

Observing Techniques and Calibration



David Frayer (Green Bank Observatory)



The GBT provides a lot of observing choices

- Pick receiver based on frequency
- Pick backend based on observing type (line, continuum, pulsar,)
- Pick observing techniques based on science goals (point source, large field, narrow lines vs broad lines....)
- Calibration strategies depend on receiver and science needs

Available GBT receivers

Table 1: GBT Receivers

| Receiver | Frequency Range |
|---|-------------------------------------|
| Prime Focus 1 | 290-920 MHz |
| Prime Focus 2 | 910-1230 MHz |
| L-band | 1.15-1.73 GHz |
| S-band | 1.73-2.60 GHz |
| C-band (shared risk) | 3.8-8.0 GHz |
| X-band | 8.0-11.6 GHz |
| Ku-band | 12.0-15.4 GHz |
| K-band Focal Plane Array (7 pixels) | 18.0-26.0 GHz |
| Ka-band | 26.0-39.5 GHz |
| Q-band | 38.2-49.8 GHz |
| W-band | 67-93.3 GHz |
| MUSTANG 2 bolometer array (shared risk) | 80-100 GHz |
| ARGUS (shared risk) | 75-115.3 GHz, Private PI instrument |


What
frequency
do you
need?

Available GBT Backends

Table 2: GBT Backends and Observing Modes

| Backend | Observing Modes |
|--|-----------------------------------|
| Versatile Green Bank Astronomical Spectrometer (VEGAS) | Continuum, pulsar, spectral line |
| Digital Continuum Receiver (DCR) | Continuum |
| Green Bank Ultimate Pulsar Processing Instrument (GUPPI) | Pulsar |
| Mark V Very Long Baseline Array Disk Recorder | Very Long Baseline Interferometry |
| Caltech Continuum Backend (CCB) (Ka-band) | Continuum |
| Zspectrometer (Ka-band) | Private PI instrument |
| Radar | Private PI instrument |

Observing Mode vs Backend Capabilities

| What are you doing?: | Continuum | Continuum full-stokes | Line | Pulsar | VLB | Radar |
|----------------------|---|--|---|-------------------------------------|---------------------------|------------------|
| | DCR | Mode-1 VEGAS | VEGAS | GUPPI | Mark5 VLBA recorder | Radar backend |
| | CCB (Ka) | Mueller matrix calibration (function of parallactic angle) | {29 modes} | VEGAS- Pulsar | | |
| | Mustang (3mm) | |  | {Search mode, timing mode} | | |
| | Reduction uses specialized scripts | | | | | |

VEGAS

Modes:

16 separate spectrometer channels (8 dual polarization channels) that can be divided between beams and different frequencies as needed and can support up to 8 spectral sub-windows per spectrometer.

Maximum data rate ~160GB/s, but most projects at <1MB/s

Table 4: VEGAS modes.

| Mode | Spectral Windows per Spectrometer | Bandwidth per Spectrometer (MHz) | Number of Channels per Spectrometer | Approximate Spectral Resolution (kHz) |
|------|-----------------------------------|----------------------------------|-------------------------------------|---------------------------------------|
| 1 | 1 | 1500 ^a | 1024 | 1465 |
| 2 | 1 | 1500 ^a | 16384 | 92 |
| 3 | 1 | 1080 ^b | 16384 | 66 |
| 4 | 1 | 187.5 | 32768 | 5.7 |
| 5 | 1 | 187.5 | 65536 | 2.9 |
| 6 | 1 | 187.5 | 131072 | 1.4 |
| 7 | 1 | 100 | 32768 | 3.1 |
| 8 | 1 | 100 | 65536 | 1.5 |
| 9 | 1 | 100 | 131072 | 0.8 |
| 10 | 1 | 23.44 | 32768 | 0.7 |
| 11 | 1 | 23.44 | 65536 | 0.4 |
| 12 | 1 | 23.44 | 131072 | 0.2 |
| 13 | 1 | 23.44 | 262144 | 0.1 |
| 14 | 1 | 23.44 | 524288 | 0.05 |
| 15 | 1 | 11.72 | 32768 | 0.4 |
| 16 | 1 | 11.72 | 65536 | 0.2 |
| 17 | 1 | 11.72 | 131072 | 0.1 |
| 18 | 1 | 11.72 | 262144 | 0.05 |
| 19 | 1 | 11.72 | 524288 | 0.02 |
| 20 | 8 ^c | 23.44 | 4096 | 5.7 |
| 21 | 8 ^c | 23.44 | 8192 | 2.9 |
| 22 | 8 ^c | 23.44 | 16384 | 1.4 |
| 23 | 8 ^c | 23.44 | 32768 | 0.7 |
| 24 | 8 ^c | 23.44 | 65536 | 0.4 |
| 25 | 8 ^c | 16.875 | 4096 | 4.1 |
| 26 | 8 ^c | 16.875 | 8192 | 2.0 |
| 27 | 8 ^c | 16.875 | 16384 | 1.0 |
| 28 | 8 ^c | 16.875 | 32768 | 0.5 |
| 29 | 8 ^c | 16.875 | 65536 | 0.26 |

^a The useable bandwidth for this mode is 1250 MHz.

^b The useable bandwidth for this mode is 850 MHz.

^c For modes 20-24, the spectral windows must be placed within 1500 MHz with a useable frequency range of 150 to 1400 MHz. For modes 25-29, the spectral windows must be placed within 1000 MHz with a useable frequency range of 150 to 950 MHz.

Picking your observing mode

The telescope measures:

T_a = “antenna temperature”

- $T_a(\text{total}) = T_{\text{source}} + \{T_{\text{rx}} + T_{\text{bg}} + T_{\text{atm}} + T_{\text{spill}}\}$
- Where $\{\dots\}$ = other contributions
- Want T_{source} , so carry out ON – OFF
- $T_a(\text{ON}) = T_{\text{source}} + \{\dots\}$
- $T_a(\text{OFF}) = \{\dots\}$
- So $T_a(\text{ON}) - T_a(\text{OFF}) = T_{\text{source}}$

➔ Need to carry out ON-OFF observations and there are different observing techniques for measuring ON-OFF

Different Observing Modes to derive the reference data (OFF)

Types of reference observations

➤ Frequency Switching

- In or Out-of-band

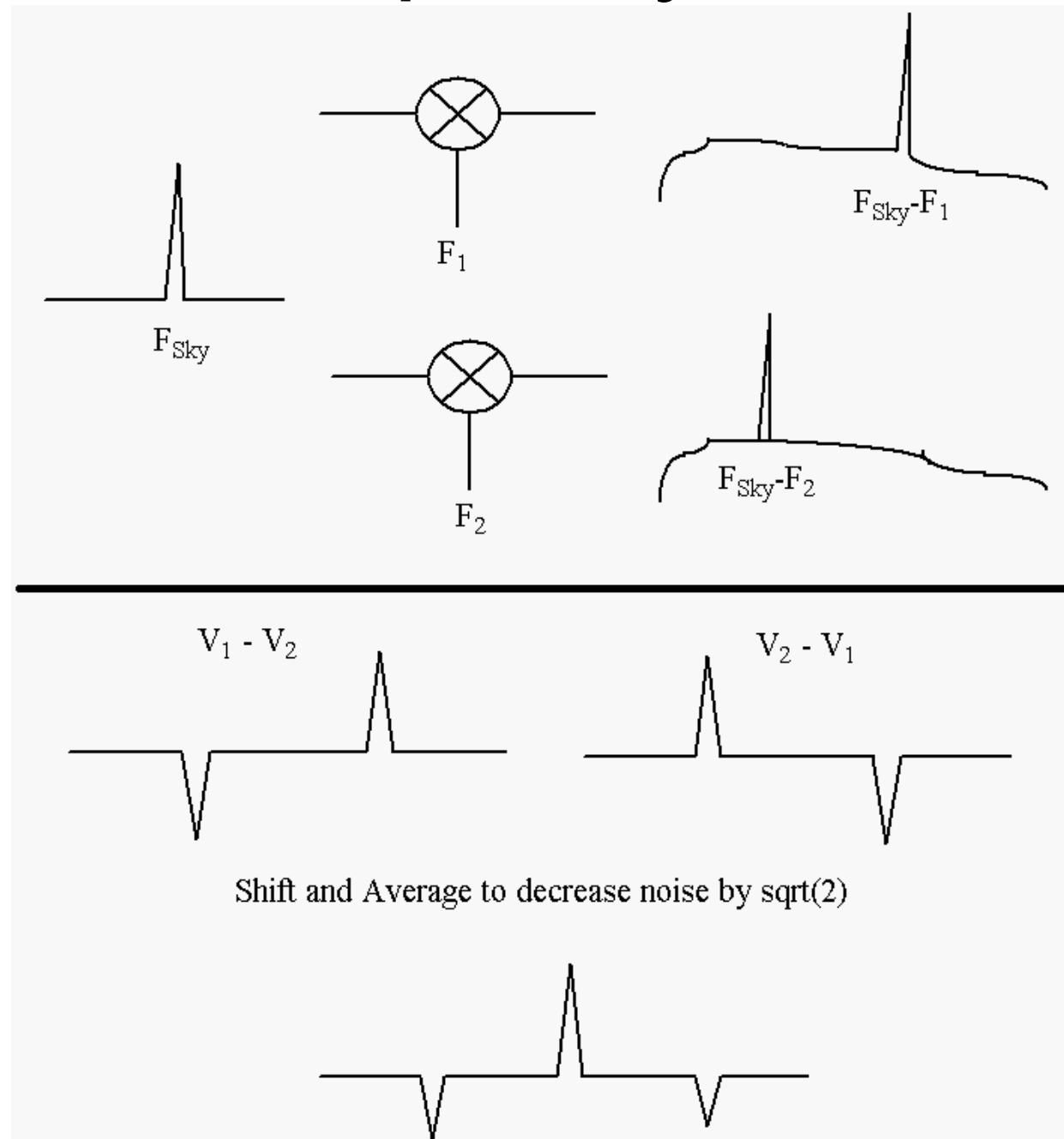
➤ Position Switching

- Reference-Off
- Mapping-Off

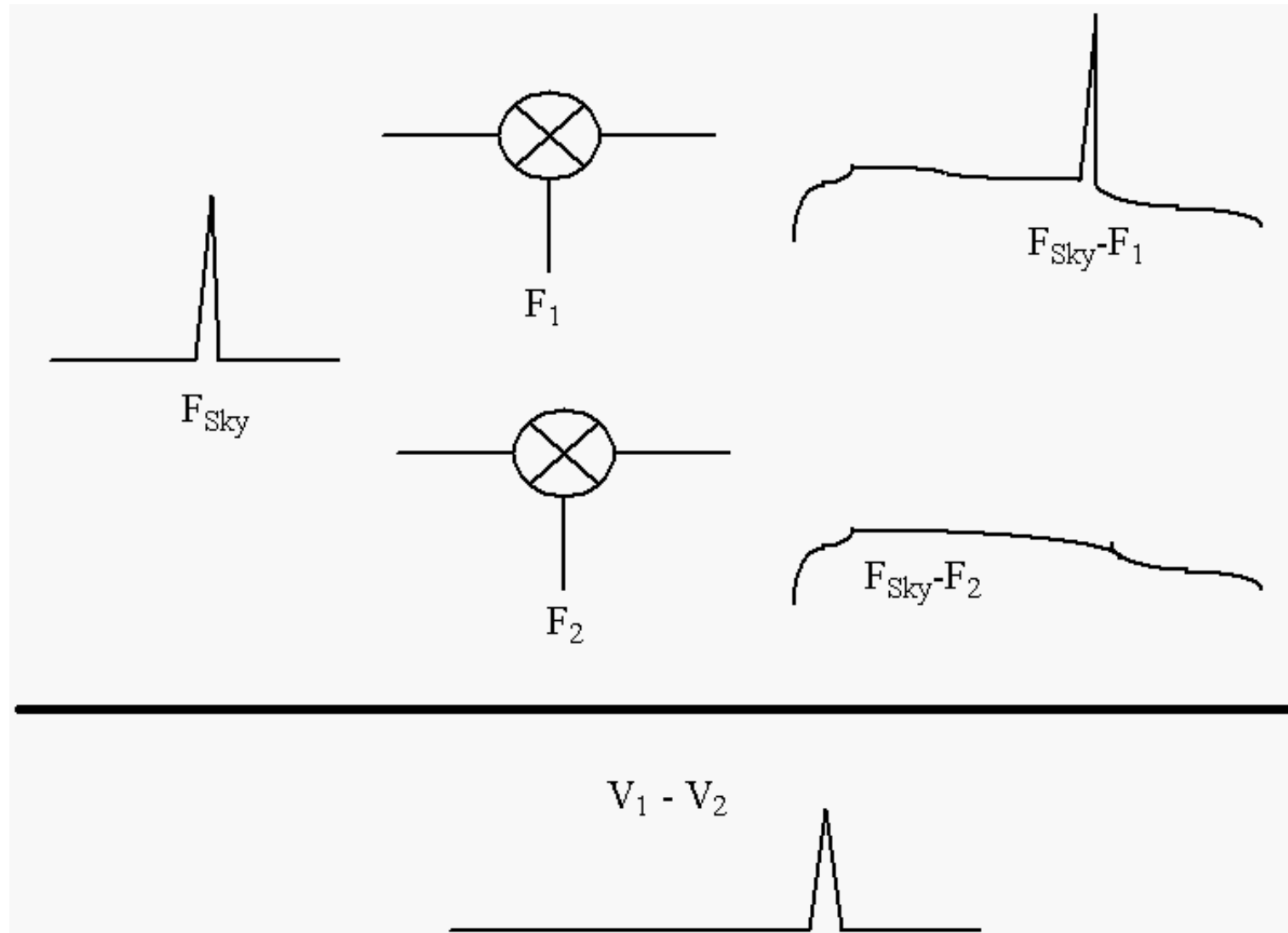
➤ Dual-Beam Position Switching

- **Nod** -- Move telescope
- **SubBeamNod** -- Move Subreflector

In-Band Frequency Switching



Out-Of-Band Frequency Switching



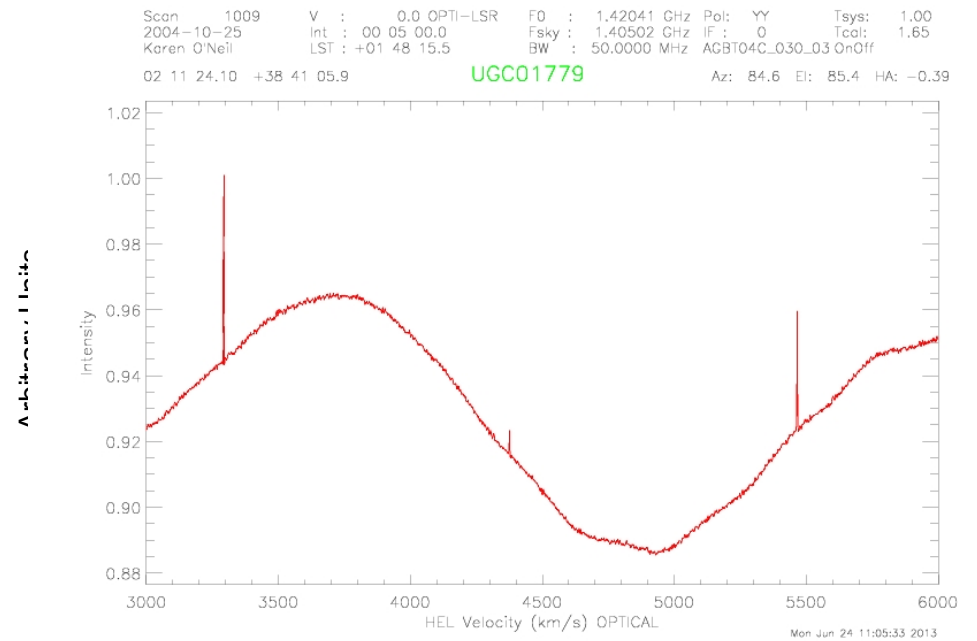
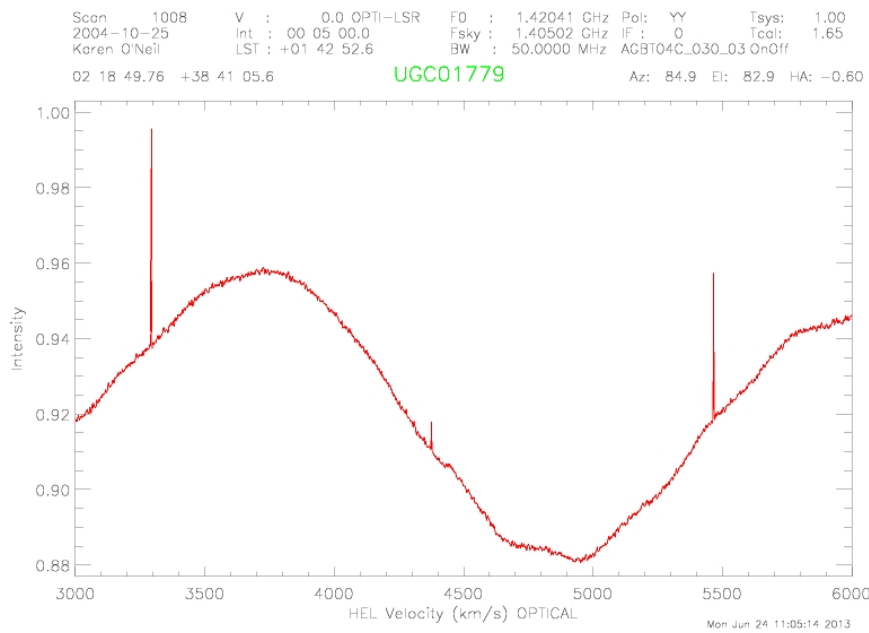
Position Switching

ON source

$$T_{\text{source}} + T_{\text{everything else}}$$

OFF source

$$T_{\text{everything else}}$$

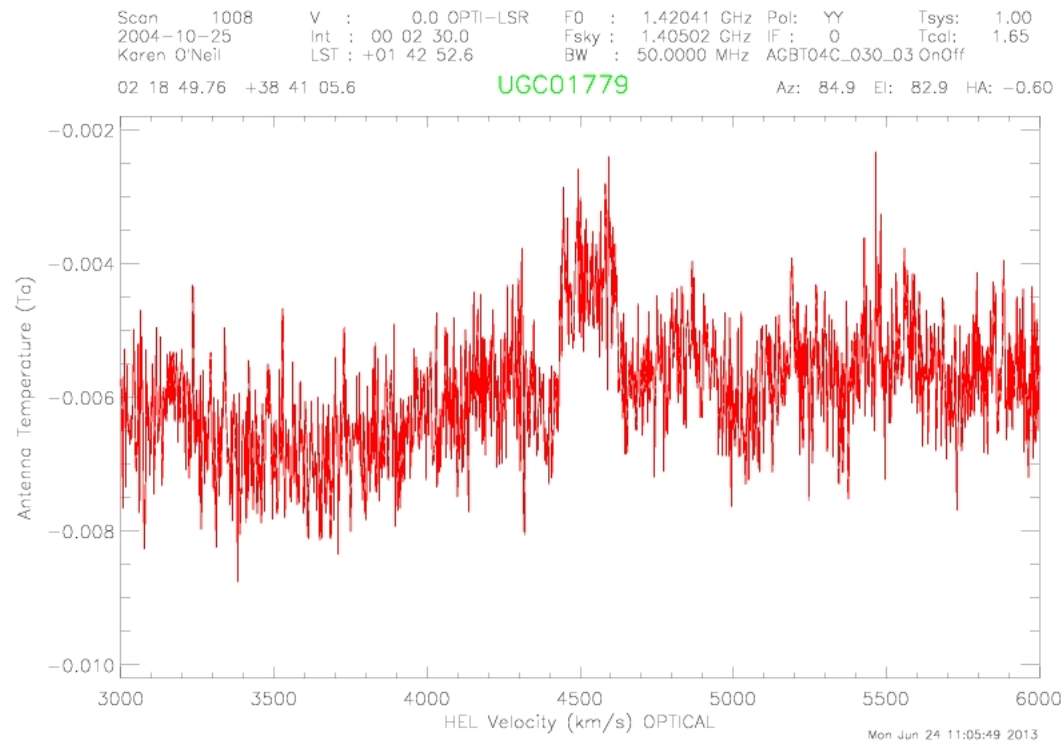


Position Switching: ON-OFF on Sky

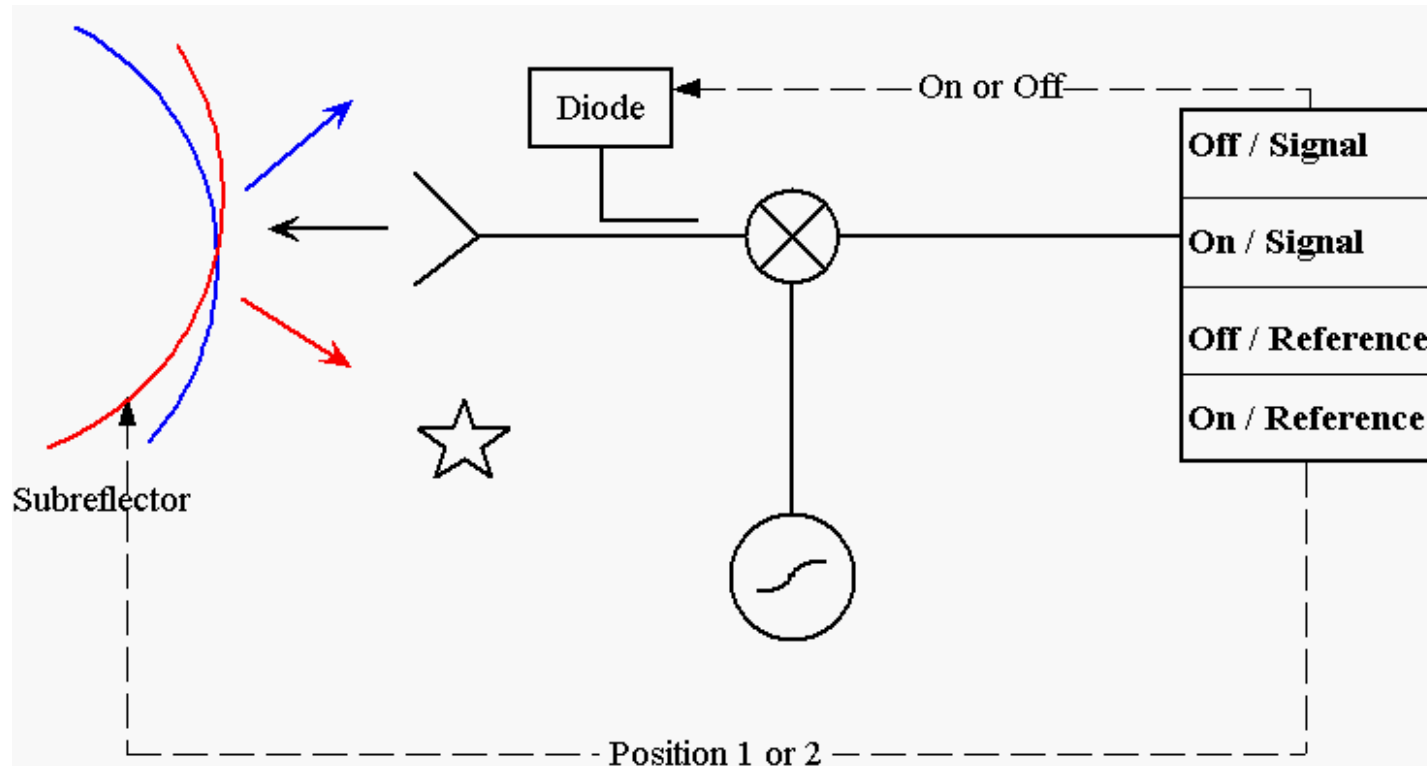
ON - OFF

$$(T_{\text{source}} + T_{\text{everything else}}) - (T_{\text{everything else}})$$

Arbitrary Counts

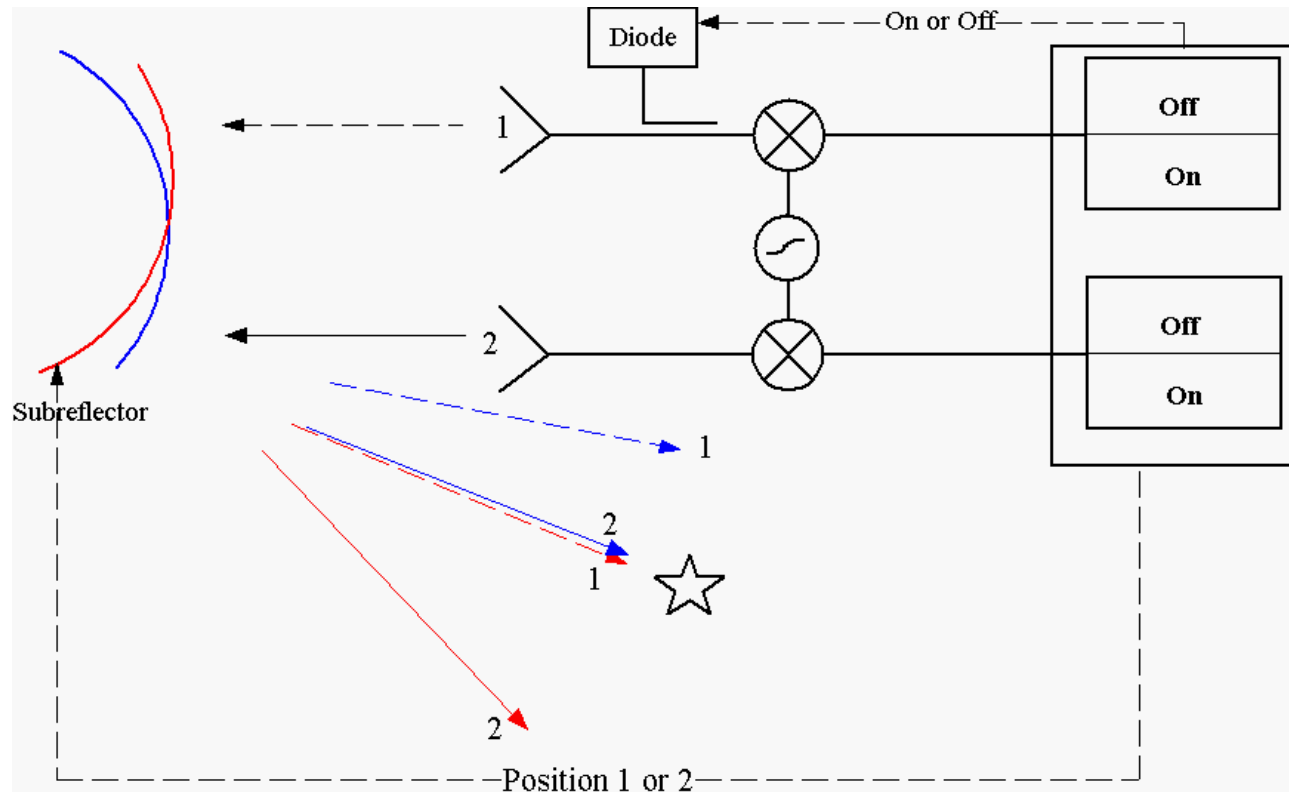


Beam Switching – Subreflector or tertiary mirror



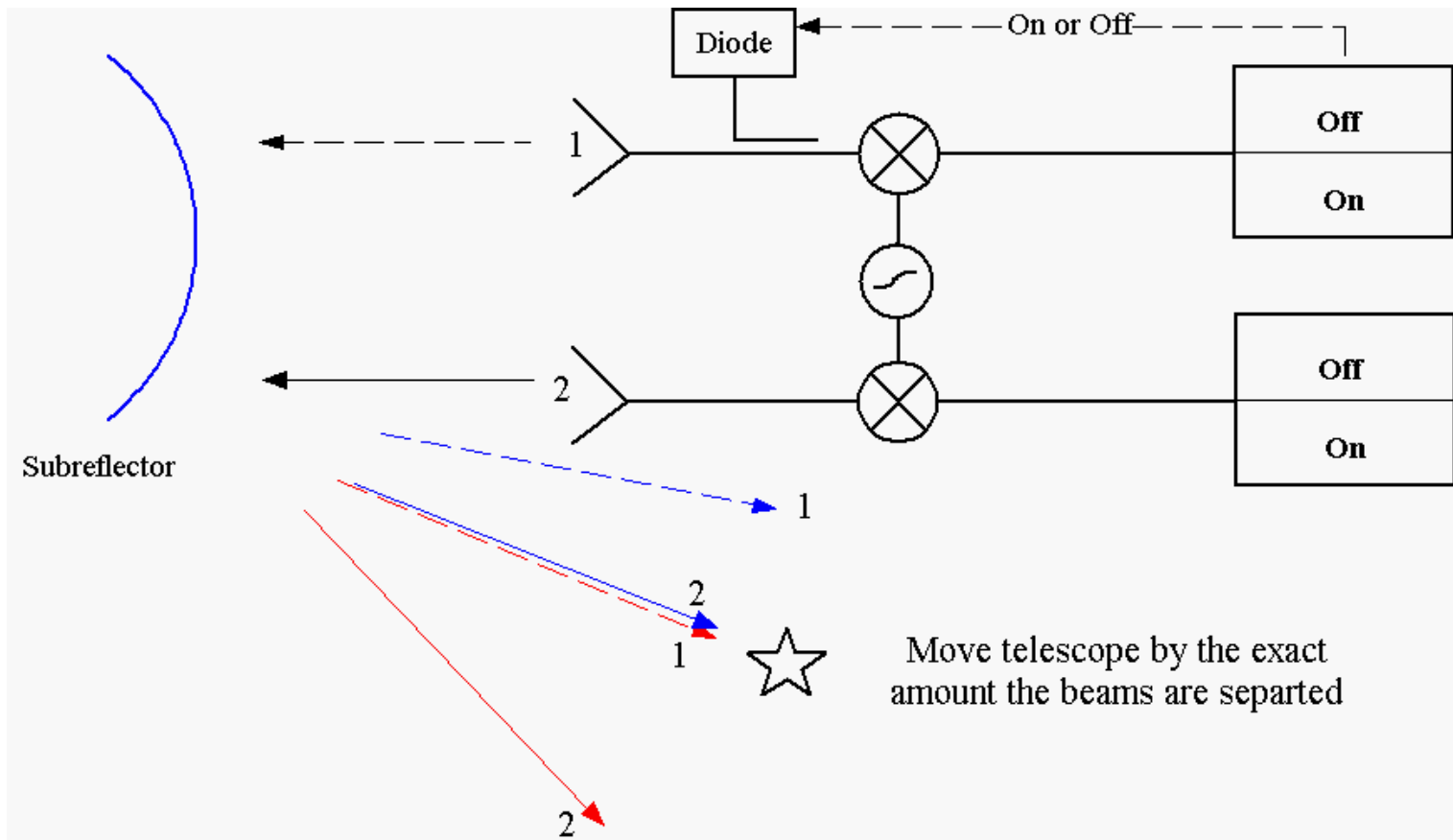
- Removes any 'fast' gain/bandpass changes
- Low overhead. $\frac{1}{2}$ time spent off source

Subreflector Nodding with multi-beam receivers (SubBeamNod)



- Removes any 'fast' gain/bandpass changes
- Low overhead. ~All the time is spent on source

Nodding with dual-beam receivers - Telescope motion (NOD)



- Removes any 'fast' gain/bandpass changes
- Overhead from moving the telescope. All the time is spent on source

Mapping Techniques

| | | | | | | | | |
|---|---|--|--|--|--|---|--|---|
| 1 | 7 | | | | | | | 1 |
| 2 | 8 | | | | | | | 2 |
| 3 | 9 | | | | | | | 3 |
| 4 | | | | | | 9 | | 4 |
| 5 | | | | | | 8 | | 5 |
| 6 | | | | | | 7 | | 6 |

- **Point map**

- Sit, Move, Sit, Move, etc.

- **On-The-Fly Mapping**

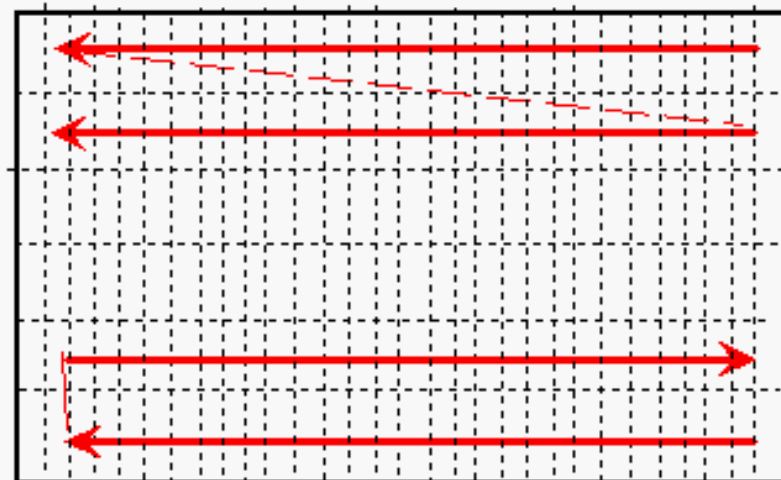
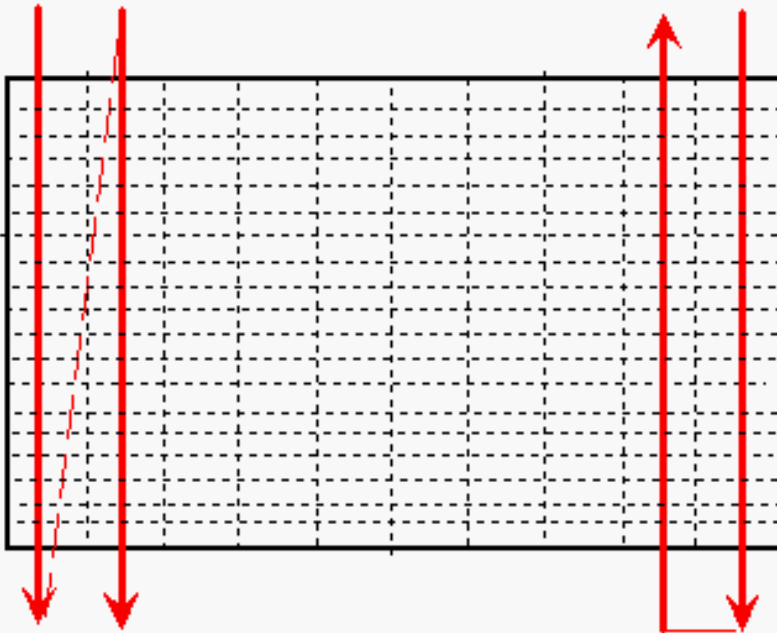
- Slew a column or row while collecting data

- Move to next column row

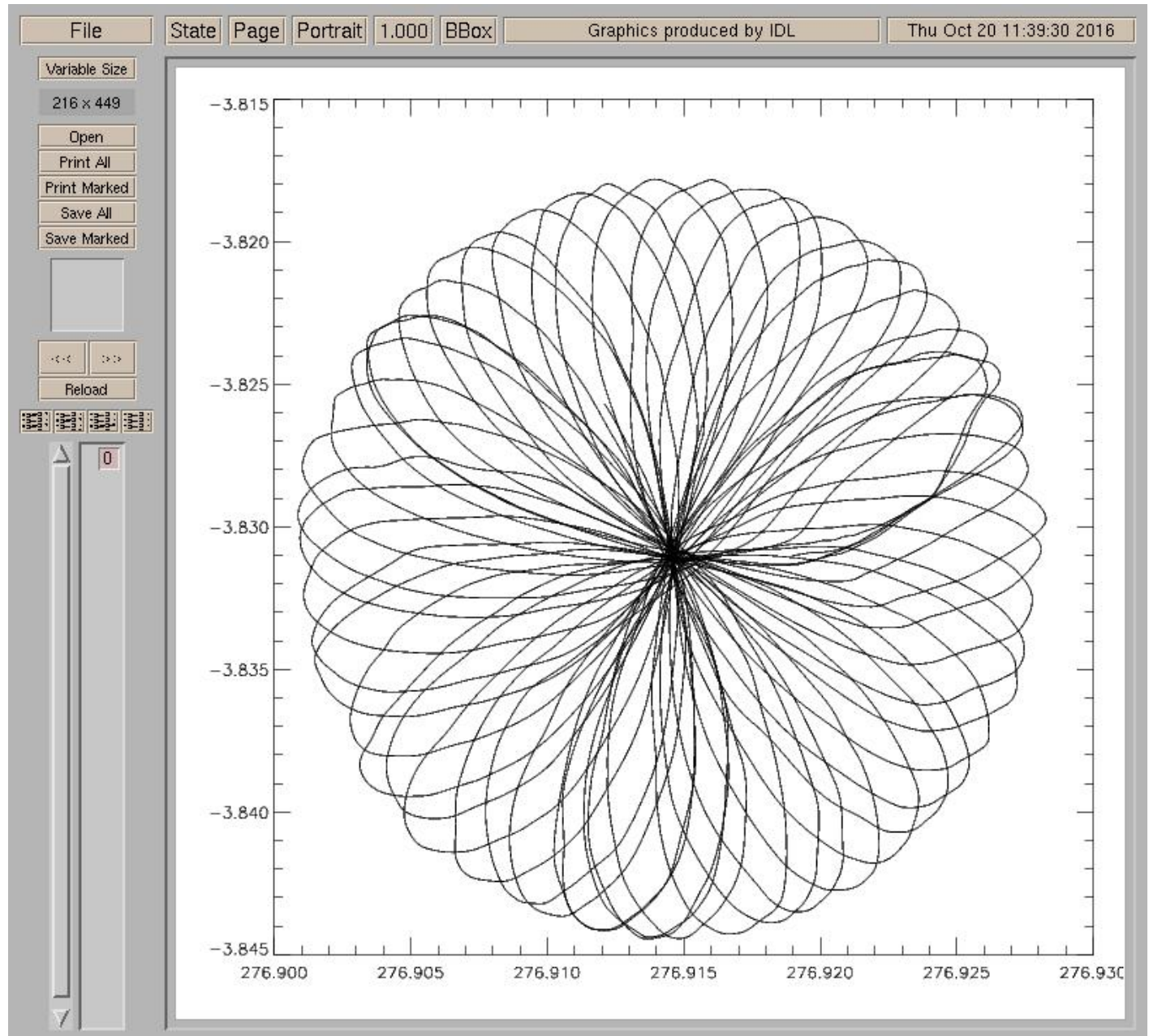
- Basket weave

- Should oversample $\sim 3x$ Nyquist along direction of slew

Reference/OFF from a “source-free” map position or separate “OFF” spectrum taken.



Example Daisy Scan Map



Frequency vs Position Switching

- Narrow line in non-crowded spectrum → Frequency Switching (FS)
- Narrow line in crowded spectral region or significant RFI → Position Switching (PS)
- Broad line → PS
- Narrow line < 10 km/s
- Broad line > 100 km/s

Observing Mode – Small Source

If source size $<$ beam, Line Obs, and PS:

- Nod {two beams} – if not limited by baselines
- SubBeamNod {two beams} – if baseline limited
- OnOff {one beam}
- Track (with and w/o offset)

If source size $<$ beam, Line Obs and FS:

- Track

If source size $<$ beam, Continuum Obs:

- Daisy map (efficient way to deal with $1/f$ noise)

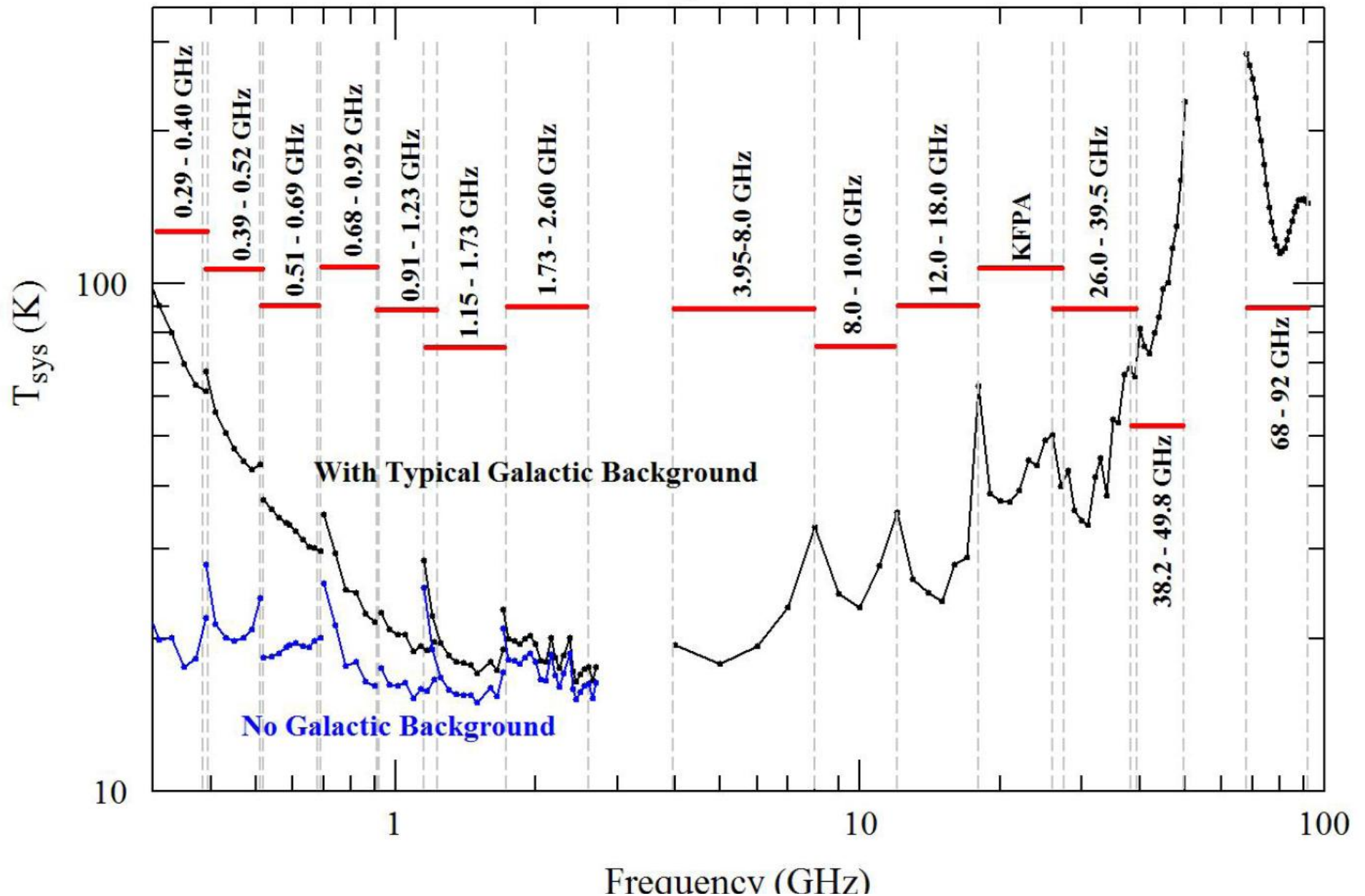
Observing Mode – Large Source

- Map $>$ FOV of instrument
 - RaLongMap and/or DecLatMap
- Map $< \sim$ FOV of instrument
 - RaLong/DecLat mapping
 - Daisy
 - Box scans
 - PointMap (Grid) if needing a deep spectrum

Performance of the GBT

Noise Levels (T_{sys}) for Typical Weather

Log-Log Plot of Expected T_{sys} for Typical Weather Conditions



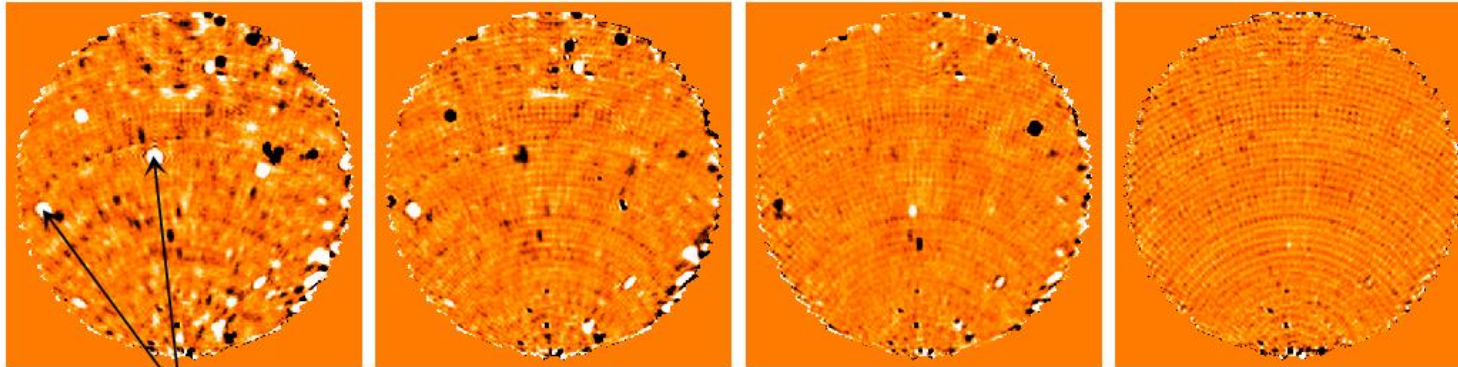
GBT Surface Improved in 2009

January 2009

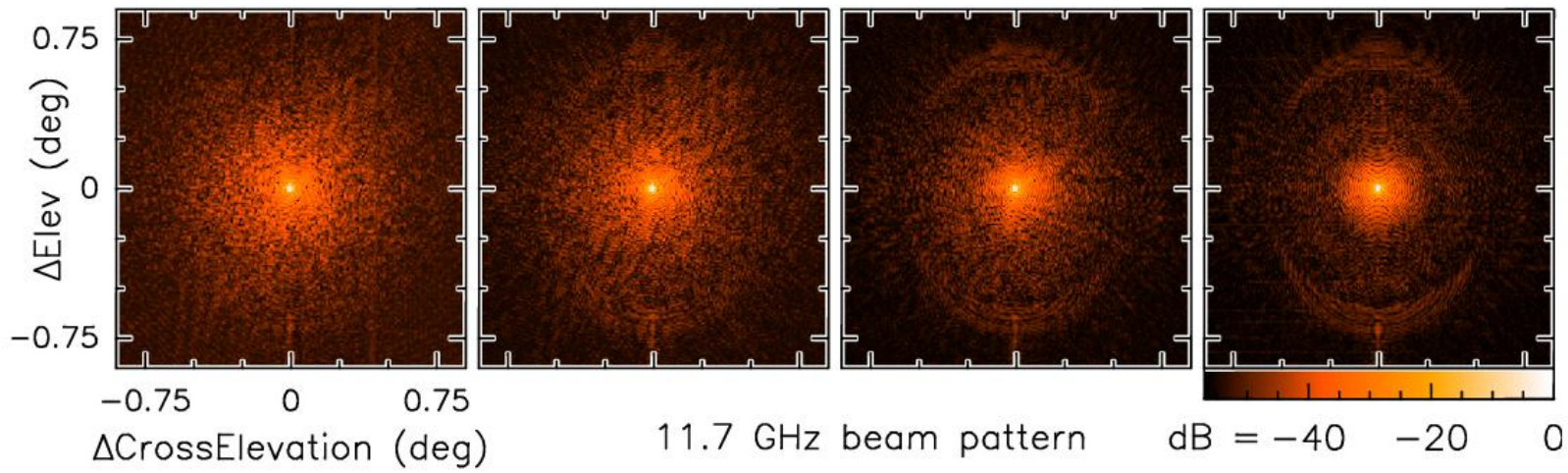
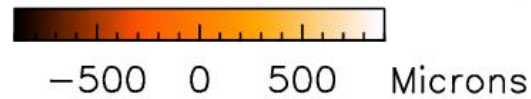
February 2009

March 2009

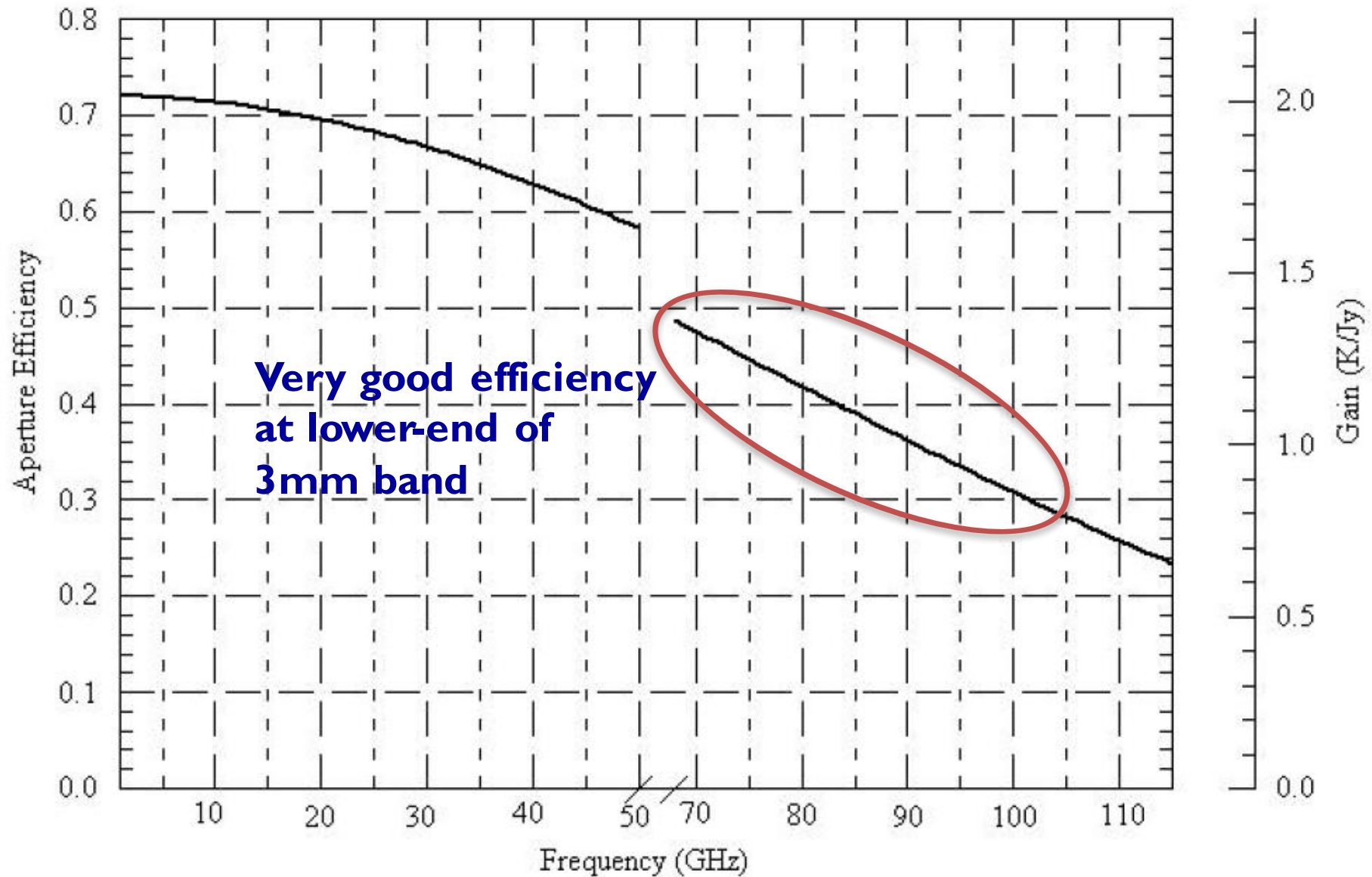
September 2009



Broken Actuators



GBT Aperture Efficiency and Gain (K/Jv)



GBT Pointing and Surface Performance

- ~5-10 arcscec blind pointing
- ~2 arcsec offset pointing
- ~1 arcsec tracking accuracy
- Rms (surface) ~ 0.35mm – no corrections during day
- Rms (surface) ~ 0.3mm – no corrections during night
- Rms(surface) ~0.23mm with corrections at night
- Long-term Goal: Rms(surface)~0.20mm

Observing: Antenna Optimization

- Should point+focus every 30min-1hr depending on frequency and time of day (point+focus takes ~5min)
- AutoOOF (which takes ~30min) is used to correct the surface for thermal effects for Q-band and W-band at night.
- Daytime surface changes <1hr time scales and the AutoOOF solutions can cause more harm than good after ~1hr from the AutoOOF (so it is typically not useful to use the “thermal” corrections during the day).

Calibration

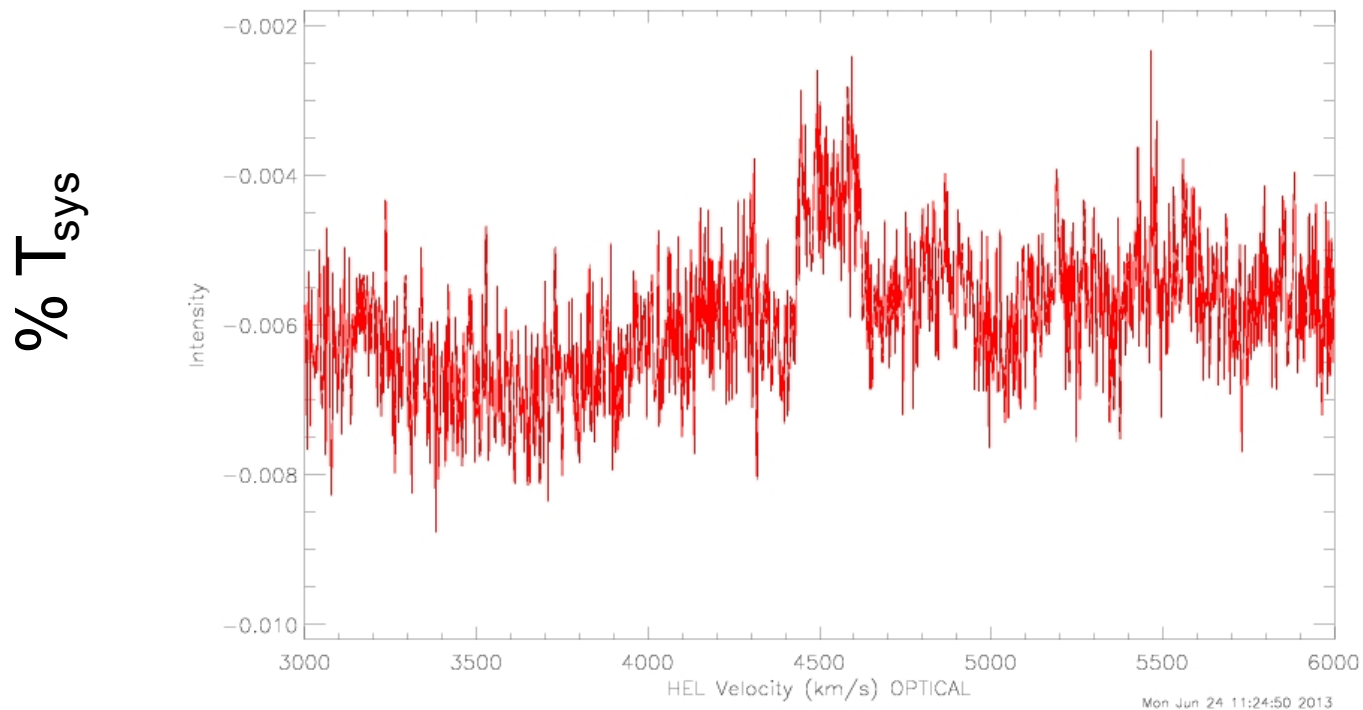
Calibration of Data

$$(ON - OFF) / OFF$$

$$[(T_{\text{source}} + T_{\text{everything else}}) - (T_{\text{everything else}})] / T_{\text{everything else}}$$

$$= (\text{Source temperature}) / (\text{"System" temperature})$$

Scan 1008 V : 0.0 OPTI-LSR F0 : 1.42041 GHz Pol: YY Tsys: 1.00
2004-10-25 Int : 00 05 00.0 Fsky : 1.40502 GHz IF : 0 Tcal: 1.65
Karen O'Neil LST : +01 42 52.6 BW : 50.0000 MHz AGBT04C_030_03 OnOff
02 18 49.76 +38 41 05.6 UGC01779 Az: 84.9 El: 82.9 HA: -0.60



GBT Definition of T_a

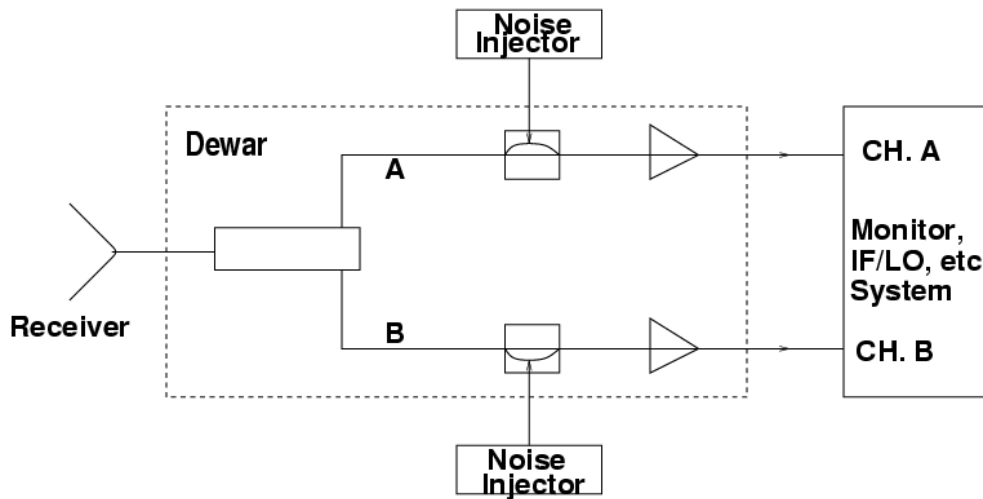
$$T_a = \frac{(\text{ON} - \text{OFF})}{\text{OFF}} T_{\text{system}}$$

Blank Sky or other

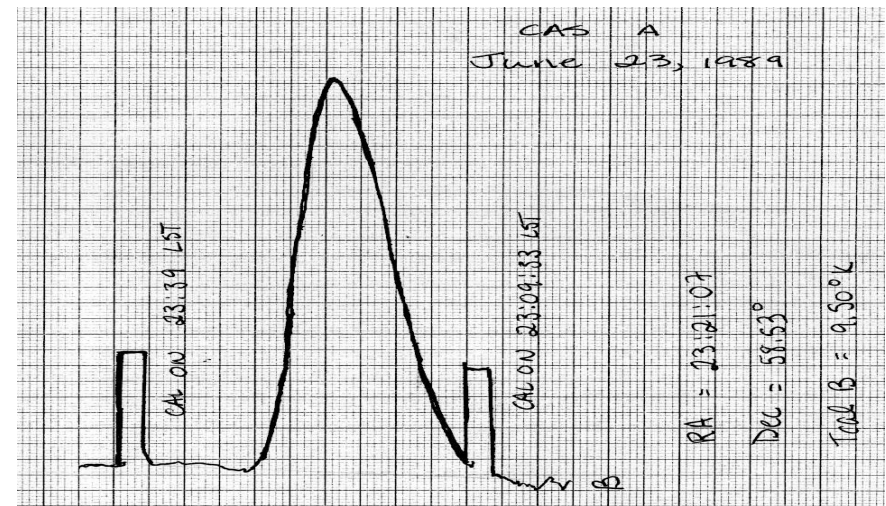
From diodes, Hot/Cold loads, etc.

Determining T_{sys}

Noise Diodes



All GBT receivers besides 4mm, Argus, and Mustang use noise diodes.



Determining T_{sys}

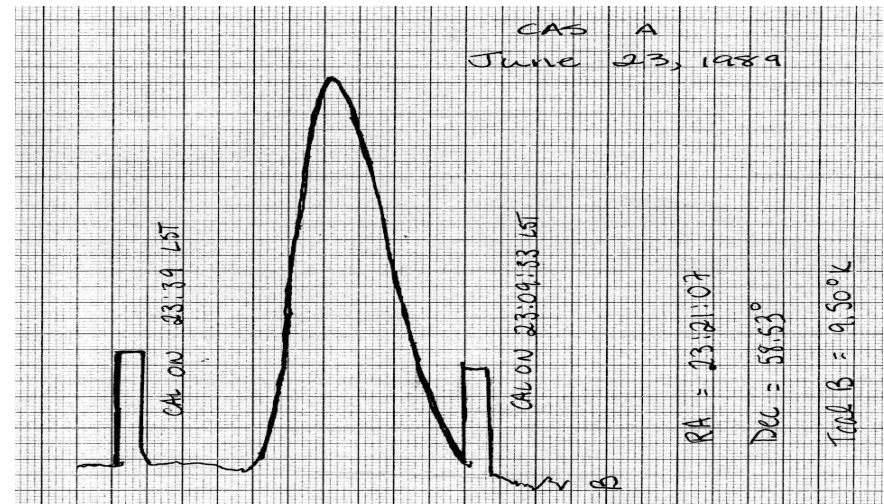
Noise Diodes

$$T_{sys} = T_{cal} * OFF / (ON - OFF)$$

GBT: Flicker diode on/off

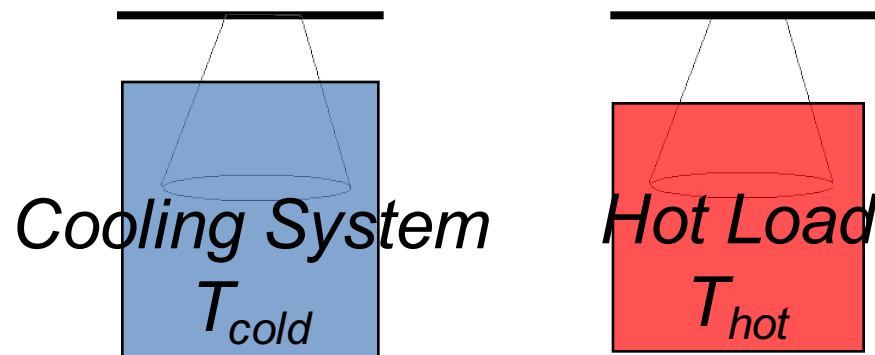
$$T_{sys} = T_{cal} * OFF / (ON - OFF) + T_{cal} / 2$$

Typically choose low T_{cal} value to minimize T_{sys} and high T_{cal} value for very bright sources (for Rx that have two options)



Determining T_{sys}

Hot & Cold Loads

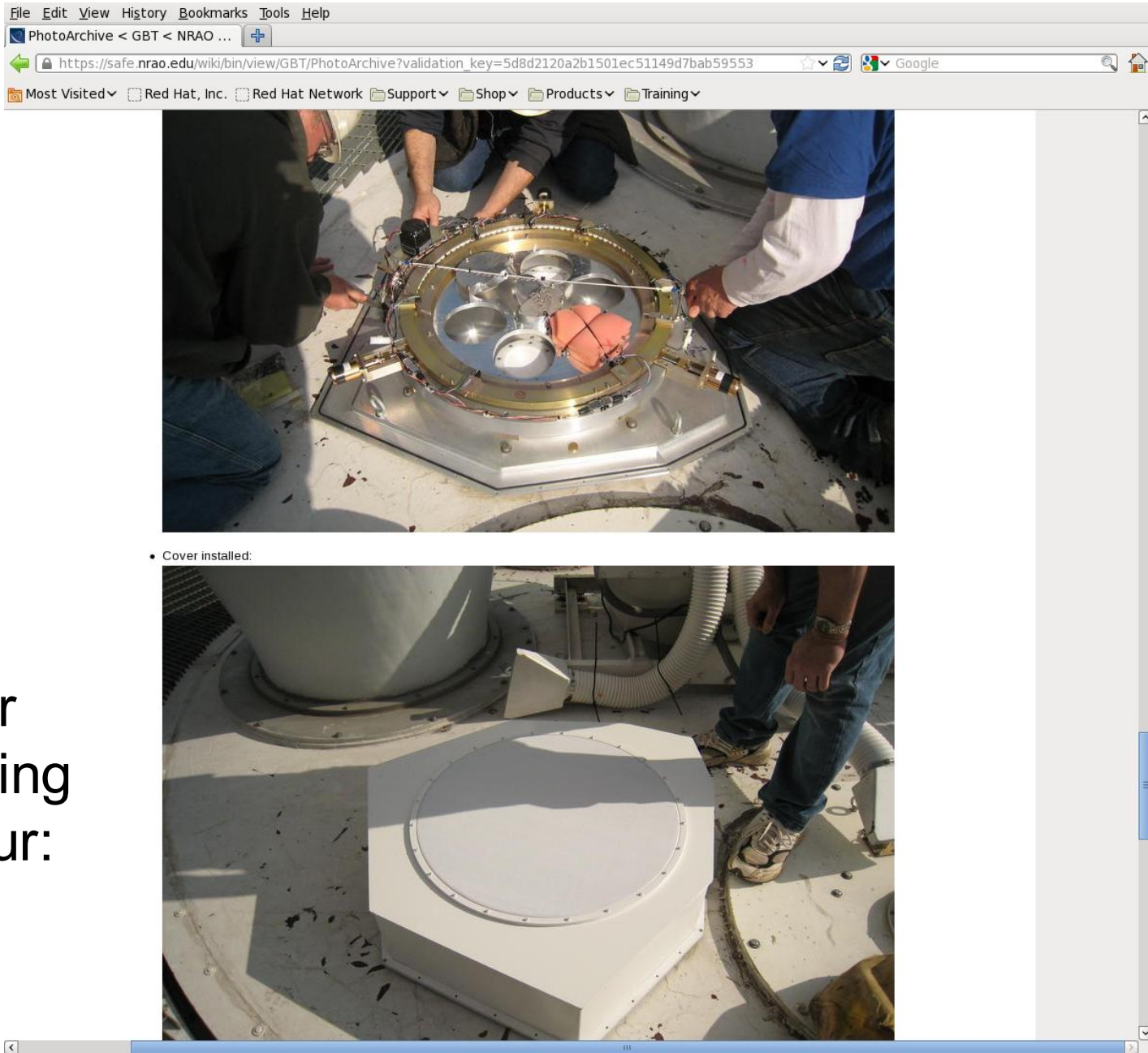


Gain: $g = (T_{hot} - T_{cold}) / (V_{hot} - V_{cold})$ [K/Volts]

$T_{sys} = g V_{off}$

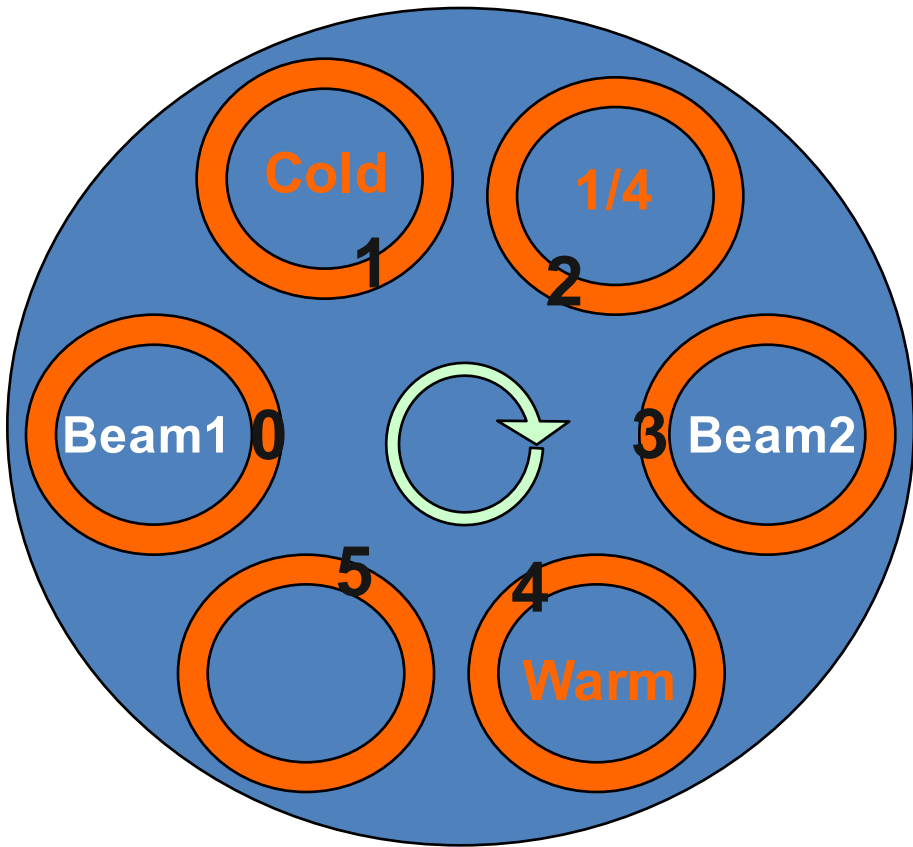
Example GBT 4mm Rx

Installation of 4mm calibration wheel and external cover



Look for
this during
GBT tour:

4mm Calibration Wheel



| | Wheel Position (defined wrt Beam1) | Beam 1 | Beam 2 |
|---|--|-----------------|-----------------|
| 0 | Observing | Sky | Sky |
| 1 | Cold1 | Cold | Warm |
| 2 | Position2 | 1/4wave circ | Sky |
| 3 | Position3 | Sky | Sky |
| 4 | Cold2 | Warm | Cold |
| 5 | Position5 | Sky | 1/4wave Circ |

CalSeq-auto Scan (GFM display)

File Edit View Tools Help

ObservationManagement - 1 DataDisplay - 1 GbtStatus - 1

52 B0212+735 OnOff (1 of 2)
53 B0212+735 OnOff (2 of 2)
54 J1012+5307 Track (1 of 1)
55 J1012+5307 Track (1 of 1)
56 J1012+5307 Track (1 of 1)
57 J1012+5307 Track (1 of 1)
58 J1012+5307 Track (1 of 1)
59 J1012+5307 Track (1 of 1)
60 J1012+5307 Track (1 of 1)
61 JUPITER CALSEQ (1 of 1)
62 JUPITER Peak (1 of 4)
63 JUPITER Peak (2 of 4)
64 JUPITER Peak (3 of 4)
65 JUPITER Peak (4 of 4)
66 JUPITER FocusSubreflector (1 of 1)
67 JUPITER CALSEQ (1 of 1)
68 JUPITER Peak (1 of 4)
69 JUPITER Peak (2 of 4)
70 JUPITER Peak (3 of 4)
71 JUPITER Peak (4 of 4)
72 JUPITER FocusSubreflector (1 of 1)
100 2255+4202 Peak (1 of 4)
101 2255+4202 Peak (2 of 4)
102 2255+4202 Peak (3 of 4)
103 2255+4202 Peak (4 of 4)
104 2255+4202 FocusSubreflector (1 of 1)
105 2322+4445 Peak (1 of 4)
106 2322+4445 Peak (2 of 4)
107 2322+4445 Peak (3 of 4)

Pointing Focus OOF Continuum Spectral Line

61:JUPITER

Power

Time

Warm1 Beam1

Warm2 Beam2

Sky

Cold1

Cold2

Beams:
 1
 2

Polarizations:
 X
 Y

Phases:
 Signal / No Cal

Frequencies (GHz)
 77.00

Pyro Client Initialized. Using Pyro V3.4

Proj: TREG_140917, Scan: 10, Sub: 1, EWidth: 8.810, Width: 9.108, Center: -0.026, Height: 11.658, Tsys: 16.716
Scan numbers in calibration sequence: [61]
Calibration results:
TWARM 281.0
TCOLD 50.0
gain(beam-1, pol-Y) = 7.61e-04 K/counts
gain(beam-1, pol-X) = 7.08e-04 K/counts
gain(beam-2, pol-X) = 7.68e-04 K/counts
gain(beam-2, pol-Y) = 6.67e-04 K/counts
Tsys(beam-1, pol-X, Observing) = 113.6 K
Tsys(beam-1, pol-Y, Observing) = 111.5 K
Tsys(beam-2, pol-Y, Observing) = 111.0 K
Tsys(beam-2, pol-X, Observing) = 109.7 K

← When you click on a calseq scan, GFM reports the gains and Tsys in the console window

ObservationManagement Log - 1 DataDisplay Log - 1 GbtStatus Log - 1 Command Console

Idle (Offline)

Absolute Calibration on known astronomical sources (point sources)

→ Corrects for any errors in the adopted T_{diode} /gains measured in the lab and corrects for the telescope response

Observe and process source and known calibrator (3cX) source data in the same way, then the flux density of the source $S(\text{source})$ is simply:

$$S(\text{source})/S(3cX) = T(\text{source})/T(3cX),$$

where $S(3cX)$ is known.

Absolute calibration typically known to 5-15%

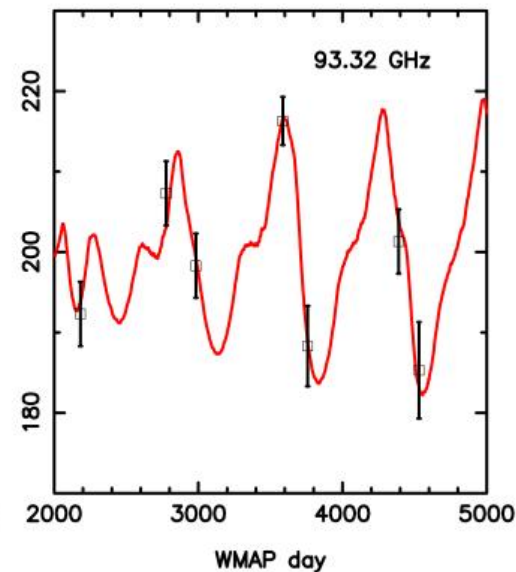
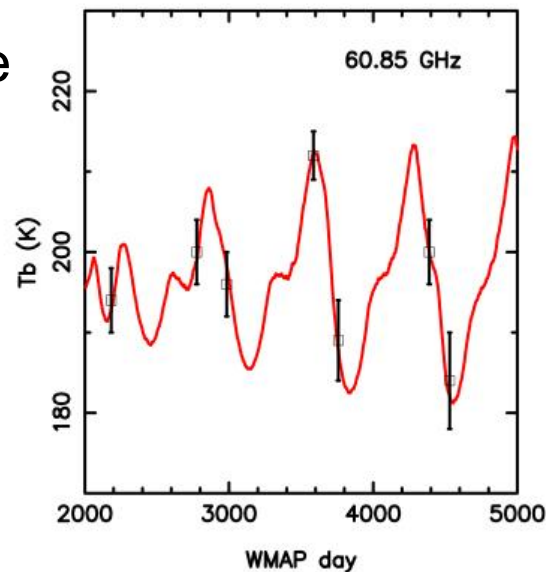
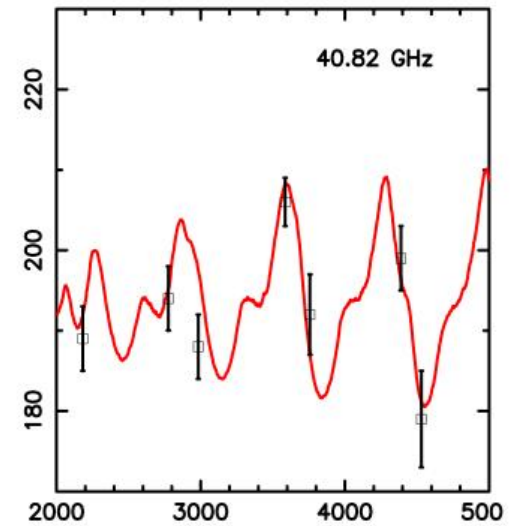
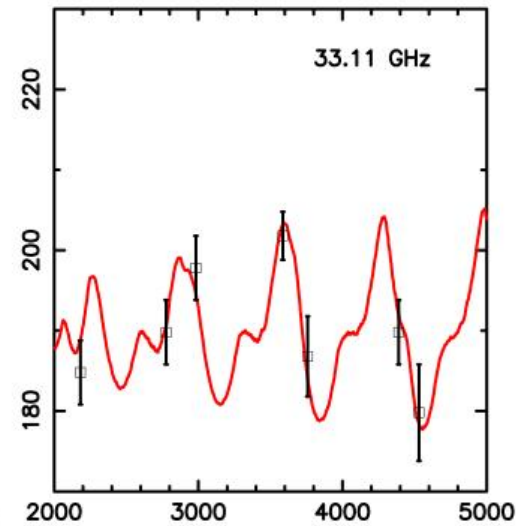
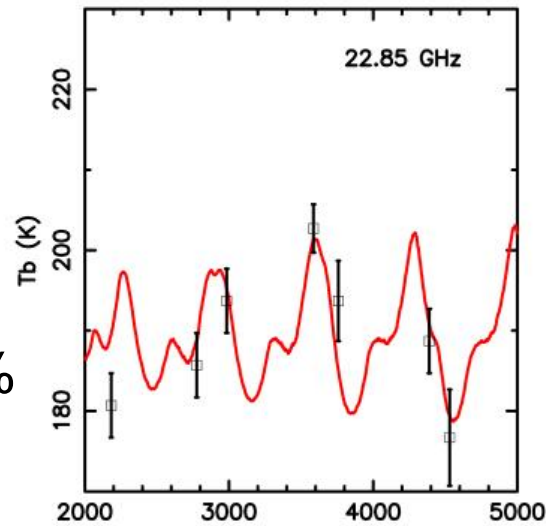
Absolute Calibration tied to Mars via WMAP

VLA
calibration (1-
50 GHz):

➤ <20 GHz ~1%
accurate

➤ 20-50 GHz:
~3% accurate

Perley &
Butler 2013

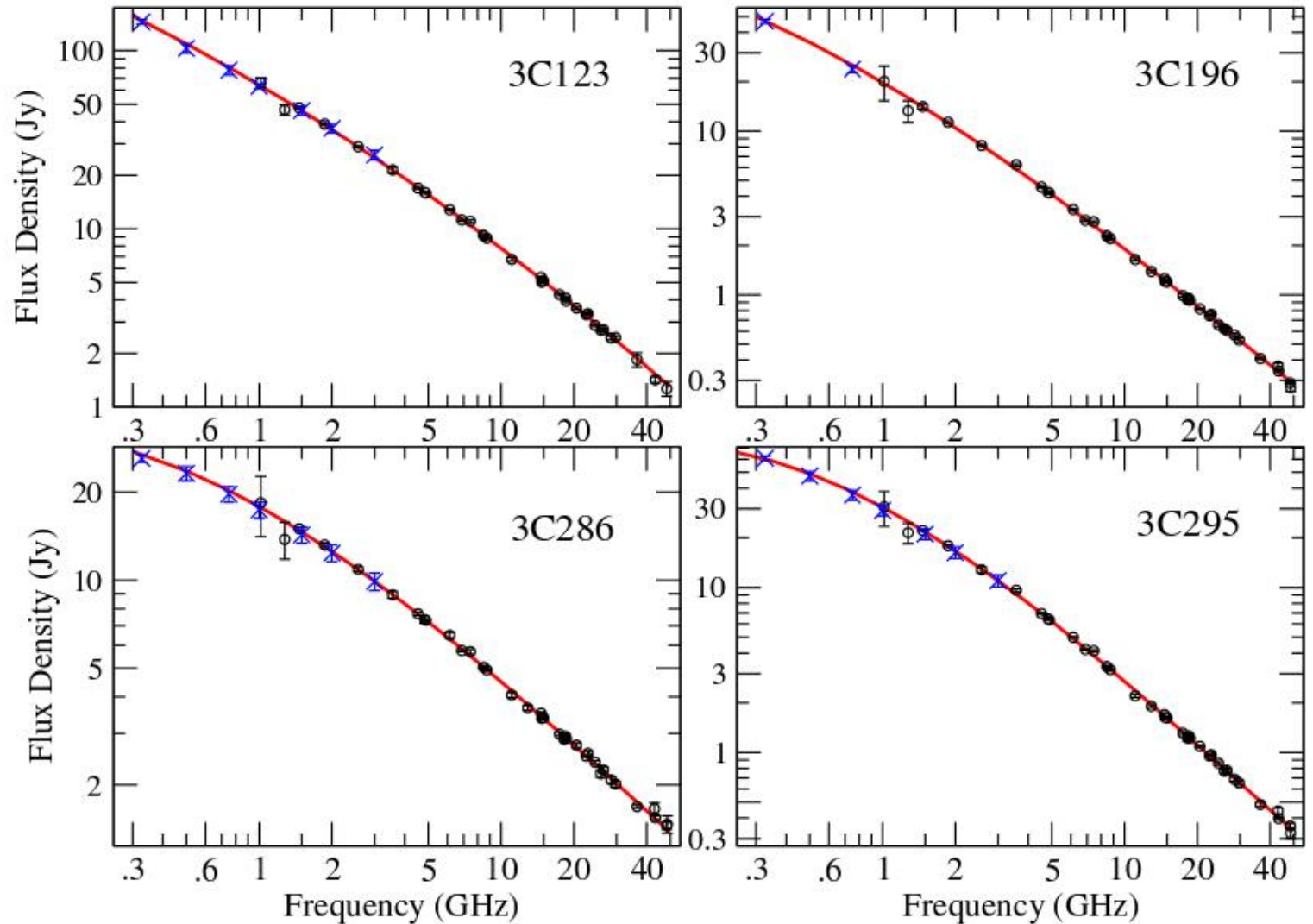


Mars WMAP
observations
with model in
red

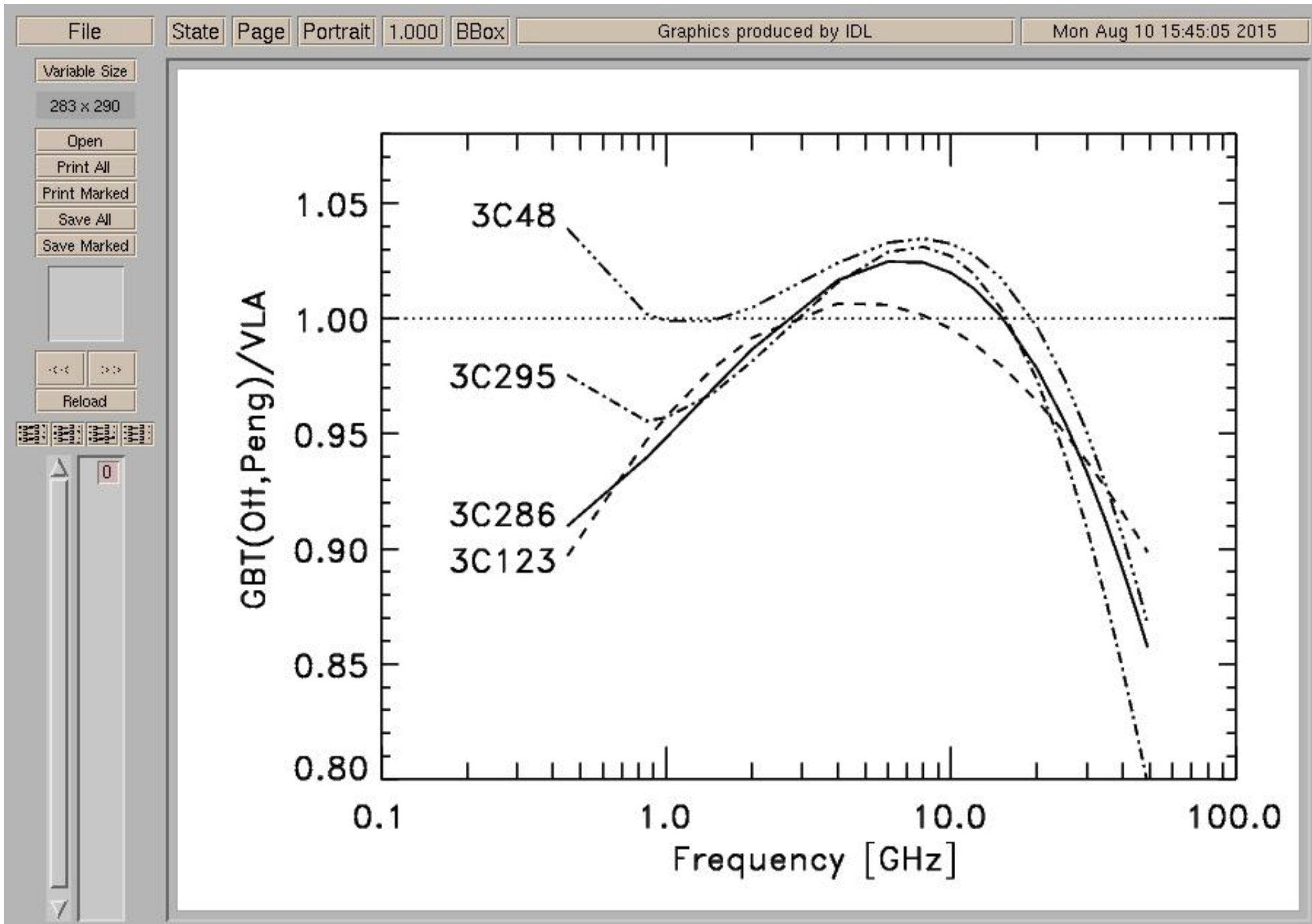
VLA Stable Calibrators

GBT
Calibration
“Plan”:

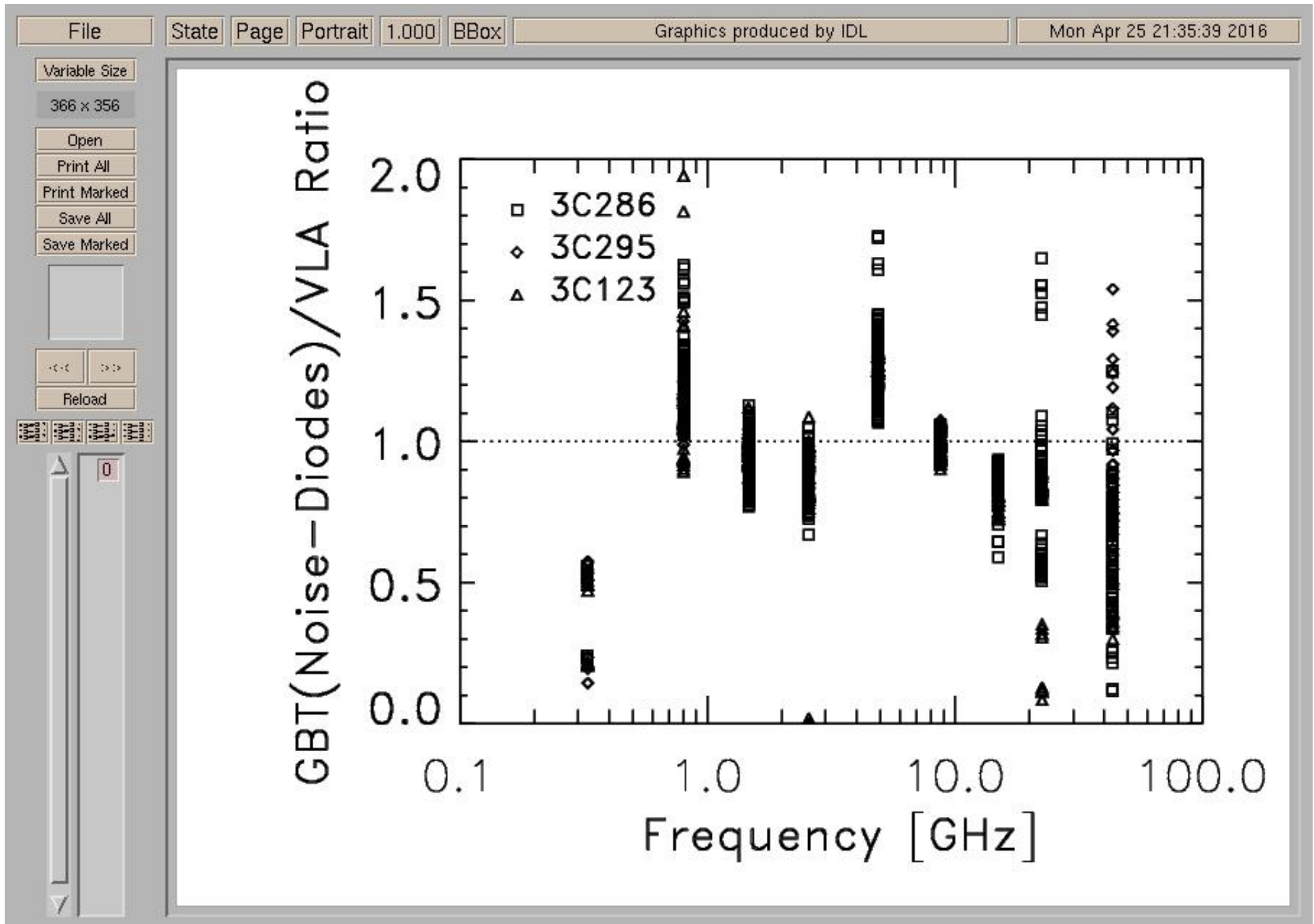
Eventually tie
GBT to VLA
calibration
scale for 1-50
GHz, and we
will use ALMA
for 3mm
absolute
calibration



Comparison of Calibration Scales (Ott 1994 vs VLA 2013)



GBT Calibration Measurements 2015-2016



Do not blindly accept the GBT Noise Diode Calibration

- Noise diodes are recommended to be sent back for re-calibration every 6 months to meet laboratory specs – we never do do this – we could expect drifts on time scale of 1-2 years.
- The KFPA has variable noise diodes.
- The noise diodes were last calibrated empirically for the GBT 10+ years ago.....
- There are significant variations in the noise diodes as a function of frequency.
- You should calibrate your data.

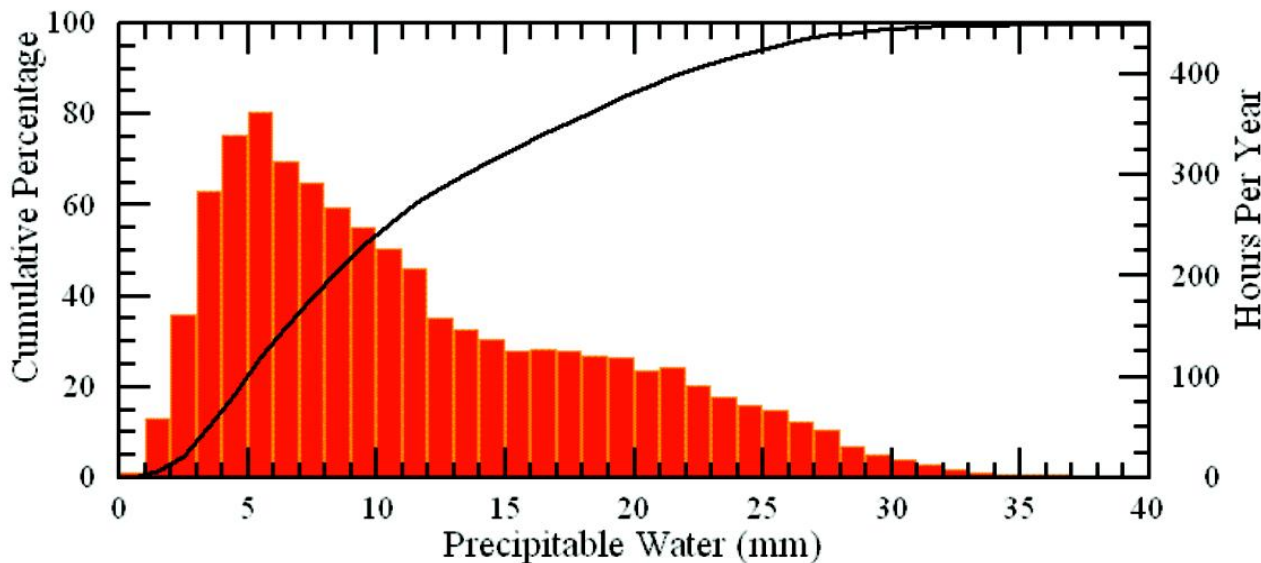
Estimate of Error in GBT Calibration

| Band | GBT/VLA Calibration |
|------|---------------------|
| 340 | 0.50 |
| 800 | 1.17 |
| L | 0.92 |
| S | 0.88 |
| C | 1.32 |
| X | 1.00 |
| Ku | 0.87 |
| KFPA | 0.90 |
| Ka | 1.01 |
| Q | 0.83 |

Based on 15A486 calibration program and ongoing observing programs over 2015-2016. Results based on averaging both polarizations.

The atmosphere is important at high frequency (>10 GHz)

- Opacity
 - $T_{\text{sys}} = T_{\text{rcvr}} + T_{\text{spill}} + T_{\text{bg}} * \exp(-\tau * A) + T_{\text{atm}} * [\exp(-\tau * A) - 1]$
 - Air Mass $A \sim 1/\sin(\text{Elev})$ (for Elev > 15°)
- Stability
 - T_{sys} can vary quickly with time
 - Worse when Tau is high



GBT site has many days with low water vapor per year (<10mm H₂O are ok for 3mm, 50% of time)

Background Information on Calibration

Temperature Scales

- $T_a = T_{\text{sys}} (\text{ON-OFF}) / \text{OFF}$ (uncorrected antenna temperature)
- $T_a' = T_a \exp(\tau_o A)$
- $T_{\text{mb}} = T_a' / \eta_{\text{mb}}$ ($\eta_{\text{mb}} \sim 1.3 \eta_a$)
- $T_a^* = T_a' / \eta_l$ (mm-telescopes typically return T_a^*)
- $T_r^* = T_a' / (\eta_l \eta_{\text{fss}})$
- $T_a' / S_v = 2.84 \eta_a$ (for the GBT)

Calibration with Two Loads

Two loads "Direct" calibration, e.g. 4m Rx

$$g = (T_{amb} - T_{cold}) / (V_{amb} - V_{cold})$$

$$T_A = T_{sys} \left(\frac{ON - OFF}{OFF} \right) = g (ON - OFF)$$

$$T_A' = T_A e^{\tau_0 A}$$

need τ

Calibration with One Load, T_A^*

One load chopper calibration:

With a chopper wheel/ vane and a simple temperature sensor, one can calibrate to the approximate T_A^* scale without any knowledge of the sky.

$$T_A^* = T_{cal} \left[\frac{V_{on} - V_{off}}{V_{amb} - V_{off}} \right]$$

need T_{ATM}

$$T_{cal} \equiv \left[\frac{T_{amb} - T_A^{sky}}{\eta_l} \right] e^{\tau_0 A}$$

is yuk, but:

Algebra \Rightarrow

$$T_{cal} = T_{ATM} + (T_{amb} - T_{ATM}) e^{\tau_0 A}$$

what Argus will use.

↑
model

eq. A9 of KU91
re-written

assumes $T_{spill} \approx T_{amb}$ and ignoring T_{bg}

Some have assumed $T_{cal} = T_{amb} = T_{ATM}$ with T_A^* calibration

Tsys for T_A^* scale different than Tsys for T_A

$$T_A^* = T_{\text{sys}}^* \left(\frac{\text{ON-OFF}}{\text{OFF}} \right)$$

where $T_{\text{sys}}^* = T_{\text{sys}} \cdot \frac{e^{z_0 A}}{\eta_l}$ includes ATM

ie

$$T_A^* = T_A \cdot \frac{e^{z_0 A}}{\eta_l}$$

Point-Source Calibration: Flux Density vs Antenna Temp

$$P_{\text{rec}} = \frac{1}{2} A_e S_\nu \Delta\nu = k T_a' \Delta\nu$$

$$A_e = \eta_a (\pi/4) D^2$$

$$\rightarrow S_\nu = 3520 T_a' / (\eta_a [D/m]^2)$$

i.e., $T_a' / S_\nu = 2.84 \eta_a$ for the GBT ($\eta_a = 0.71$ at low ν)

Used for point-source calibration:

- Measure T_a
- Correct for atmosphere $\rightarrow T_a'$
- Know S_ν
- Derive η_a

Extended Sources: T_{mb} vs T_{source}

$$T_A' = \frac{1}{\Omega_A} \iint P_n(\theta, \phi) T_s(\theta, \phi) d\Omega$$

↑
source

compute using T_{mb}

$$\frac{\Omega_{mb}}{\Omega_A} = \eta_{mb} \quad ; \quad T_A' = \eta_{mb} T_{mb}$$

$$T_{mb} = \frac{T_A'}{\eta_{mb}} = \frac{1}{\Omega_{mb}} \iint P_n(\theta, \phi) T_s(\theta, \phi) d\Omega$$

case 1. If T_s is uniform, $\theta_s < \theta_{mb} \Rightarrow \Omega_s \ll \Omega_{MB}$
 $\Rightarrow P_n \approx 1$ over source:

$$T_{mb} = \frac{1}{\Omega_{MB}} T_s \iint_{\text{source}} P_n d\Omega$$

$$= T_s \frac{\Omega_s}{\Omega_{MB}} = \left(\frac{\theta_s}{\theta_{mb}} \right)^2$$

$$T_{mb} = T_s \left(\frac{\theta_s}{\theta_{mb}} \right)^2$$

Small source $\theta_s < \theta_{mb}$



"Filling factor"
"Beam dilution"

Gaussian Source

More general, assume T_s Gaussian and beam Gaussian

$$\Omega_{\text{Gaussian}} = 1.133 \theta_{\text{FWHM}}^2$$

$$T_{\text{mb}} = T_s \left[\frac{\theta_s^2}{\theta_{\text{mb}}^2 + \theta_s^2} \right]$$

$$\theta_{\text{mb}} \gg \theta_s \quad T_{\text{mb}} = T_s \left(\theta_s / \theta_{\text{mb}} \right)^2 \quad \checkmark$$

$$\theta_s \gg \theta_{\text{mb}} \quad T_{\text{mb}} = T_s \quad \checkmark$$

Concluding Remarks

- To observe weak signals, one needs to measure ON-OFF
- Several different observing techniques can be used to give ON-OFF (freq-switched, position switched)
- At cm wavelengths, we use noise diodes to calibrate the data, while at mm wavelengths ambient/cold loads are used
- Users should correct for atmosphere at all frequencies, but it is crucial at high freq.
- Users should observe a known calibrator once per semester per target frequency to calibrate the noise diodes and instrumental effects empirically.
- Absolute calibration should be done in good weather.