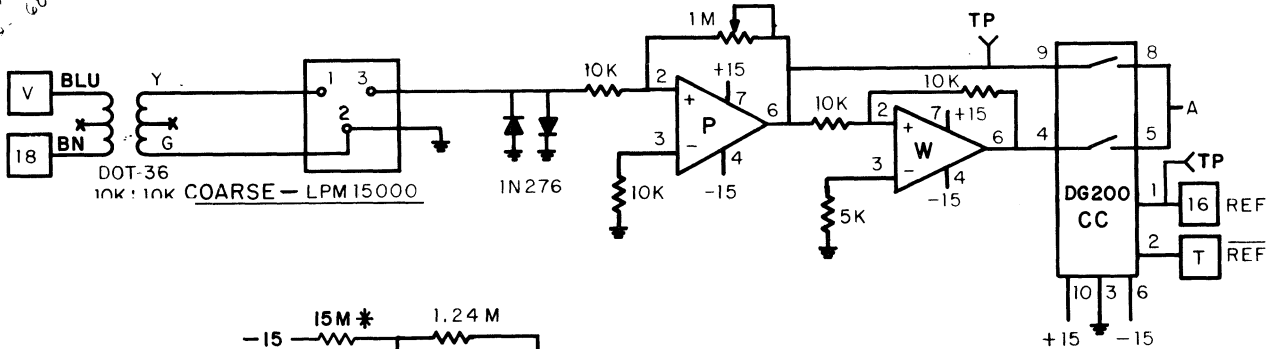


X-20 = +15  
Y-21 = -15  
B-2 = +5  
A-1, Z-22 = GND  
RESISTORS = 1%, \* = 5%  
OP AMPS = 741

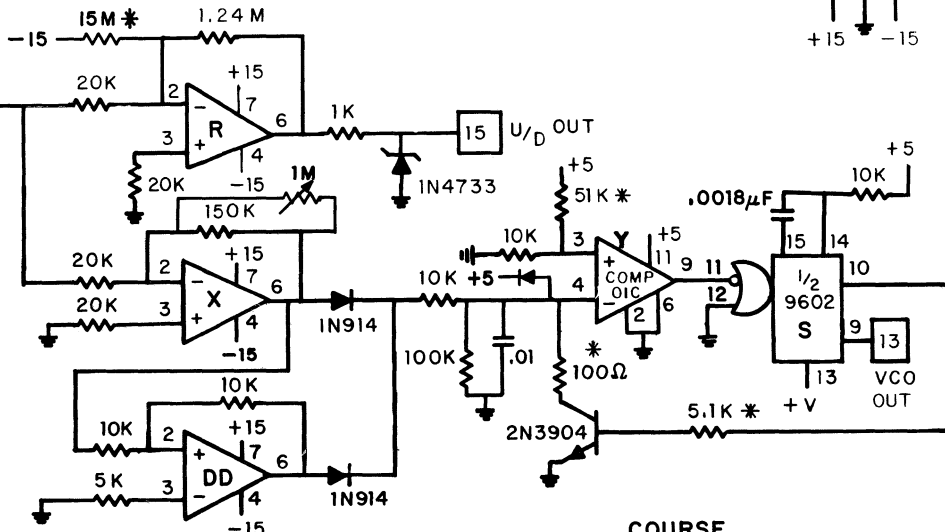


FINE

PI 60  
2'



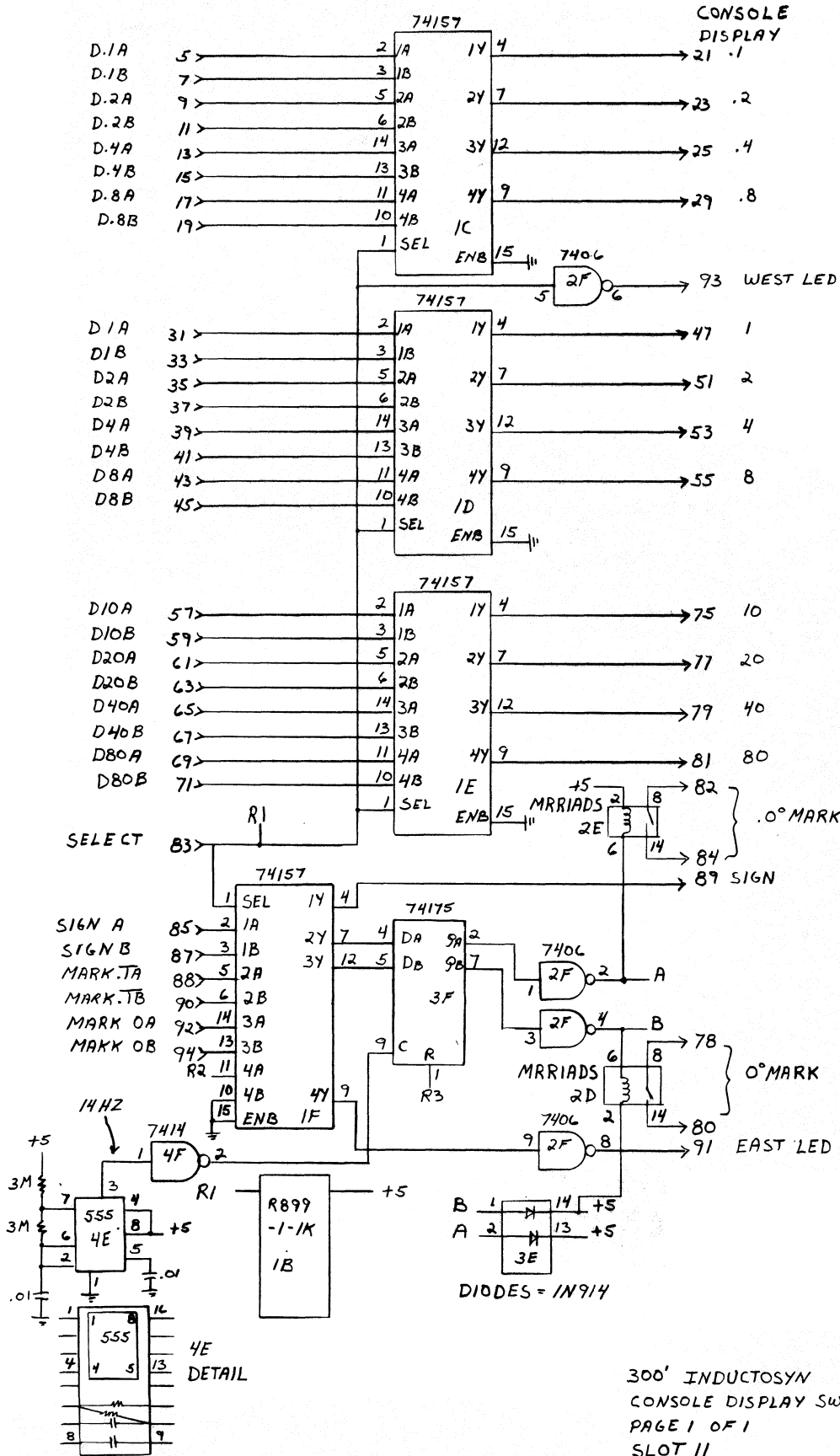
X-20 = +15  
Y-21 = -15  
B-2 = +5  
A-1, Z-22 = GND  
RESISTORS = 1%, \* = 5%  
OP AMPS = 741



COURSE

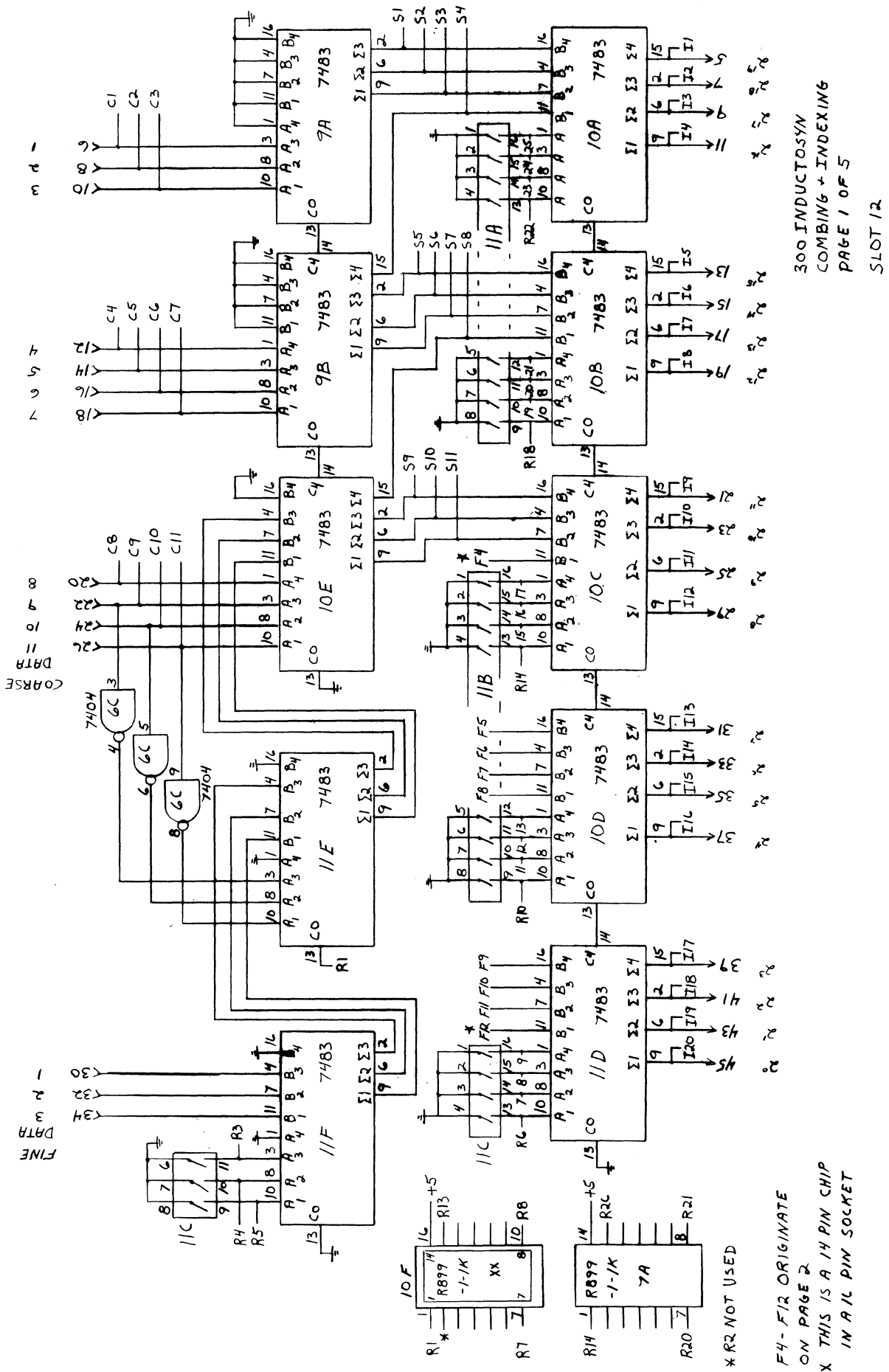
POSITION READOUT, RESOLVER TO DIGITAL COMPUTER  
ANALOG CIRCUITS / SYNC. DET. / ERROR AMP. / VCO SLOTT 9

74157  
SEL=0=A  
A=EAST IND



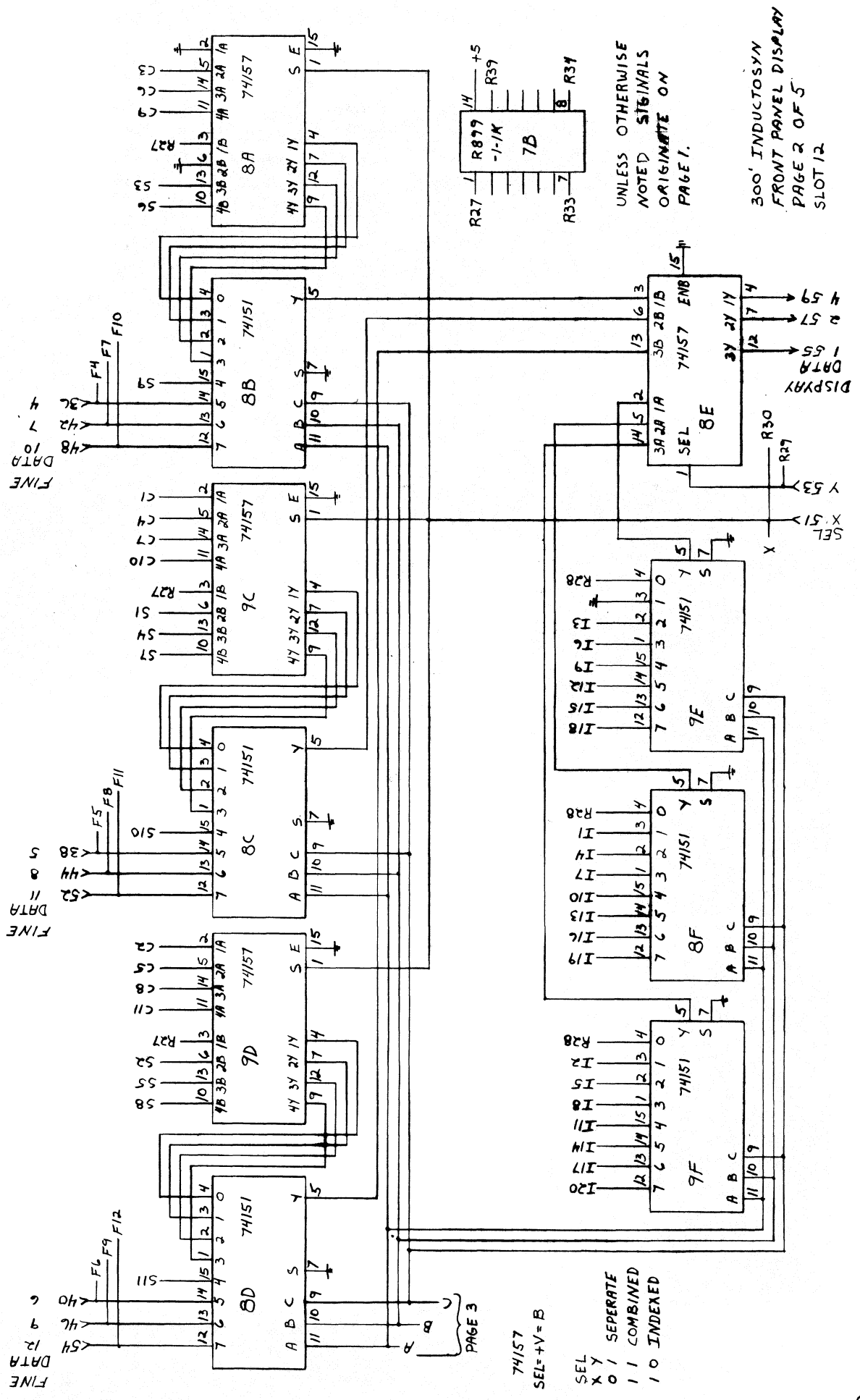
300' INDUCTOSYN  
CONSOLE DISPLAY SWITCH  
PAGE 1 OF 1  
SLOT 11





300 INDUCTOSYN  
 COMBINING + INDEXING  
 PAGE 1 OF 5  
 SLOT 12

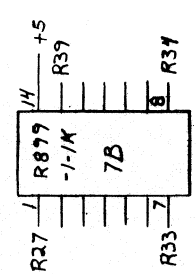
\* F4 - F12 ORIGINATE  
 ON PAGE 2  
 XX THIS IS A 14 PIN CHIP  
 IN A 16 PIN SOCKET



FINE DATA 12  
K54  
9  
K46  
6  
K40  
FL F9 F12  
S11

FINE DATA 11  
K52  
8  
K44  
5  
Y38  
F5 F8 F11  
S10

FINE DATA 10  
K48  
7  
K42  
4  
K36  
F4 F7 F10  
S9



UNLESS OTHERWISE NOTED SIGNALS ORIGINATE ON PAGE 1.

300' INDUCTOSYN  
FRONT PANEL DISPLAY  
PAGE 2 OF 5  
SLOT 12

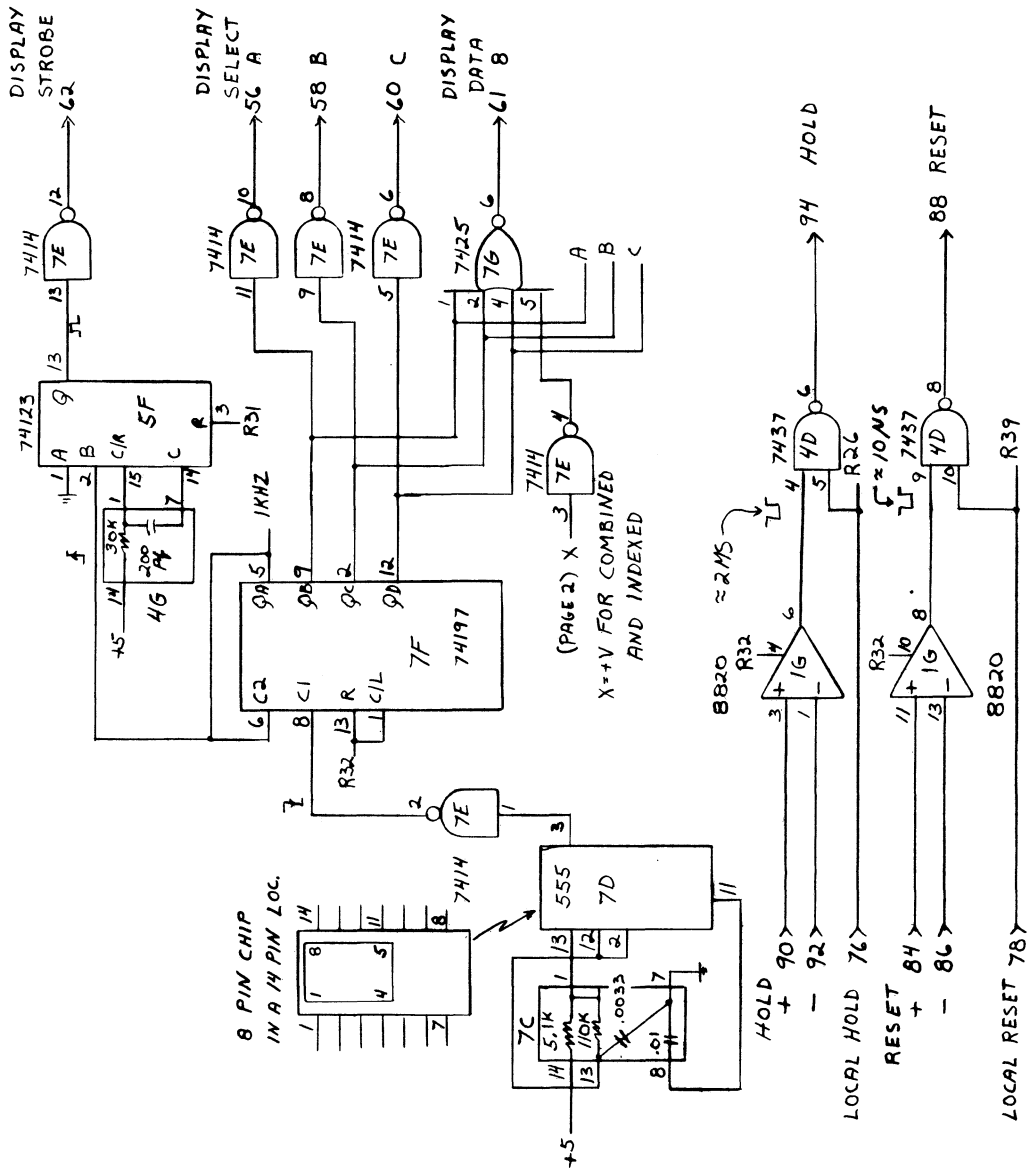
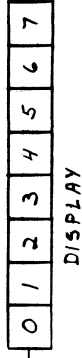
PAGE 3  
74157  
SEL=+V=B

SEL  
X Y SEPERATE  
O I COMBINED  
I O INDEXED

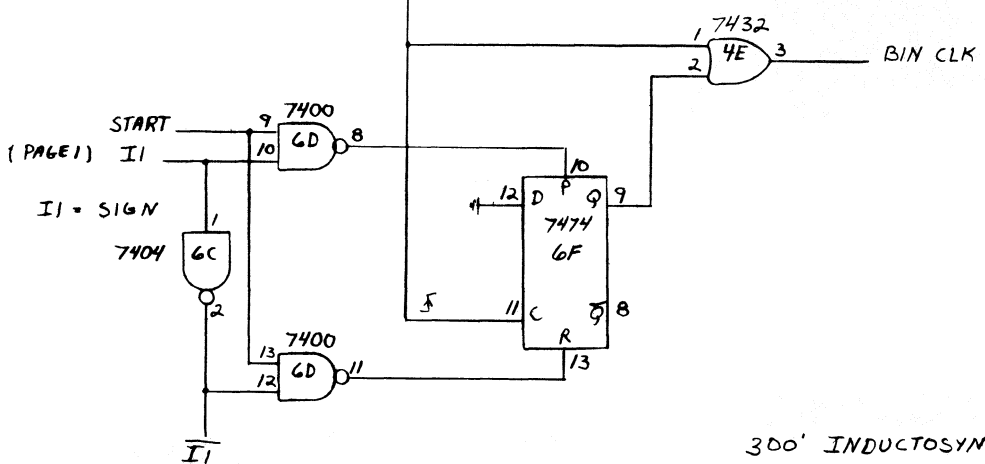
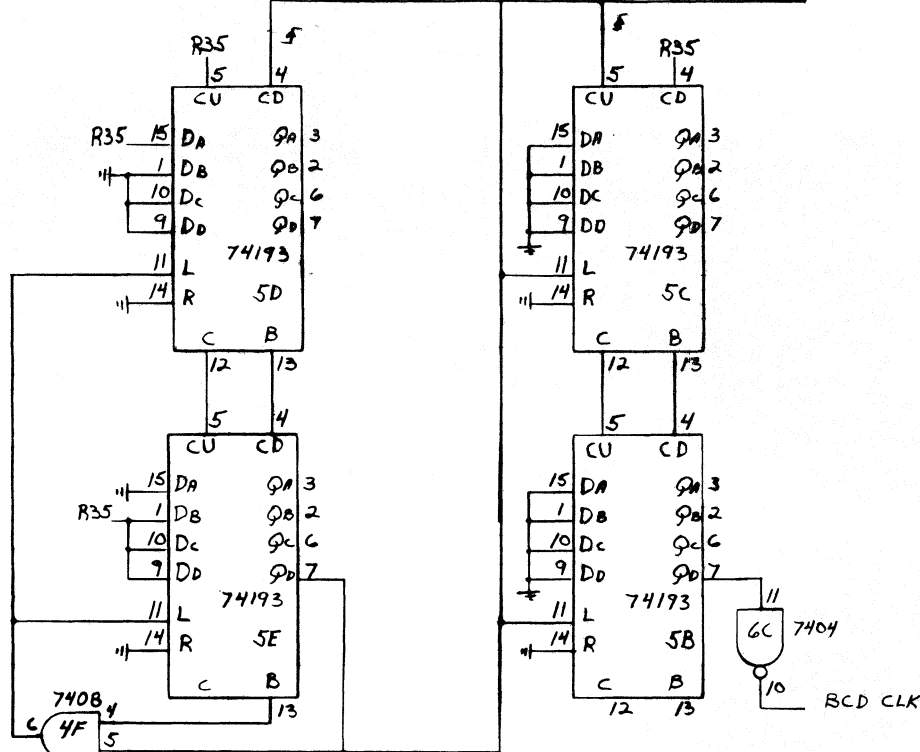
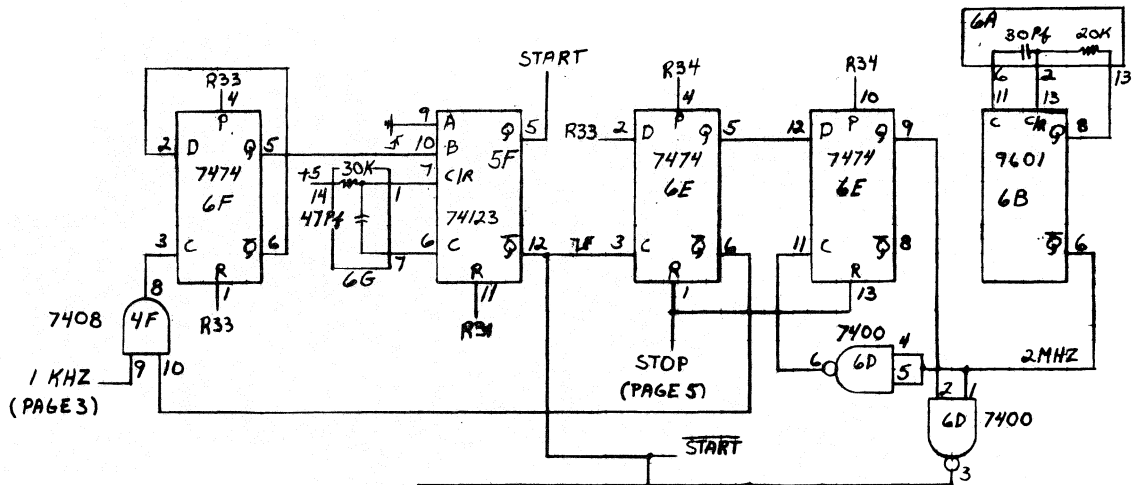
SEL X S1  
Y S3  
R27  
R30  
1 SEL  
3A 2A 1A  
3B 2B 1B  
74157 ENB 15  
3Y 2Y 1Y  
12 7 4  
155  
DATA  
155  
257  
459

DISPLAY MULTIPLEXING

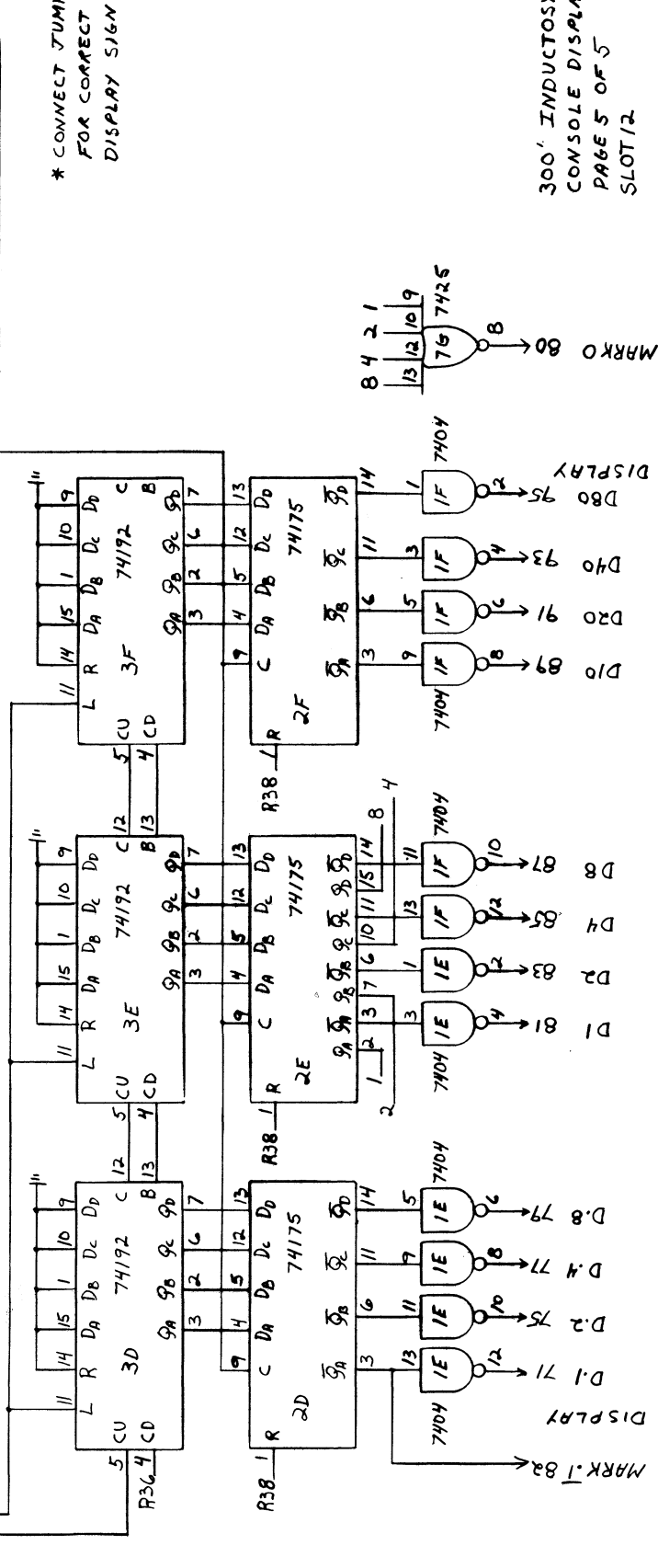
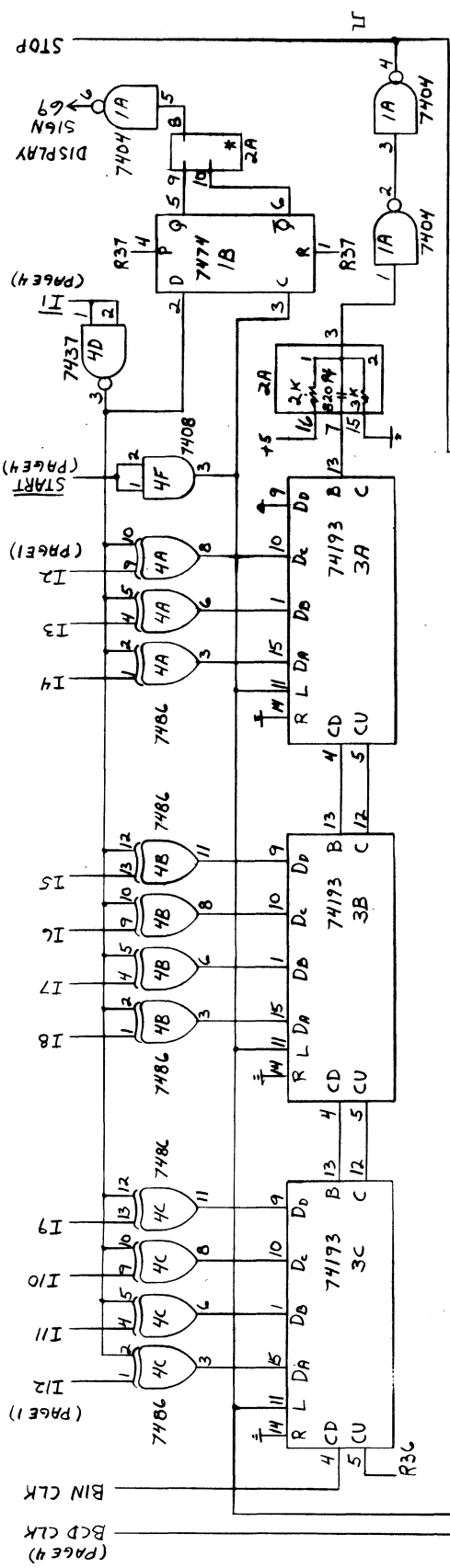
SEPERATE	COMBINED			INDEXED		
	1 8	4 4	2 1	1 1	2 1	1 1
0	0	0	0	0	0	0
1	0	3	4	0	5	1
2	0	6	7	0	5	1
3	0	9	0	5	5	1
4	0	5	5	0	5	1
5	0	4	5	0	5	1
6	0	7	5	0	5	1
7	0	7	5	0	5	1



300' INDUCTOSYM  
FRONT PANEL DISPLAY  
PAGE 3 OF 5  
SLOT 12



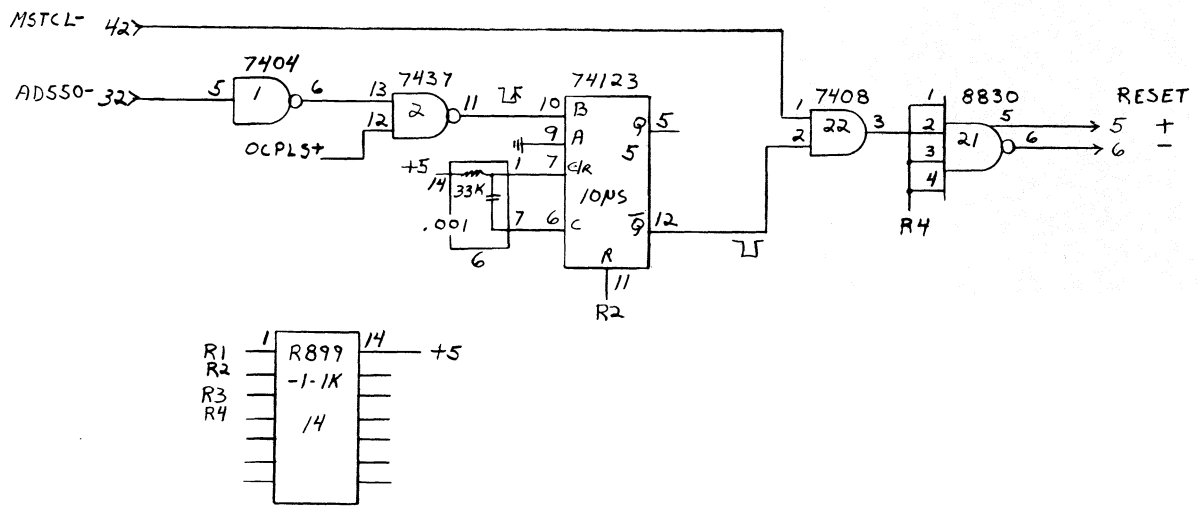
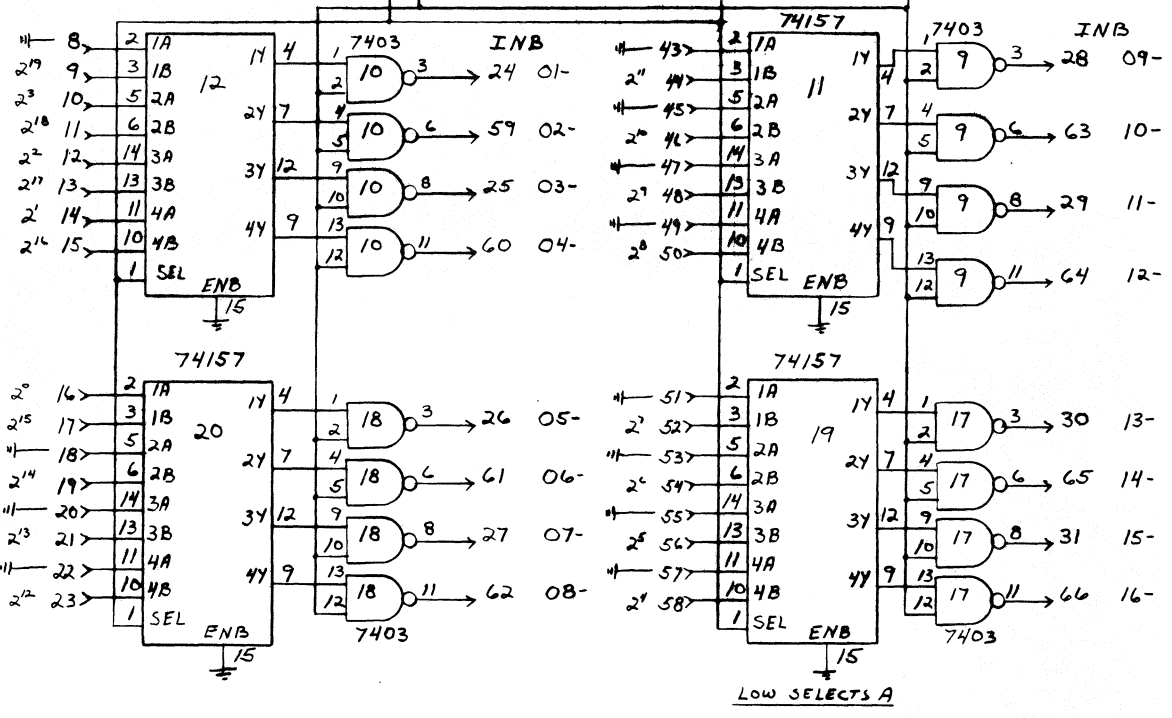
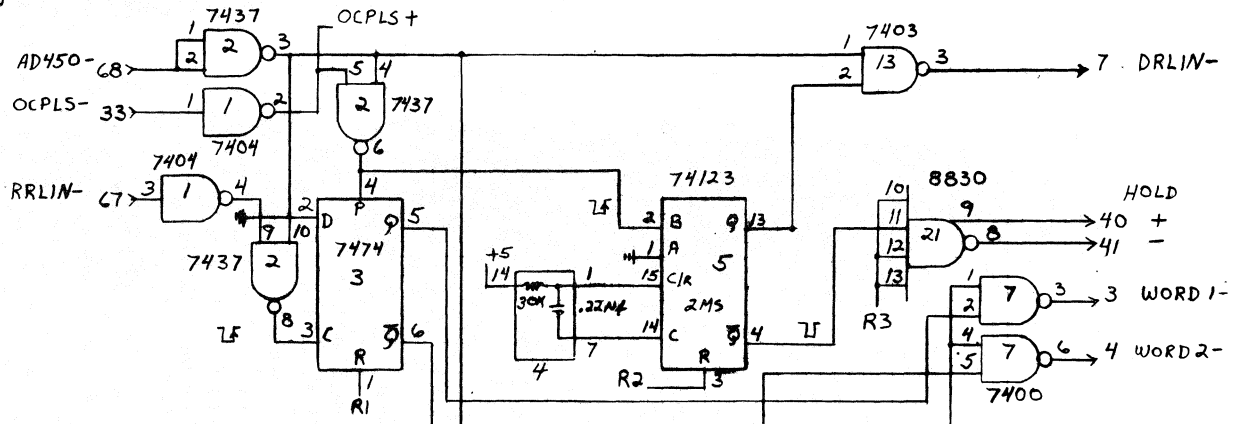
300' INDUCTOSYN  
CONSOLE DISPLAY  
PAGE 4 OF 5  
SLOT 12

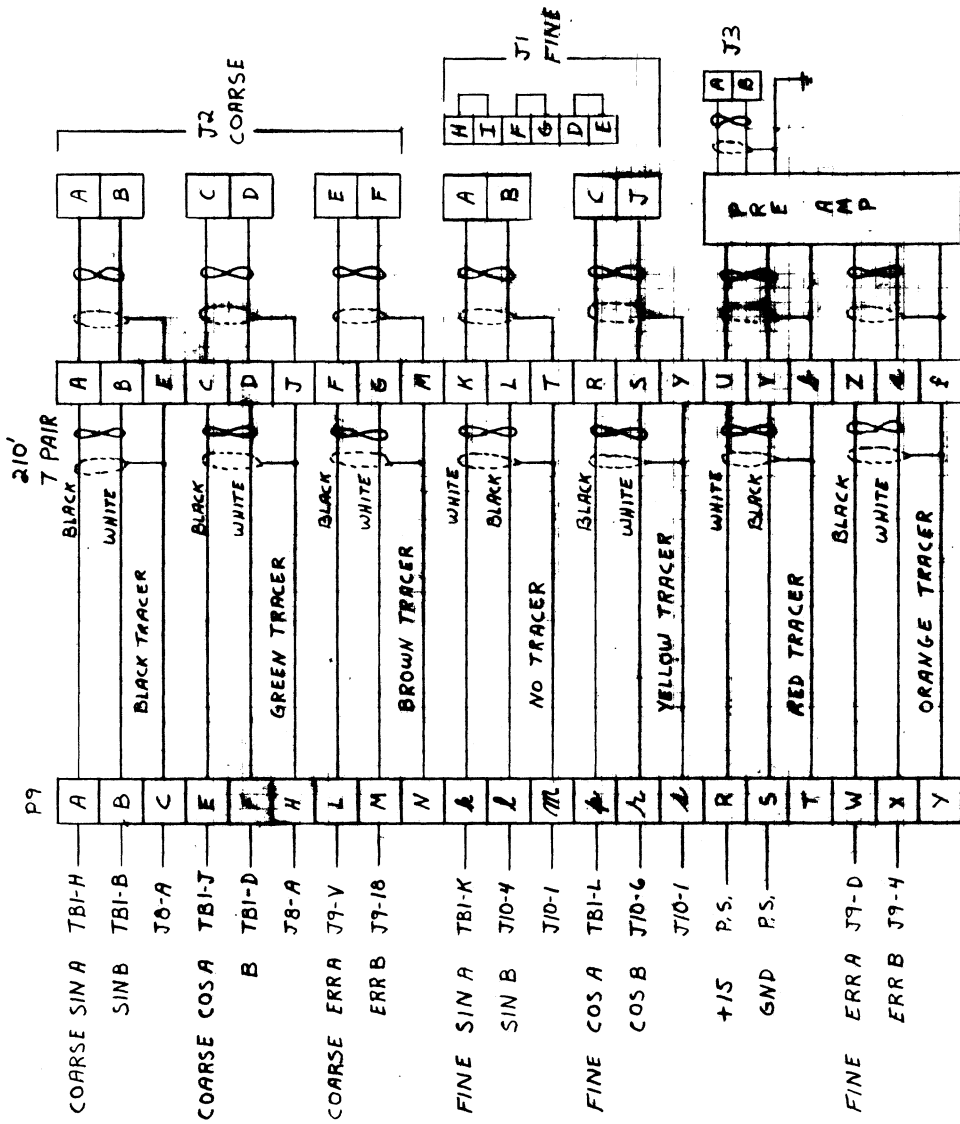
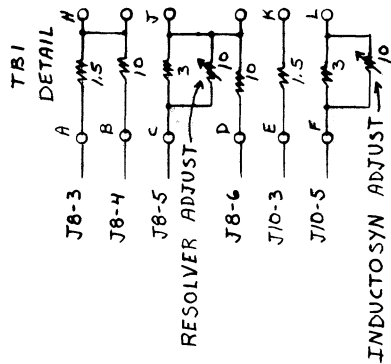
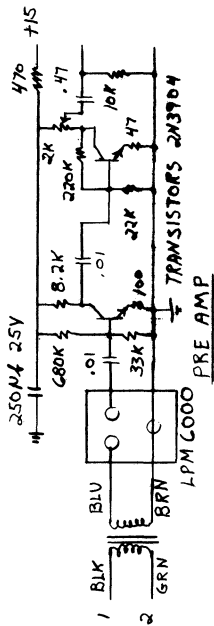


\* CONNECT JUMPER FOR CORRECT DISPLAY SIGN

300' INDUCTOSYN.  
CONSOLE DISPLAY  
PAGE 5 OF 5  
SLOT 12

9





56 PIN ELCO  
EXPOSED PINS  
KEY BIG PIN 1  
SMALL PIN 7

81-194228-15P → BULKHEAD  
81-194628-15S → CABLE

300' INDUCTOSYN  
EAST CABLE