Metrology at the Sardinia Radio Telescope

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Sardinia Radio Telescope



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Agenda

- SRT main characteristics description
- > SRT status at the end of the astronomical validation
- Work progress status of the first SRT metrology systems:
 - With-phase microwave holography
 - Inclinometers
 - Temperature probes
 - Optical laser and Position sensing devices (PSD)
- Conclusions



SRT Project



SRT technical specifications

Gregorian Configuration with shaped surfaces

Primary Mirror D=64 m – 1008 panels - 65 μm ; Secondary Mirror D=7.9 m – 49 panels - 50 μm

Active Surface: Primary mirror adjustable with 1116 actuators

12 motors (eight in azimuth and four in elevation)

29 bit absolute encoders (error 0,8 arcsec); Six focal positions Can host up to 20 dual polarization receivers; ACU based on a BECKHOFF hardware Primary surf. Accuracy goal: ≈ 150 µm RMS Pointing accuracy goal (RMS): $2 \div 5$ arcsec Max antenna efficiency goal: $\approx 60 \%$ Gain exp. 0.50 to 0.70 K/Jy @ 0.3–50GHz and 0.34 K/Jy @ (70–115GHz). **Frequency agility**



SRT status: installed receivers

F/D =2.35 7.5GHz < *f* < 115GHz

18-26,5 GHz

0.305-0.410 /1.3-1.8 GHz



Active surface: shape of primary mirror controlled with actuators

- Compensate deformations of the primary mirror
- Convert shaped profile to a true-parabola (for primary focus)



Actuators problem: Corrosion phenomena

The problem with the actuators was due to two concurring negative phenomena, like strain-induced-corrosion and galvanic currents. The coupling of two alloys, like steel and ERGAL contributed to increase those two phenomena, creating cracks in the ERGAL part and compromising the actuators integrity.





SRT status: surface accuracy

After the first panels alignment of the secondary and primary mirror with fotogrammetric measurement (by SIGMA 3D) AICON DPA mit Nikon D3X, 24.5 MPixel (6048 x 4032) 2 Scale bars, TrafoStar

Subreflector surface



Accuracy: ~ 60 µm RMS @ 45° elevation

Accuracy: ~ 290 µm RMS @ 45° elevation

Accuracy in the adjacent panels corner alignment better than 100 µm

Overall RMS accuracy of the reflecting surfaces $\epsilon \sim 310 \ \mu m$ (= $\lambda/20 \ @ \sim 48 \ GHz$)

Very good surface efficiency up to 48 GHz



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Primary reflector surface

Primary mirror Fotogrammetry results

Surface deflections in different elevation positions from 15 to 90 deg elevation, refered to 45 deg reference













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X+Elevator

-18

30

10.

SRT status: antenna performances

Top:

Elevation-averaged beam patterns (in Jy/beam) of 20 OTF scans

Bottom:

Beam cross-sections along the Azimuth and Elevation axes (in dB).

Calibrator 3C147 @ 7,24 GHz Calibrator 3C84 @ 25,54 GHz

Fitting a Gaussian we can find the secondary lobe intensity averaged over an annulus of 4.5' radius and 3' width is -24 dB and the third lobe is – 33 dB in which it is possible to see the effect of the trusses of the quadripod but for the K band the secondary lobe is -12 dB so not in specific



Courtesty of SRT Astronomical Validation (Prandoni et al. in preparation)

SRT status: antenna performances

Map dimension 6' x 6'

Maps of Contour levels start at -25 dB and increase by 1 dB.

HPBW 2.6 arcmin

The secondary lobe moves from the upper part to the lower moving from the 60° EL





Courtesty of SRT Astronomical Validation (Prandoni et al. in preparation)



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SRT status: antenna performances

After the fine tuning of the telescope with active surfaces working, the pointing model allows SRT to observe at 22 GHz with a:

- focusing accuracy < 1 mm</p>
- an azimuth and elevation pointing errors < 4 arc sec</p>



SRT metrology short-term goals

Waiting for the higher frequency receivers, the metrology team is working to further improve the current SRT efficiency

- Short-term goals:
 - To measure the primary surface accuracy better than 150 µm (i.e. an overall surface accuracy 190 µm, a very good efficiency up to ~80 GHz) with Microwave holography system to measure RT far-field pattern by pointing a Ku-band GEO satellite (elevation angle 44 deg);
 - To contribute to correct azimuth and elevation pointing errors < HPBW/10 (~1 arcsec with HPBW =12 arcsec @ 100 GHz) with two inclinometers on top of the alidade structure;
 - **Temperature sensors** for reducing detrimental thermal gradient effects on the pointing errors;
 - To correct pointing errors and focusing accuracy < $\lambda/10$ (~0.3 mm @ 100 GHz) with <code>optical laser-PSDs</code> behind the subreflector central panel;



Status of holography system



Status of Inclinometer

On the base of the recommendations coming from the SRT thermal design study



Inclinometer #1

Status of inclinometer

Tests to check the planarity of the azimuth rail



<u>Systematic errors</u> not far from the expected one (±3 arcsec) deriving from the rail planarity tolerance. However they can be included in the antenna pointing model



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Work progress status of inclinometer

Inclinometer measurement during astronomical observation on a circumpolar radio source at 23 GHz (K-band receiver) from sunrise to noon.



NOTE. With the antenna pointing model working, **residual offsets** take into account both alidade and quadripod temperature variation (not only alidade as in the inclinometer measurement)

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Status of temperature probes

The number and position of the temperature probes on SRT structure were inferred by FEM model:



- 16 probes on the alidade
- 8 probes on the quadrupod



Probes installation, cabling and interfacing with Beckhoff embeddes PC will be soon accomplished





Status of optical laser PSD

Two PSD for a real-time measurement of the secondary mirror misalignments, one is already installed behind the central panel of the sub-reflector and we are testing its performances



PSDs can measure X, Y, Z translation (derived by two X measur.) and X,Y axes rotation of the subreflector. Only one at the moment is installed.



SRT metrology future plans

- Include inclinometer, PSD and temperature probe data in the antenna pointing model in order to reduce the errors and to try to compensate for alidade and quadrupod thermal deformations
- Beside the traditional holography, we plan to use the Out-of-Focus method on SRT for a quasi-real time mapping of the primary surface deformations, due even to thermal gradients effects and the linear sensors
- New systems: Laser Tracker and Real Time photogrammetry



Conclusions

- Many thanks to Richard for his efforts in organizing this workshop;
- I think that if we could have this workshop few years ago we could be in a better condition in the development of an efficient and well organized Metrology plan for SRT.

