Performance measurements and models of Tianma Radio telescope(TM65m)

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Efficiency/system noise temperature/SEFD

Surface measurement by holography and gravity model



Pointing VS efficiency



Pointing error/beam width	0.1	0.2	0.3	0.4	0.5	
Loss of gain	0.027	0.105	0.22	0.36	0.5	

Pointing error main comes from:

- 1) Mechanical error [model,titlemeter]
- 2) Encoder accuracy and stability
- 3) Servo system
- 4) Sub_reflector XY offsets [model,PSD]
- 5) Active surface[model]
- 6) Temperature [model,titlemeter,sensor,PSD]
- 7) Wind[PSD,half_power track]

Pointing Model measurement





Delt_AZ= C1+ tan(E0)*cos(A0)*C3 + tan(E0)*sin(A0)*C4 + tan(E0)*C5-1/cos(E0)*C6

Delt_EL= C2- sin(A0)*C3+ cos(A0)*C4+ cos(E0)*C7+ C8/tan(E0)

K band pointing model (sub_reflector enable)





Sub_reflector Model



Tested model VS FEM simulation



Efficiency & Tsys measurement



C band(4GHz-8GHz) system noise temperature



C band performance Sub_reflector fixed @4.8GHz 20MHz Bandwidth



C band performance Sub_reflector Enable @4.8GHz 20MHz Bandwidth



X band performance Sub_reflector fixed @8.75GHz 20MHz Bandwidth



Sub_reflector Enable @8.75GHz 20MHz Bandwidth



Ku band performance Sub_reflector Enable @15.6GHz 20MHz Bandwidth



Ka band performance Sub_reflector Enable @31.1GHz 20MHz Bandwidth



L/C/S/X/Ku/Ka bands performance

	Sub	-	T	DREU		归一化 Poly(aX³+bX²+cX+d)				
Band	_reflector	Frequency	Isys		Efficiency max	(X=Elevation/degree)				
			@Zenith	(K /JY)		а	b	c	d	
L(V)	fixed	1488	32	0.768	0.64@El=46.4	1.6E-6	-3.6247E-4	0.02326739	0.54048039	
L(H)	fixed	1488	30	0.796	0.66@El=43.4	2.05E-6	-3.565E-4	0.01929101	0.66628028	
S(LCP)	fixed	2265	50	0.680	0.57@E1=9.463	5.0E-8	-9.83E-6	-0.00143989	1.01446614	
S(RCP)	fixed	2265	52	0.709	0.59@ E1=9.463	7.0E-8	-1.197E-5	-0.00158865	1.01604279	
C(LCP)	move	4800	20	0.771	0.64 @El=48.7	6.4E-7	-1.1908E-4	0.00705175	0.86551495	
C(RCP)	move	4800	20	0.785	0.65 @El=47.1	6.8E-7	-1.2899E-4	0.00759555	0.85688260	
C(LCP)	move	6425	19	0.719	0.60 @El=54.7	3.0E-8	-3.028E-5	0.00303171	0.91954072	
C(RCP)	move	6425	19	0.708	0.59 @E1=54.7	1.5E-7	-4.839E-5	0.00395895	0.90378113	
C(LCP)	move	7500	17	0.764	0.64 @El=55.3	1.7E-7	-6.686E-5	0.00585544	0.85217763	
C(RCP)	move	7500	17	0.715	0.60 @E1=56.9	9.0E-8	-5.493E-5	0.00537263	0.85531771	
X(LCP)	move	8400	33	0.789	0.66 @El=60.1	-1.99E-6	2.4240E-4	-0.00757999	1.01166495	
X(RCP)	move	8400	31	0.782	0.65 @El=60.9	-1.99E-6	2.4415E-4	-0.00763073	1.00900602	
Ku(LCP)	move	15600	25	0.807	0.67@ E1=50.877	-5.13E-6	0.00039693	-0.00038984	0.66734680	
Ku(RCP)	move	15600	30	0.850	0.71@ El=51.738	-4.71E-6	0.00030573	0.00616772	0.51438883	
Ka(LCP)	move	31100	80	0.560	0.47@ E1=48.211	-6.14E-6	0.00022601	0.02134805	0.13347055	
Ka(RCP)	move	31100	70	0.563	0.47@ E1=48.937	-6.35E-6	0.00026943	0.01925549	0.15628293	

K band dual beam Tsys/Trec/Tsky



K band Beam1–RCP @19. 45GHz 16y8m25 cloudy







Q band Beam1 performance @43GH 2016y8m6 cloudy



Microwave Holography on TM65m for surface error measurement

Phase coherent satellite ____ high accuracy pannel setting radio source (VLBI)___ gravity deformation

Phase Retrieve

OOF _____ gravity deformation & real-time detection [See Dr. JianDong's poster]







Asia4 Ku beacon (12.25GHz)



Far Field Amplitude and Phase









D (m)	65	63	60	58	56	(UT)
RMS(mm)	0.274	0.267	0.257	0.251	0.243	16y1m19 09:16-11:40
	0.278	0.270	0.263	0.260	0.255	16y1m19 14:44-17:06
	0.288	0.281	0.273	0.263	0.256	16y1m27 11:24-13:54

Measurement Error



Repeated measurement error by 3 times independent tests



D (m)	65	63	60	58	56	53	50
RMS (mm)	0.132	0.121	0.113	0.109	0.106	0.099	0.093

Ka efficiency improvement @31.15GHz



Ka 31.15GHz efficiency improvement in theory: 36% (0.58mm) -> 54% (0.3mm)

Main Surface Gravity Model Measurment by Short Baseline(~6km) VLBI



Radial sweep scans and correlation



One pattern: ~ 20minutes Resolusion: ~ 3m Meaure error: ~ 0.17mm Radio source: 3C84 Integeration time: 1second Freq&Bandwidth: 8.4GHz&16MHz





Gravity model simulation and measurement

left: FEM simulation files

'E:\65	im\主动面\	促动器订	鄅整量	(原始)	\5°	仰角促动	器调整量	.txť	;
'E:\65	im\主动面\	促动器订	副整量	(原始)	\10°	仰角促动	り器调整量	1.txt	1
'E:\65	ím\主动面\	促动器订	那整量	(原始)	\15°	仰角促动	り器调整量	1.txt	1
'E:\65	im\主动面\	促动器订	副整量	(原始)	\20°	仰角促动	り器调整量	1.txt	1
'E:\65	im\主动面\	促动器订	副整量	(原始)	\25°	仰角促动	り器调整量	1.txt	1
'E:\65	im\主动面\	促动器订	那整量	(原始)	\30°	仰角促动	り器调整量	1.txt	1
'E:\65	ím\主动面\	促动器订	副整量	(原始)	\35°	仰角促动	り器调整量	1.txt	1
'E:\65	im\主动面\	促动器订	酮整量	(原始)	\40°	仰角促动	り器调整量	1.txt	` ;
'E:\65	im\主动面\	促动器订	副整量	(原始)	\45°	仰角促动	り器调整量	1.txt	1
'E:\65	im\主动面\	促动器订	副整量	(原始)	\55°	仰角促动	り器调整量	1.txt	1
'E:\65	ím\主动面\	促动器订	那整量	(原始)	\60°	仰角促动	り器调整量	1.txt	1
'E:\65	ím\主动面\	促动器订	副整量	(原始)	\65°	仰角促动	り器调整量	1.txt	1
'E:\65	im\主动面\	促动器订	副整量	(原始)	\70°	仰角促动	り器调整量	1.txt	1
'E:\65	im\主动面\	促动器订	副整量	(原始)	\75°	仰角促动	り器调整量	1.txt	1
'E:\65	im\主动面\	促动器订	郦整量	(原始)	\80°	仰角促动	り器调整量	1.txt	` ;
'E:\65	im\主动面\	促动器订	鄅整量	(原始)	\85°	仰角促动	り器调整量	1.txt	1
'E:\65	im\主动面\	促动器订	鄅整量	(原始)	\90°	仰角促动	り器调整量	1.txt	1

right: measurement file

'D:\share\2015y8m20\1453\Activesurface.txt';	17.6
'D:\share\2015y8m20\1524\Activesurface.txt';	22.9
'D:\share\2015y8m20\1555\Activesurface.txt';	28.1
'D:\share\2015y8m20\1626\Activesurface.txt';	33.9
'D:\share\2015y8m20\1657\Activesurface.txt';	39.4
'D:\share\2015y8m20\1728\Activesurface.txt';	45.4
'D:\share\2015y8m20\1759\Activesurface.txt';	51.4
'D:\share\2015y8m20\1830\Activesurface.txt';	57.1
'D:\share\2015y8m20\1901\Activesurface.txt';	62.4
'D:\share\2015y8m20\1932\Activesurface.txt';	68.3
'D:\share\2015y8m20\2003\Activesurface.txt';	73.3

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Sub-reflector XYZ position derived from holography aperture phase VS the sub-reflector model constructed from amplitude sweeps



conclusions

- All receivers have been installed. K and Q bands need more testing for the weather and pointing problems
- Introduced the performance of pointing, surface accuracy and models construction
- Elevation pointing error needs more improvement and verification in servo control, encoder setup and models
- Both phase coherent and phase retrieve holography are adoped for pannel setting and gravity deformation model construciton. The surface accuracy is better than 0.3mm(RMS) at elevations around 53°. For higher and lower elevations we need more testing and verification for the accuracy improvements

Questions...